



H2 API PROGRAMMING GUIDE



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1. Version Information

Version Update Description Table

Version	Description	Date
V2.0.24	Added: device_gpio_setbits , device_gpio_resetbits .	07/16/2026
V2.0.18	Added: Modulation Configuration Functions section.	05/22/2026
V2.0.17	Add: device_query_state function.	04/30/2026
V2.0.12	Add: device_open_eth , device_config_fan , device_config_clock , device_query_clock , device_reset_clock_monitor , channel_config_trigger_out , channel_query_trigger_out , channel_config_lo_mode , channel_query_lo_mode , tx_config_lscan and tx_query_lscan function.	04/20/2026
V2.0.10	Add: device_list_usb , device_query_supply , device_config_gnss , device_query_gnss , device_query_gnss_info , device_epoch_to_utc , tx_config_fscan , tx_query_fscan and tx_config_stream function.	03/18/2026
V1.0	Initial version.	01/10/2026

2. Overview

This API system is a dynamic link library developed in C, used for programming and controlling the device. The signal generator mainly operates in the following three modes:

Continuous Wave Mode	In this mode, the device transmits a continuous wave, and no data needs to be sent from the user to the device.
Real-Time Streaming Mode	In this mode, the user can send IQ waveform data to the device via the USB interface. The device receives and plays the data in real time. When the user stops sending data, the device will finish playing all received data before stopping. The real-time sampling rate (up to 62.5 MHz) and data throughput are limited by the physical bandwidth of the data interface, while the total data size is not limited.
Playback Mode	This mode uses a pre-stored waveform playback mechanism. The user can first download IQ waveform data into the device memory, and then achieve multi-waveform playback by specifying the waveform index, number of playback loops, sampling rate, and the number of waveforms to be played. Since all waveform data is pre-stored, maximum analog bandwidth output can be achieved without relying on high-speed real-time data transmission. Note that the total amount of storable waveform data is limited by the device memory capacity (up to 128 MB).

3. Device and API version

The system operates through the coordinated execution of multiple software and firmware components. In this system, the involved components include: the main control firmware (MFW/MCU), FPGA firmware (FFW), bus firmware (Bus), and the application programming interface (API).

Version Matching Principle

To ensure stable system operation, the versions of the above components must strictly follow the baseline version alignment principle. Please refer to the table below for version verification and deployment.

Table 1 Software and Firmware Baseline Version Mapping Table

API	FPGA	MCU	Bus
2.0.24	2.0.14	2.0.29	2.0.1
2.0.21	2.0.13	2.0.22	2.0.1
2.0.18	2.0.12	2.0.19	2.0.1
2.0.17	2.0.11	2.0.13	2.0.1

Note:

1. To avoid system abnormalities, do not mix software and firmware from different baseline versions. Ensure that all components are deployed or upgraded strictly according to the versions listed in the table above.
2. Make sure that the API version in use matches the version indicated on the cover of the manual, to prevent inconsistencies between the documented interface descriptions and the actual functionality.

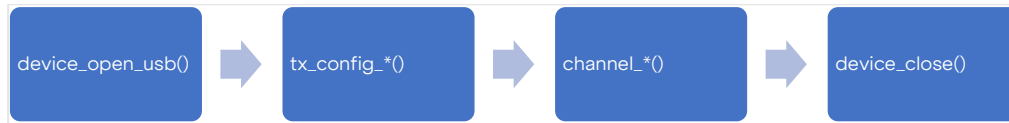
4. Overview of Function Categories

Table 2 API Function Categories

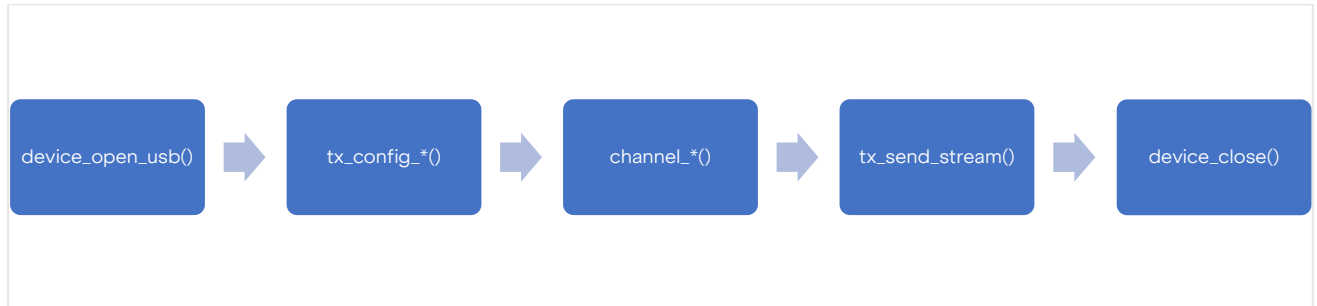
Function Category	Description
Device and System	Global functions that can be called in any operating mode. This category includes device open/close, global settings, retrieving device information, and obtaining device status.
Channel Settings	Channel-level control for managing the device's independent signal paths. Functions allow configuration, enabling, parameter setting, and status querying for specified channels, forming the basis for multi-channel synchronous or independent control.
Transmission Settings	Controls the transmission chain. Functions in this category configure transmission parameters, manage signal transmission processes, handle transmission data, and query transmission status. This is the core of the signal generator functionality.

5. API Calling Flow

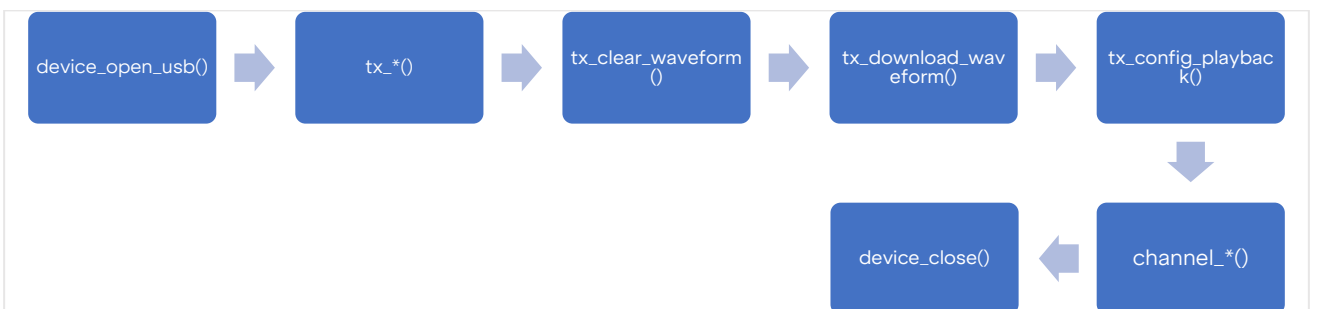
5.1 CW Mode



5.2 Real-Time Streaming Mode



5.3 Playback Mode



6. Device and System Function

`device_open_usb` must be called to initialize the device before accessing any hardware-related API functions. Upon completion of the application logic, call `device_close` to terminate the session and release allocated memory resources.

6.1 `device_list_usb`

```
int device_list_usb(  
    device\_info* devInfo,  
    uint32\_t* count  
)
```

Description

Enumerates the list of USB devices currently connected to the host.

Compatibility	2.0.2 and later.
---------------	------------------

Parameter description

[out] devInfo	Returns basic information for all currently connected devices. Valid data includes model and uid; refer to the device_info structure definition for details.
--------------------------------------	--

[out] count	Total number of USB devices currently connected to the host.
------------------------------------	--

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	None.
---------------------	-------

Example

```
device_info devInfo;  
uint32\_t count = 0;  
int status = device_list_usb(&devInfo, &count);
```

6.2 device_open_usb

```
int device_open_usb(  
    void** device,  
    uint8_t dnum,  
    channel ch_o[],  
    uint16_t* chn,  
    device_info* dinfo  
)
```

Description

Initializes the device connection. This function establishes low-level communication and enumerates available channels based on the startup configuration. It must be called before any subsequent API operations. Upon success, it returns the device handle, channel list, channel count, and basic device information.

Compatibility	2.0.1 and later.
---------------	------------------

Parameter description

[out] device	Returns the device handle. This handle is used to reference the target device in subsequent API calls.
---------------------	--

[in] dnum	Specifies the zero-based index of the device to be opened. Used to select the target unit when multiple devices are connected.
------------------	--

[out] ch_o	Returns an array of channels supported by the device. Refer to the channel structure definition for details.
-------------------	--

[out] chn	Returns the total number of channels.
------------------	---------------------------------------

[out] dinfo	Returns basic device information. Refer to the device_info structure definition for details.
--------------------	--

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	This function must be invoked before any other API calls and should only be executed once during the initialization phase. Subsequent operations rely on the device handle returned by this function. For every successful device_open_usb call, device_close must be invoked upon completion to release allocated resources.
---------------------	---

Example	Refer to the relevant example of the tx_config_cw() function.
---------	---

6.3 device_open_eth

```
int device_open_eth(  
    void** device,  
    eth_setting settings,  
    channel ch_o[],  
    uint16_t* chn,  
    device_info* dinfo  
)
```

Description

Initializes the ETH device connection. This function establishes low-level communication and enumerates available channels based on the startup configuration. It must be called before any subsequent API operations. Upon success, it returns the device handle, channel list, channel count, and basic device information.

Compatibility

2.0.11 and later.

Parameter description

[in] device

Returns the device handle. This handle is used to reference the target device in subsequent API calls.

[in] settings

Specifies the ETH device startup configuration. Refer to the [eth_setting](#) structure definition for details.

[out] ch_o

Returns an array of channels supported by the device. Refer to the [channel](#) structure definition for details.

[out] chn

Returns the total number of channels.

[out] dinfo

Returns basic device information. Refer to the [device_info](#) structure definition for details.

Return Value

0: Success; Non-zero: Error code. Refer to the [Appendix 1](#) for details.

Calling constraints

This function must be invoked before any other API calls and should only be executed once during the initialization phase. Subsequent operations rely on the device handle returned by this function. For every successful device_open_eth call, device_close must be invoked upon completion to release allocated resources.

Example

```
int status = 0;  
void* device = nullptr;  
device_info dinfo;
```

```

channel ch[8]; uint16_t chn = 0;
eth_setting settings;
settings.eth_interface = ETH_STANDARD;
settings.eth_is_ipv6 = 0;
settings.eth_ip_address[0] = 192;
settings.eth_ip_address[1] = 168;
settings.eth_ip_address[2] = 1;
settings.eth_ip_address[3] = 100;
settings.eth_remote_port = 5000;
settings.eth_read_timeout = 5000;
status = device_open_eth(&device, settings, ch, &chn, &dinfo);
status = device_close(&device);

```

6.4 device_close

int device_close(void device)**

Description

Closes the device connection and releases associated resources.

Compatibility 1.0.1 and later.

Parameter description

[in] device Device handle. This handle becomes invalid once the connection is closed.

Return value 0: Success; Non-zero: Error code. Refer to the [Appendix 1](#) for details.

Calling constraints This function should only be invoked at the end of program execution. Upon invocation, the device connection is closed and allocated resources are released. To reuse the device, device_open_* must be called again to re-establish the connection and initialize the hardware.

Example Refer to the relevant example of [tx_config_cw\(\)](#) function.

6.5 device_preset

int device_preset(void** device)	
Description	
Performs a device reset, including a global reset of all available channels.	
Compatibility	1.0.1 and later.
Parameter description	
[in] device	Device handle.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	
<pre>int status = -1; void* device = nullptr; device_info dinfo; channel ch[8]; uint16_t chn = 0; uint8_t dnum = 0; status = device_open_usb(&device, dnum, ch, &chn, &dinfo); status = device_preset(&device); status = device_close(&device);</pre>	

6.6 device_query_temperature

int device_query_temperature(void** device, float* temp_o)	
Description	
Queries the current temperature of the device.	
Compatibility	2.0.1 and later.
Parameter description	
[in] device	Device handle.
[out] temp_o	Returns the device temperature in degrees Celsius.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.

Example

```
int status = -1;
void* device = nullptr;
device_info dinfo;
channel ch[8];
uint16_t chn = 0;
uint8_t dnum = 0;
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);
float temp_o = 0;
status = device_query_temperature(&device, &temp_o);
status = device_close(&device);
```

6.7 device_query_state

int device_query_state(void device)**

Description

Query the current state of the device.

Compatibility	1.0.1 and later.
---------------	------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
--------------------	----------------

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	Must be called after device_open_* initialization.
---------------------	--

6.8 device_config_fan

```
int device_config_fan(
    void** device,
    fan_mode mode,
    float auto_threshold
)
```

Description

Configures the fan operation settings.

Compatibility	2.0.12 and later.
---------------	-------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
--------------------	----------------

[in] mod	Sets the fan operating mode. Refer to the fan_mode enumeration definition for details.
-----------------	--

[in] auto_threshold	Sets the temperature thresholds for automatic mode.
----------------------------	---

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.

6.9 device_gpio_setbits

<pre>int device_gpio_setbits (void** device, uint16_t bits)</pre>	
Description	
Set GPIO.	
Compatibility	2.0.24 and later.
Parameter description	
[in] device	Device handle.
[in] bits	Controls the 16 GPIO I/O pins. A value of 1 drives the corresponding GPIO pin to a high level, while a value of 0 drives it to a low level.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	
<pre>int status = -1; void* device = nullptr; device_info dinfo; channel ch[8]; uint16_t chn = 0; uint8_t dnum = 0; status = device_open_usb(&device, dnum, ch, &chn, &dinfo); uint16_t bits = 0b00000000000001001; status = device_gpio_setbits(&device, bits); status = device_close(&device);</pre>	

6.10 device_gpio_resetbits

```
int device_gpio_resetbits (  
    void** device,  
    uint16_t bits  
)
```

Description

Reset GPIO.

Compatibility	2.0.24 and later.
---------------	-------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
-------------	----------------

[in] bits	Controls the 16 GPIO I/O pins. A value of 1 drives the corresponding GPIO pin to a high level, while a value of 0 drives it to a low level.
-----------	---

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	Must be called after device_open_* initialization.
---------------------	--

Example

```
int status = -1;  
void* device = nullptr;  
device_info dinfo;  
channel ch[8];  
uint16_t chn = 0;  
uint8_t dnum = 0;  
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);  
uint16_t bits = 0b00000000000001001;  
status = device_gpio_resetbits(&device, bits);  
status = device_close(&device);
```

6.11 device_query_supply

```
int device_query_supply(  
    void** device,  
    supply_info* supplyInfo_o  
)
```

Description

Queries the current power supply status and electrical parameters of the device.

Compatibility	2.0.10 and later.
---------------	-------------------

Parameter description

[in] device	Device handle.
-------------	----------------

[out] supplyInfo_o	Returns the device voltage and current parameters. Refer to the supply_info structure definition for details.
--------------------	---

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	Must be called after device_open_* initialization.
---------------------	--

Example

```
int status = -1; void* device = nullptr;  
device_info dinfo;  
channel ch[8];  
uint16_t chn = 0; uint8_t dnum = 0;  
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);  
supply_info supplyInfo_o;  
status = device_query_supply(&device, &supplyInfo_o);  
status = device_close(&device);
```

6.12 device_config_gnss

<pre>int device_config_gnss(void** device, gnss_setting gnss)</pre>	
Description	
Configures the GNSS operating parameters for the device.	
Compatibility	2.0.7 and later.
Parameter description	
[in] device	Device handle.
[in] gnss	GNSS configuration parameters. Refer to the gnss_setting structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of device_epoch_to_utc() function.

6.13 device_query_gnss

<pre>int device_query_gnss(void** device, gnss_setting* gnss_o)</pre>	
Description	
Queries the current GNSS configuration of the device.	
Compatibility	2.0.7 and later.
Parameter description	
[in] device	Device handle.
[in] gnss	Returns the current GNSS configuration parameters. Refer to the gnss_setting structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of device_epoch_to_utc() function.

6.14 device_query_gnss_info

```
int device_query_gnss_info(  
    void** device,  
    gnss_info* gnss_o  
)
```

Description

Queries the current GNSS information of the device.

Compatibility	2.0.1 and later.
---------------	------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
-------------	----------------

[out] gnss_o	Returns the GNSS information of the device. Refer to the gnss_info structure definition for details.
--------------	--

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	Must be called after device_open_* initialization.
---------------------	--

Example	Refer to the relevant example of device_epoch_to_utc() function.
---------	--

6.15 device_query_apiverion

```
uint32_t device_query_apiverion()
```

Description

Returns the API version information associated with the current library.

Compatibility	1.0.1 and later.
---------------	------------------

Return value	API version number. Represented using major, minor, and revision versions. bit[31..16]: major version; bit[15..8]: minor version; bit[7..0]: revision version.
--------------	---

Calling constraints	None.
---------------------	-------

Example

```
uint32_t verion = device_query_apiverion();  
int major = 0, minor = 0, rev = 0;  
major = (verion >> 16) & 0xffff;  
minor = (verion >> 8) & 0xff;  
rev = verion & 0xff;
```

6.16 device_config_clock

```
int device_query_gnss_info(  
    void** device,  
    referenceclock_source source,  
    double fref,  
    state out  
)
```

Description

Configures the reference clock source for the device.

Compatibility	2.0.11 and later.
---------------	-------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
-------------	----------------

[in] source	Set the reference clock source. Refer to the referenceclock_source structure definition for details.
-------------	---

[in] fref	Set the reference clock frequency in Hz.
-----------	--

[in] out	Returns the enablement state of the reference clock output.
----------	---

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	Must be called after device_open_* initialization.
---------------------	--

Example

```
int status = -1;  
void* device = nullptr;  
device_info dinfo;  
channel ch[8];  
uint16_t chn = 0;  
uint8_t dnum = 0;  
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);  
referenceclock_source source = REFCLKSOURCE_EXTERNAL;  
double fref = 10e6;  
state out = STATE_OFF;  
status = device_config_clock(&device, source, fref, out);  
state locked_o;  
status = device_query_clock(&device, &source, &fref, &out, &locked_o);  
status = device_close(&device);
```

6.17 device_query_clock

```
int device_query_clock(  
    void** device,  
    referenceclock_source* source_o,  
    double* freq_o,  
    state* out_o,  
    state* locked_o  
)
```

Description

Queries the current reference clock configuration status of the device.

Compatibility	2.0.11 and later.
---------------	-------------------

Parameter description

[in] device	Device handle.
-------------	----------------

[out] source_o	Returns the reference clock source. Refer to the referenceclock_source structure definition for details.
----------------	---

[out] freq_o	Returns the reference clock frequency in Hz.
--------------	--

[out] out_o	Returns the enablement state of the reference clock output.
-------------	---

[out] locked_o	Returns the lock status of the reference clock monitoring. (The actual reference clock frequency can only be accurately retrieved when the status is Locked).
----------------	--

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	Must be called after device_open_* initialization.
---------------------	--

Example	Refer to the relevant example of device_config_clock() function.
---------	--

6.18 device_reset_clock_monitor

```
int device_reset_clock_monitor(void** device)
```

Description

Resets the reference clock monitoring.

Compatibility	2.0.11 and later.
---------------	-------------------

Parameter description

[in] device	Device handle. This handle becomes invalid once the connection is closed.
-------------	---

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	
<pre>int status = -1; void* device = nullptr; device_info dinfo; channel ch[8]; uint16_t chn = 0; uint8_t dnum = 0; status = device_open_usb(&device, dnum, ch, &chn, &dinfo); status = device_reset_clock_monitor(&device); status = device_close(&device);</pre>	

6.19 device_epoch_to_utc

<pre>void device_epoch_to_utc(uint64_t ns_sinceepoch, int16_t* year, int16_t* mon, int16_t* day, int16_t* hour, int16_t* min, int16_t* sec, int16_t* ms, int16_t* us, int16_t* ns)</pre>	
Description	
Converts a Unix Epoch timestamp (in nanoseconds) into a readable UTC time format.	
Compatibility	2.0.7 and later.
Parameter description	
[in] ns_sinceepoch	Elapsed time since Unix Epoch in nanoseconds.
[out] year	Returns the year (e.g., 2026).
[out] mon	Returns the month (1 to 12).
[out] day	Returns the day (1 to 31).
[out] hour	Returns the hour (0 to 23).
[out] min	Returns the minute (0 to 59).

[out] sec	Returns the second (0 to 59).
[out] ms	Returns the millisecond (0 to 999).
[out] us	Returns the microsecond (0 to 999).
[out] ns	Returns the nanosecond (0 to 999).
Return value	None.
Calling constraints	Must be called after the GNSS is Locked and the device_query_gnss_info function has been executed.

Example

```
int status = -1; void* device = nullptr; device_info dinfo;
channel ch[8];
uint16_t chn = 0; uint8_t dnum = 0;
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);
gnss_setting gnss;
gnss.antenna = 1;
status = device_config_gnss(&device, gnss);
status = device_query_gnss(&device, &gnss);
gnss_info gnss_info_o;
status = device_query_gnss_info(&device, &gnss_info_o);
int16_t year = 0, mon = 0, day = 0, hour = 0, min = 0, sec = 0, ms = 0, us = 0, ns = 0;
device_epoch_to_utc(gnss_info_o.ns_sinceepoch, &year, &mon, &day, &hour, &min, &sec,
&ms, &us, &ns);
status = device_close(&device);
```

7. Channel Setting Function

7.1 channel_preset

int channel_preset(channel* ch)	
Description	
Performs a reset operation on multiple channels without initiating output.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Channel array. Refer to the channel structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	
<pre>int status = -1; void* device = nullptr; device_info dinfo; channel ch[8]; uint16_t chn = 0; uint8_t dnum = 0; status = device_open_usb(&device, dnum, ch, &chn, &dinfo); status = channel_preset(ch); status = device_close(&device);</pre>	

7.2 channel_start

int channel_start(channel* ch)	
Description	
Initiates multi-channel operation. This function must be invoked to apply changes and start the channels after modifying RF or baseband parameters	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Channel array. Refer to the channel structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_cw() function.

7.3 channel_stop

int channel_stop(channel* ch)	
Description	
Terminates multi-channel operation.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Channel array. Refer to the channel structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_cw() function.

7.4 channel_trigger_bus

int channel_trigger_bus(channel* ch)	
Description	
Executes a single bus trigger across multiple channels.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Channel array. Refer to the definition of the channel structure for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Please refer to the relevant example of the tx_config_cw() function.

7.5 channel_config_trigger

<pre>int channel_config_trigger(channel* ch, const tx_trigger* trg)</pre>	
Description	
Configures the trigger parameters for the specified channels.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Target channels. Refer to the channel structure definition for details.
[in] trg	Trigger configuration parameters. Refer to the tx_trigger structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_cw() function.

7.6 channel_query_trigger

<pre>int channel_query_trigger(channel* ch, tx_trigger* trg_o)</pre>	
Description	
Queries the current trigger configuration for the specified channels.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Target channels. Refer to the channel structure definition for details.
[out] trg_o	Returns the trigger configuration. Refer to the tx_trigger structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_cw() function.

7.7 channel_config_trigger_out

```
int channel_config_trigger_out(  
    channel* ch,  
    const trigger_out* trg  
)
```

Description

Configures the trigger output parameters for the specified channels.

Compatibility

2.0.11 and later.

Parameter description

[in] **ch**

Target channels. Refer to the [channel](#) structure definition for details.

[in] **trg**

Trigger output configuration parameters. Refer to the [trigger_out](#) structure definition for details.

Return value

0: Success; Non-zero: Error code. Refer to the [Appendix 1](#) for details.

Calling constraints

Must be called after device_open_* initialization.

Example

```
int status = -1;  
void* device = nullptr;  
device_info dinfo;  
channel ch[8];  
uint16_t chn = 0;  
uint8_t dnum = 0;  
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);  
double start = 1.0e9;  
double stop = 2.0e9;  
double step = 100e6;  
float level = 0.0f;  
float dwell = 1e-4;  
status = tx_config_fscan(ch, start, stop, step, level, dwell);  
tx_trigger trg;  
trg.source = TRIGGER_SOURCE_BUS;  
trg.action = TRIGGER_ACTION_SWEEP;  
trg.count = -1;  
status = channel_config_trigger(ch, &trg);
```

```

trigger_out trgout;
trgout.enable = STATE_ON;
trgout.action = TRIGGER_ACTION_HOP;
trgout.edge = TRIGGER_EDGE_RISING;
status = channel_config_trigger_out(ch, &trgout);
status = channel_query_trigger_out(ch, &trgout);
status = tx_config_cw(ch);
status = tx_config_output(ch, STATE_ON, STATE_OFF);
status = channel_start(ch);
status = channel_trigger_bus(ch);
status = device_close(&device);

```

7.8 channel_query_trigger_out

```

int channel_query_trigger_out(
    channel* ch,
    trigger_out* trg_o
)

```

Description

Queries the current trigger output configuration for the specified channels.

Compatibility	2.0.11 and later.
Parameter description	
[in] ch	Target channels. Refer to the channel structure definition for details.
[out] trg_o	Returns the trigger output configuration parameters. See the definition of the trigger_out structure for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of channel_config_trigger_out() function.

7.9 channel_config_lo_mode

```
int channel_config_lo_mode(  
    channel* ch,  
    lomode mode  
)
```

Description

Configures the LO mode for the specified channels.

Compatibility

2.0.11 and later.

Parameter description

[in] ch

Target channels. Refer to the [channel](#) structure definition for details.

[in] mode

LO mode configuration. Refer to the [lomode](#) structure definition for details.

Return value

0: Success; Non-zero: Error code. Refer to the [Appendix 1](#) for details.

Calling constraints

Must be called after device_open_* initialization.

Example

```
int status = -1;  
void* device = nullptr;  
device_info dinfo;  
channel ch[8];  
uint16_t chn = 0;  
uint8_t dnum = 0;  
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);  
lomode mode = LOMODE_LOWPHASENOISE;  
status = channel_config_lo_mode(ch, mode);  
status = channel_query_lo_mode(ch, &mode);  
status = device_close(&device);
```

7.10 channel_query_lo_mode

<pre>int channel_query_lo_mode(channel* ch, lomode* mode_o)</pre>	
Description	
Queries the current LO mode configuration for the specified channels.	
Compatibility	2.0.11 and later.
Parameter description	
[in] ch	Target channels. Refer to the channel structure definition for details.
[out] mode_o	Returns the LO mode configuration. Refer to the lomode structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of channel_config_lo_mode() function.

8. Transmission Setting Functions

8.1 tx_clear_waveform

int tx_clear_waveform(void** device)	
Description	
Clears all waveform data from the device memory.	
Compatibility	2.0.1 and later.
Parameter description	
[in] device	Device handle.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_playback() function.

8.2 tx_download_waveform

int tx_download_waveform(void** device, int16_t iq[], uint32_t points, uint16_t* waveform_o)	
Description	
Downloads waveform data to the device memory.	
Compatibility	2.0.1 and later.
Parameter description	
[in] device	Device handle.
[in] iq	IQ data array.
[in] points	Number of IQ point pairs.
[out] waveform_o	Waveform index.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_playback() function.

8.3 tx_config_ffm

```
int tx_config_ffm(  
    channel* ch,  
    double fc,  
    float level  
)
```

Description

Configures the frequency and amplitude parameters for the specified channels in FFM mode.

Compatibility	1.0.1 and later.
---------------	------------------

Parameter description

[in] ch	Target channels. Refer to the channel structure definition for details.
----------------	---

[in] fc	Center frequency.
----------------	-------------------

[in] level	Output amplitude.
-------------------	-------------------

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	Must be called after device_open_* initialization.
---------------------	--

Example	Refer to the relevant example of tx_config_cw() function.
---------	---

8.4 tx_query_ffm

```
int tx_query_ffm(  
    channel* ch,  
    double* fc_o,  
    float* level_o  
)
```

Description

Queries the current frequency and amplitude parameters for the specified channels in FFM mode.

Compatibility	1.0.1 and later.
---------------	------------------

Parameter description

[in] ch	Target channels. Refer to the channel structure definition for details.
----------------	---

[out] fc_o	Returns the center frequency.
-------------------	-------------------------------

[out] level_o	Returns the output amplitude.
----------------------	-------------------------------

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of the tx_config_cw() function.

8.5 tx_config_fscan

<pre>int tx_config_fscan(channel* ch, double start, double stop, double step, float level, float dwell)</pre>	
Description Configures the frequency sweep parameters for the specified channels. Performs an incremental sweep from the Start frequency to the Stop frequency using a defined Step size at a constant power level.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Target channels. Refer to the channel structure definition for details.
[in] start	Start frequency of the sweep.
[in] stop	Stop frequency of the sweep.
[in] step	Frequency step of the sweep.
[in] level	Output amplitude.
[in] dwell	Dwell time per frequency point (seconds). In TRIGGER_ACTION_HOP mode, the dwell time parameter is ignored, and frequency switching is governed exclusively by the arrival of a trigger event.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	

```

int status = -1;
void* device = nullptr;
device_info dinfo;
channel ch[8];
uint16_t chn = 0;
uint8_t dnum = 0;
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);
double start = 1.0e9;
double stop = 2.0e9;
double step = 100e6;
float level = 0.0f;
float dwell = 1e-4;
status = tx_config_fscan(ch, start, stop, step, level, dwell);
status = tx_query_fscan(ch, &start, &stop, &step, &level, &dwell);
tx_trigger trg;
trg.source = TRIGGER_SOURCE_BUS;
trg.action = TRIGGER_ACTION_SWEEP;
trg.count = -1;
status = channel_config_trigger(ch, &trg);
status = tx_config_cw(ch);
status = tx_config_output(ch, STATE_ON, STATE_OFF);
status = channel_start(ch);
status = channel_trigger_bus(ch);
status = device_close(&device);

```

8.6 tx_query_fscan

```

int tx_query_fscan(
    channel* ch,
    double* start_o,
    double* stop_o,
    double* step_o,
    float* level_o,
    float* dwell_o
)

```

Description

Queries the current frequency sweep configuration for the specified channels.

Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Target channels. Refer to the channel structure definition for details.
[out] start_o	Returns the start frequency of the sweep.
[out] stop_o	Returns the stop frequency of the sweep.
[out] step_o	Returns the frequency step of the sweep.
[out] level_o	Returns the output amplitude.
[out] dwel_o	Returns the dwell time per frequency point (in seconds).
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_fscan() function.

8.7 tx_config_lscan

<pre> int tx_config_lscan(channel* ch, double fc, float level_start, float level_stop, float level_step, float dwell) </pre>	
Description Configures the amplitude sweep parameters for the specified channels. Performs an incremental sweep from Level Start to Level Stop using a defined Level Step size at a constant center frequency fc.	
Compatibility	2.0.11 and later.
Parameter description	
[in] ch	Target channels. Refer to the channel definition structure.
[in] fc	Center frequency.
[in] level_start	Sweep start amplitude.
[in] level_stop	Sweep stop amplitude.
[in] level_step	Sweep step amplitude.
[in] dwell	Dwell time per amplitude point (seconds).

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	
<pre> int status = -1; void *device = nullptr; device_info dinfo; channel ch[8]; uint16_t chn = 0; uint8_t dnum = 0; status = device_open_usb(&device, dnum, ch, &chn, &dinfo); double fc = 1.0e9; float level_start = -20; float level_stop = -10; float level_step = 1; float dwell = 1e-4; status = tx_config_lscan(ch, fc, level_start, level_stop, level_step, dwell); status = tx_query_lscan(ch, &fc, &level_start, &level_stop, &level_step, &dwell); tx_trigger trg; trg.source = TRIGGER_SOURCE_BUS; trg.action = TRIGGER_ACTION_SWEEP; trg.count = -1; status = channel_config_trigger(ch, &trg); status = tx_config_cw(ch); status = tx_config_output(ch, STATE_ON, STATE_OFF); status = channel_start(ch); status = channel_trigger_bus(ch); status = device_close(&device); </pre>	

8.8 tx_query_lscan

```
int tx_query_lscan(
```

```
    channel* ch,  
    double* fc_o,  
    float* level_start_o,  
    float* level_stop_o,  
    float* level_step_o,  
    float* dwell_o  
)
```

Description

Queries the current amplitude sweep configuration for the specified channels.

Compatibility	2.0.11 and later.
Parameter description	
[in] ch	Target channels. Refer to the channel structure definition for details.
[out] fc_o	Returns the center frequency.
[out] level_start_o	Returns the sweep start amplitude.
[out] level_stop_o	Returns the sweep stop amplitude.
[out] level_step_o	Returns the sweep step amplitude.
[out] dwell_o	Returns the dwell time per amplitude point (seconds).
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_lscan() function.

8.9 tx_config_output

```
int tx_config_output(
```

```
    channel* ch,  
    state rfout,  
    state mod  
)
```

Description

Configures the RF and modulation output states for multiple channels.

Compatibility	2.0.1 and later.
---------------	------------------

Parameter description

[in] ch	Channel configuration array. Refer to the channel structure definition for details.
[in] rfout	RF output state configuration. Refer to the state enumeration structure definition for details.
[in] mod	Modulation output state configuration, refer to the state enumeration structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_cw() function.

8.10 tx_query_output

<pre>int tx_query_output(channel* ch, state* rfout_o, state* mod_o)</pre>	
Description	
Queries the current RF and modulation output states for multiple channels.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Channel configuration array. Refer to the channel structure definition for details.
[out] rfout_o	Returns the RF output state. Refer to the state enumeration structure definition for details.
[out] mod_o	Returns the modulation output state. Refer to the state enumeration structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_config_cw() function.

8.11 tx_config_cw

int tx_config_cw(channel* ch)	
Description	
Enables multi-channel Continuous Wave (CW) transmission.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Channel configuration array. Refer to the channel structure definition for details.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	
<pre>int status = -1; void* device = nullptr; device_info dinfo; channel ch[8]; uint16_t chn = 0; uint8_t dnum = 0; status = device_open_usb(&device, dnum, ch, &chn, &dinfo); double fc = 1.0e9; float level = 0.0f; status = tx_config_ffm(ch, fc, level); status = tx_query_ffm(ch, &fc, &level); tx_trigger trg; trg.source = TRIGGER_SOURCE_BUS; status = channel_config_trigger(ch, &trg); status = channel_query_trigger(ch, &trg); status = tx_config_cw(ch); status = tx_config_output(ch, STATE_ON, STATE_OFF); state rfout_o, mod_o; status = tx_query_output(ch, &rfout_o, &mod_o); status = channel_start(ch); status = channel_trigger_bus(ch); std::this_thread::sleep_for(std::chrono::seconds(10)); status = channel_stop(ch); status = device_close(&device);</pre>	

8.12 tx_config_stream

<pre>int tx_config_stream(channel* ch, double sample_rate)</pre>	
Description	
Configures the streaming playback parameters for the specified channel.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Channel configuration array. Refer to the channel structure definition for details.
[in] sample_rate	Channel sampling rate.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the relevant example of tx_send_stream() function.

8.13 tx_send_stream

<pre>int tx_send_stream(channel* ch, int16_t iq[], uint32_t points)</pre>	
Description	
Performs real-time IQ streaming playback on the specified channel.	
Compatibility	2.0.1 and later.
Parameter description	
[in] ch	Channel configuration array. Refer to the channel structure definition for details.
[in] iq	IQ data array.
[in] points	Number of IQ point pairs.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.

Example

```
// Simulated waveform: generates a sine wave
std::vector<int16_t> sim_generatewaveform_sine()
{
    constexpr uint32_t TOTAL_INT16_POINTS = 500000;
    constexpr uint32_t IQ_POINTS = TOTAL_INT16_POINTS / 2;
    constexpr int16_t AMP = 30000;
    constexpr uint32_t CYCLES = 100;
    const double twoPi = 2.0 * 3.141592654;
    std::vector<int16_t> iq;
    iq.reserve(TOTAL_INT16_POINTS);
    for (uint32_t n = 0; n < IQ_POINTS; ++n) {
        double phase = twoPi * CYCLES * n / IQ_POINTS;
        iq.push_back(static_cast<int16_t>(AMP * std::cos(phase)));
        iq.push_back(static_cast<int16_t>(AMP * std::sin(phase)));
    }
    return iq;
}

int status = -1;
void* device = nullptr;
device_info dinfo;
channel ch[8];
uint16_t chn = 0;
uint8_t dnum = 0;
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);
double samplerate = 50e6;
std::vector<int16_t> data;
data = sim_generatewaveform_sine();
double fc = 1.0e9;
float level = 0.0f;
status = tx_config_ffm(ch, fc, level);
tx_trigger trg;
trg.source = TRIGGER_SOURCE_BUS;
status = channel_config_trigger(ch, &trg);
```

```

status = tx_config_stream(ch, samplerate);
status = tx_config_output(ch, STATE_ON, STATE_ON);
status = channel_start(ch);
status = channel_trigger_bus(ch);
for (int i = 0; i < 100000; ++i) {
    status = tx_send_stream(ch, data.data(), data.size() / 2);
    if (status != STATUS_NOERROR) {
        break;
    }
}
status = device_close(&device);

```

8.14 tx_config_playback

```

int tx_config_playback(
    channel* ch,
    const int16_t waveform[],
    const int32_t repeat[],
    const double sample_rate[],
    int16_t waveforms
)

```

Description

Configures waveform playback parameters (ARB Mode) for the specified channels. Once configured, a `channel_trigger_bus` call is required to initiate the transmission via the trigger bus.

Compatibility	2.0.1 and later.
---------------	------------------

Parameter description

[in] ch	Channel configuration array. Refer to the channel structure definition for details.
[in] waveform	Waveform index array. Specifies the indices of the waveforms to be played.
[in] repeat	Waveform repeat count. Specifies the number of playback cycles for each waveform segment within the sequence.
[in] sample_rate	Waveform playback sampling rate.
[in] waveforms	Number of waveforms to play

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	
<pre> std::vector<int16_t> sim_generatewaveform_pulse(double duty_cycle) { constexpr uint32_t TOTAL_IQ_POINTS = 250000; constexpr uint32_t TOTAL_INT16_POINTS = TOTAL_IQ_POINTS * 2; constexpr int16_t I_VALUE = 32766; if (duty_cycle < 0.0) duty_cycle = 0.0; if (duty_cycle > 1.0) duty_cycle = 1.0; uint32_t active_iq = static_cast<uint32_t>(TOTAL_IQ_POINTS * duty_cycle); std::vector<int16_t> iq; iq.reserve(TOTAL_INT16_POINTS); for (uint32_t i = 0; i < active_iq; ++i) { iq.push_back(I_VALUE); // I iq.push_back(0); // Q } uint32_t remain_iq = TOTAL_IQ_POINTS - active_iq; for (uint32_t i = 0; i < remain_iq; ++i) { iq.push_back(0); iq.push_back(0); } return iq; } double samplerate = 125e6; std::vector<int16_t> data; data = sim_generatewaveform_pulse(0.25)); int status = -1; void* device = nullptr; device_info dinfo; channel ch[8]; uint16_t chn = 0; uint8_t dnum = 0; </pre>	

```

status = device_open_usb(&device, dnum, ch, &chn, &dinfo);
double fc = 1.0e9;
float level = 0.0f;
status = tx_config_ffm(ch, fc, level);
tx_trigger trg;
trg.source = TRIGGER_SOURCE_BUS;
status = channel_config_trigger(ch, &trg);
uint16_t waveid = 0;
status = tx_clear_waveform(&device);
status = tx_download_waveform(&device, data.data(), data.size() / 2, &waveid);
int16_t waveforms = 1;
const int16_t waveform[] = { waveid };
const int32_t repeat[] = { -1 };
const double srate[] = { samplerate };
status = tx_config_playback(ch, waveform, repeat, srate, waveforms);
status = tx_config_output(ch, STATE_ON, STATE_ON);
status = channel_start(ch);
status = channel_trigger_bus(ch);
std::this_thread::sleep_for(std::chrono::seconds(10));
status = device_close(&device);

```

9. Modulation Configuration Functions

9.1 mod_open

<pre>int mod_open(void** device, char version_o[50],)</pre>	
Description	
Enables the modulation function. After the device is opened, pass the device information structure to this function for device verification, check whether the modulation library exists, register the function, create the device object, and enable the modulation function.	
Compatibility	2.0.18 and later
Parameter description	
[out] device	Returns the device handle. This handle is used to reference the target device in subsequent API calls.
[out] version_o[50]	Returns the version number of the modulation library.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	Must be called after device_open_* initialization.
Example	Refer to the example of the mod_generate_stream() function.

9.2 mod_close

<pre>int mod_close(void** device)</pre>	
Description	
Disable the modulation function.	
Compatibility	2.0.18and later
Parameter description	
[out] device	Device handle. The handle becomes invalid after the device is closed.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.

Calling constraints	This function should only be called before the modulation program terminates. After execution, the modulation function will be disabled and all related resources will be released. To enable modulation again, <code>mod_open</code> must be called again.
Example	Refer to the example of the mod_generate_stream() function.

9.3 mod_init_digitalmod

<pre>int mod_init_digitalmod(void** device, digitalmod_profile* digitalmod_profile_o)</pre>	
Description	
Initialize the digital modulation configuration structure and assign default values to all parameters in the structure.	
Compatibility	2.0.18 and later
Parameter description	
[in] device	Device handle.
[out] digitalmod_profile_o	Digital modulation configuration structure. For details, refer to the definition of the digitalmod_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after <code>mod_open</code> has been successfully executed.
Example	Refer to the example of the mod_generate_stream() function.

9.4 mod_init_am

<pre>int mod_init_am(void** device, am_profile* am_profile_o)</pre>	
Description	
Initialize the AM modulation configuration structure and assign default values to all parameters in the structure.	

Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] am_profile_o	AM configuration structure. For details, refer to the definition of the am_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.5 mod_init_fm

<pre>int mod_init_fm(void** device, fm_profile* fm_profile_o)</pre>	
Description	
Initialize the FM modulation configuration structure and assign default values to all parameters in the structure.	
Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] fm_profile_o	FM configuration structure. For details, refer to the definition of the fm_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.6 mod_init_dsss

<pre>int mod_init_dsss(void** device, dsss_profile* dsss_profile_o)</pre>	
Description	
Initialize the direct-sequence spread spectrum configuration structure and assign default values to all parameters in the structure.	

Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] dsss_profile_o	Direct-sequence spread spectrum configuration structure. For details, refer to the definition of the dsss_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.7 mod_init_pulse

<pre>int mod_init_pulse(void** device, pulse_profile* pulse_profile_o)</pre>	
Description	
Initialize the pulse modulation configuration structure and assign default values to all parameters in the structure.	
Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] pulse_profile_o	Pulse modulation configuration structure. For details, refer to the definition of the pulse_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.8 mod_init_multitone

```
int mod_init_multitone(  
    void** device,  
    multitone_profile* multitone_profile_o  
)
```

Description

Initialize the multitone configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] multitone_profile_o	Multitone configuration structure. For details, refer to the definition of the multitone_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.9 mod_init_stepsweep

```
int mod_init_stepsweep(  
    void** device,  
    stepsweep_profile* stepsweep_profile_o  
)
```

Description

Initialize the step sweep configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] stepsweep_profile_o	Step sweep configuration structure. For details, refer to the definition of the stepsweep_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.10 mod_init_rampsweep

```
int mod_init_rampsweep(  
    void** device,  
    rampsweep_profile* rampsweep_profile_o  
)
```

Description

Initialize the ramp sweep configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] rampsweep_profile_o	Ramp sweep configuration structure. For details, refer to the definition of the rampsweep_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.11 mod_init_ofdm

```
int mod_init_ofdm (  
    void** device,  
    ofdm_profile* ofdm_profile_o  
)
```

Description

Initialize the OFDM configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] ofdm_profile_o	OFDM configuration structure. For details, refer to the definition of the ofdm_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.12 mod_init_awgn

```
int mod_init_awgn (  
    void** device,  
    awgn_profile* awgn_profile_o  
)
```

Description

Initialize the Gaussian white noise configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] awgn_profile_o	Gaussian white noise configuration structure. For details, refer to the definition of the awgn_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_open has been successfully executed.

9.13 mod_config_digitalmod

```
int mod_config_digitalmod(  
    void** device,  
    const digitalmod_profile* digitalmod_profile_in  
    digitalmod_profile* digitalmod_profile_o  
)
```

Description

Initialize the digital modulation configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[in] digitalmod_profile_in	Input digital modulation configuration structure. For details, refer to the definition of the digitalmod_profile structure.

[out] digitalmod_profile_o	Output digital modulation configuration structure. For details, refer to the definition of the digitalmod_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after <code>mod_open</code> has been successfully executed.
Example	Refer to the example of the mod_generate_stream() function.

9.14 mod_config_am

<pre>int mod_config_am(void** device, const am_profile* am_profile_in am_profile* am_profile_o)</pre>	
Description	
Initialize the AM modulation configuration structure and assign default values to all parameters in the structure.	
Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[in] am_profile_in	Input AM modulation configuration structure. For details, refer to the definition of the am_profile structure.
[out] am_profile_o	Output AM modulation configuration structure. For details, refer to the definition of the am_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after <code>mod_init_am</code> has been successfully executed.

9.15 mod_config_fm

```
int mod_config_fm(  
    void** device,  
    const fm_profile* fm_profile_in  
    fm_profile* fm_profile_o  
)
```

Description

Configure FM modulation parameters. If the input configuration is invalid, the function will overwrite the output configuration structure with valid parameters.

Compatibility	2.0.18 and later
---------------	------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
-------------	----------------

[in] fm_profile_in	Input FM modulation configuration structure. For details, refer to the definition of the fm_profile structure.
--------------------	--

[out] fm_profile_o	Input FM modulation configuration structure. For details, refer to the definition of the fm_profile structure.
--------------------	--

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	This function must be called after mod_init_fm has been successfully executed.
---------------------	--

9.16 mod_config_dsss

```
int mod_config_dsss(  
    void** device,  
    const dsss_profile* dsss_profile_in  
    dsss_profile* dsss_profile_o  
)
```

Description

Initialize the direct-sequence spread spectrum configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18 and later
---------------	------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
-------------	----------------

[in] dsss_profile_in	Input direct-sequence spread spectrum configuration structure. For details, refer to the definition of the dsss_profile structure.
----------------------	--

[out] dsss_profile_o	Output direct-sequence spread spectrum configuration structure. For details, refer to the definition of the dsss_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after <code>mod_init_dass</code> has been successfully executed.

9.17 `mod_config_pulse`

<pre> int mod_config_pulse(void** device, const pulse_profile* pulse_profile_in pulse_profile* pulse_profile_o) </pre>	
Description	
Initialize the pulse modulation configuration structure and assign default values to all parameters in the structure.	
Compatibility	2.0.18 and later
Parameter description	
[in] device	Device handle.
[in] pulse_profile_in	Input pulse modulation configuration structure. For details, refer to the definition of the pulse_profile structure.
[out] pulse_profile_o	Output pulse modulation configuration structure. For details, refer to the definition of the pulse_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after <code>mod_init_pulse</code> has been successfully executed.

9.18 mod_config_multitone

```
int mod_config_multitone(  
    void** device,  
    const multitone_profile* multitone_profile_in  
    multitone_profile* multitone_profile_o  
)
```

Description

Initialize the multitone configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18 and later
---------------	------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
-------------	----------------

[in] multitone_profile_in	Input multitone modulation configuration structure. For details, refer to the definition of the multitone_profile structure.
---------------------------	--

[out] multitone_profile_o	Output multitone modulation configuration structure. For details, refer to the definition of the multitone_profile structure.
---------------------------	---

Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
--------------	--

Calling constraints	This function must be called after mod_init_multitone has been successfully executed.
---------------------	---

9.19 mod_config_stepsweep

```
int mod_config_stepsweep(  
    void** device,  
    const stepsweep_profile* stepsweep_profile_in  
    stepsweep_profile* stepsweep_profile_o  
)
```

Description

Configure step sweep parameters. If the input configuration is invalid, the function will overwrite the output configuration structure with valid parameters.

Compatibility	2.0.18 and later
---------------	------------------

Parameter description	
-----------------------	--

[in] device	Device handle.
-------------	----------------

[in] stepsweep_profile_in	Input step sweep configuration structure. For details, refer to the definition of the stepsweep_profile structure.
[out] stepsweep_profile_o	Output step sweep configuration structure. For details, refer to the definition of the stepsweep_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_init_stepsweep has been successfully executed.

9.20 mod_config_rampsweep

<pre>int mod_config_rampsweep(void** device, const rampsweep_profile* rampsweep_profile_in rampsweep_profile* rampsweep_profile_o)</pre>	
Description	
Configure ramp sweep parameters. If the input configuration is invalid, the function will overwrite the output configuration structure with valid parameters.	
Compatibility	2.0.18and later
Parameter description	
[in] device	Device handle.
[out] rampsweep_profile_o	Ramp sweep configuration structure. For details, refer to the definition of the rampsweep_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_init_rampsweep has been successfully executed.

9.21 mod_config_ofdm

```
int mod_config_ofdm (  
    void** device,  
    const ofdm_profile* ofdm_profile_in  
    ofdm_profile* ofdm_profile_o  
)
```

Description

Configure OFDM parameters. If the input configuration is invalid, the function will overwrite the output configuration structure with valid parameters.

Compatibility	2.0.18 and later
Parameter description	
[in] device	Device handle.
[in] ofdm_profile_o	Input OFDM configuration structure. For details, refer to the definition of the ofdm_profile structure.
[out] ofdm_profile_o	Output OFDM configuration structure. For details, refer to the definition of the ofdm_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after mod_init_ofdm has been successfully executed.

9.22 mod_config_awgn

```
int mod_config_awgn (  
    void** device,  
    const awgn_profile* awgn_profile_in  
    awgn_profile* awgn_profile_o  
)
```

Description

Initialize the Gaussian white noise configuration structure and assign default values to all parameters in the structure.

Compatibility	2.0.18 and later
Parameter description	
[in] device	Device handle.
[in] awgn_profile_in	Input Gaussian white noise configuration structure. For details, refer to the definition of the awgn_profile structure.

[out] awgn_profile_o	Output Gaussian white noise configuration structure. For details, refer to the definition of the awgn_profile structure.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after <code>mod_init_awgn</code> has been successfully executed.

9.23 `mod_generate_stream`

<pre> int mod_generate_stream (void** device, int32_t symbol_length, int16_t** iq_o, int32_t* length_o, double* sample_rate_o) </pre>	
Description	
After enabling the modulation function, call the initialization function to assign default values, and then use the configuration structure functions to apply parameters and generate signal data.	
Compatibility	2.0.18 and later
Parameter description	
[in] device	Device handle.
[in] symbol_length	Symbol length, used for digital modulation and direct-sequence spread spectrum modulation.
[out] iq_o	Output signal data.
[out] length_o	Output data length.
[out] sample_rate_o	Sampling rate used for generating the current data.
Return value	0: Success; Non-zero: Error code. Refer to the Appendix 1 for details.
Calling constraints	This function must be called after <code>device_open_*</code> has been successfully executed.
Example	
<pre> /* Startup configuration and device information */ int status = 0; void* device = nullptr; device_info dinfo; </pre>	

```

channel ch[MAXCHANNELS];
uint16_t chn = 0;
uint8_t dnum = 0;
char version[50] = { "" };
int16_t* iq = nullptr;
int32_t length = 0;
double sampleRate = 0;

/* Device initialization */
status = device_open_usb(&device, dnum, ch, &chn, &dinfo);
if (status != 0) {
    std::cout << "[ERROR] device_open_usb failed! status = " << status << std::endl;
    return status; // If open fails, do not proceed to waveform generation/modulation stage
}

/* Enable modulation */
status = mod_open(&device, version);
digitalmod_profile digitalModProfile_in;
digitalmod_profile digitalModProfile_out;
mod_init_digitalmod(&device, &digitalModProfile_in);

/* Parameter configuration */
digitalModProfile_in.digitalmod_type = DigitalModType_BPSK;
digitalModProfile_in.symbolrate = 5e6;
digitalModProfile_in.sps = 4;
status = mod_config_digitalmod(&device, &digitalModProfile_in, &digitalModProfile_out);

/* Get modulated waveform data */
uint32_t symbol_length = 1U << digitalModProfile_out.pn;
status = mod_generate_stream(&device, symbol_length, &iq, &length, &sampleRate);

// Extend IQ data; both I and Q exceed 65536 points
std::vector<int16_t> vector;
if (length < 65536 * 2) {
    int count = std::ceil(65536.0 * 2 / length);

```

```

vector.resize(count * length);
for (int i = 0; i < count; i++) {
    memcpy(vector.data() + i * length, iq, length * sizeof(int16_t));
}
length = count * length;
}

/* RF configuration */
double fc = 1.0e9; // Output frequency Hz
float level = 0.0f; // Output power dBm
status = tx_config_ffm(ch, fc, level); // Configure fixed frequency mode
print_status(status);

/* Trigger configuration */
tx_trigger trg;
trg.source = TRIGGER_SOURCE_BUS;
status = channel_config_trigger(ch, &trg);
print_status(status);

/* Waveform download */
uint16_t waveid = 0;
status = tx_clear_waveform(&device);
int16_t* final_waveform = vector.empty() ? iq : vector.data();
status = tx_download_waveform(&device, final_waveform, length/2, &waveid);
print_status(status);

/* Baseband configuration */
int16_t waveforms = 1; // Number of waveforms to play
const int16_t waveform[] = { waveid }; // Waveform IDs to be played
const int32_t repeat[] = { -1 }; // Repeat count for each waveform, -1 means infinite
loop
const double srate[] = { sampleRate }; // Sampling rate for each waveform
status = tx_config_playback(ch, waveform, repeat, srate, waveforms); // Configure playback
print_status(status);

```

```
status = tx_config_output(ch, STATE_ON, STATE_ON); // Enable output
status = channel_start(ch); // Start channel
status = channel_trigger_bus(ch);

std::this_thread::sleep_for(std::chrono::seconds(10));

status = mod_close(&device); // Close modulation
if (status) {
    std::cout << __LINE__ << ", mod_close_status = " << status << std::endl;
}

status = device_close(&device); // Close device
return 0;
```

10. Structure Variables

10.1 device_info

device_info	
uint16_t model	Device model.
uint64_t uid_l64	Low 64-bit device serial number.
uint32_t uid_h32	High 32-bit device serial number.
uint16_t hardware_version	Hardware version.
uint32_t mfw_version	MCU firmware version.
uint32_t ffw_version	FPGA firmware version.
uint32_t pmu_version	PMU firmware version.
uint32_t agu_version	AGU firmware version.
uint32_t bus_version	Bus peripheral firmware version.
uint32_t eio_version	EIO firmware version.
uint32_t bus_bandwidth	Bus bandwidth, unit MB/s.

10.2 supply_info

supply_info	
float rf_voltage	Power port voltage, in V.
float rf_current	Power port current, in A.
float usb_voltage	USB port voltage, in V.
float usb_current	USB port current, in A.

10.3 eth_setting

eth_setting	
eth_interface_type eth_interface	Physical interface type. Refer to the eth_interface_type enumeration structure definition for details.
uint8_t eth_is_ipv6	ETH protocol type (0: IPv4, 1: IPv6).
uint8_t eth_ip_address[16]	IP address of the ETH interface.
uint16_t eth_remote_port	Remote port of the ETH interface.
int32_t eth_read_timeout	ETH interface read timeout, in ms.

10.4 gnss_setting

gnss_setting	
uint8_t antenna	Antenna path selection. 0 for internal antenna, 1 for external antenna.
uint8_t pps_en	PPS enable state.
float pps_x	PPS frequency (in Hz).
float pps_delay	PPS delay (in seconds).

10.5 gnss_info

gnss_info	
state locked	GNSS lock status, 0: unlocked, 1: locked. Refer to the state enumeration structure definition for details.
uint8_t sat_nums	Current number of GNSS satellites in view.
uint8_t snr_max	Maximum SNR of the currently tracked GNSS satellites.
uint8_t snr_avg	Average SNR of the currently tracked GNSS satellites.
uint8_t snr_min	Minimum SNR of the currently tracked GNSS satellites.
float latitude	Latitude: positive for north, negative for south.
float longitude	Longitude: positive for east, negative for west.
float altitude	Altitude in m.
uint64_t ns_sinceepoch	System timestamp (nanoseconds).

10.6 channel

channel	
void** device	Device handle to which the channel belongs.
uint16_t num	Channel number.
channel_type type	Channel type. Refer to the channel_type enumeration structure definition for details.

10.7 tx_trigger

tx_trigger	
trigger_source source	Trigger source. Refer to the trigger_source enumeration structure definition for details.
trigger_edge edge	Trigger edge. Refer to the trigger_edge enumeration structure definition for details. This parameter is invalid under bus trigger mode.
trigger_action action	Trigger action; this parameter is invalid under fixedpoints mode. Refer to the trigger_action enumeration structure definition for details.
int32_t count	Number of trigger responses: -1 indicates unlimited responses; >0 specifies a limited number of responses; after responding count times, triggering stops and must be reactivated. Ignored in fixed-frequency mode. When the trigger action is TRIGGER_ACTION_HOP, one trigger switches through count RF states, with the interval between states defined by the configured dwell time. When the trigger action is TRIGGER_ACTION_SWEEP, one trigger performs count sweeps, and the time interval within each sweep is defined by the configured dwell time.

10.8 trigger_out

trigger_out	
state enable	Trigger output state. Refer to the state enumeration structure definition for details.
trigger_action action	Trigger action. Outputting a trigger signal upon completion of a single hop or a full sweep sequence. Refer to the trigger_action enumeration structure definition for details.
trigger_edge edge	Trigger edge. Refer to the trigger_edge enumeration structure definition for details.

10.9 digitalmod_profile

digitalmod_profile	
mod_digitalmod_type digitalmod_type	Trigger output status. Refer to the definition of the mod_digitalmod_type enumeration.
double symbolrate	Symbol rate, in Hz. Range: minimum sampling rate / samples per symbol ~ maximum sampling rate / samples per symbol.
double fskdeviation	FSK frequency deviation, in Hz, maximum is $15 \times$ symbol rate.
int32_t pn	Pseudo-random sequence, range 4 to 32, recommended maximum not exceeding 24.
mod_filter_type filter_type	Filter type. Refer to the definition of the mod_filter_type enumeration.
int32_t filter_symbols	Number of filter symbols, must be an even number. Range: 2 to ($\text{sps} \times \text{filter_symbols} \leq 400$), default is 8.
int32_t sps	Samples per symbol, even number from 4 to 32, default is 4.
double alpha	Raised cosine / root raised cosine: 0.025 to 1 Gaussian filter: 0.15 to 2.5 The alpha parameter is only valid for raised cosine, root raised cosine, and Gaussian filtering.

10.10 am_profile

am_profile	
double rate	Modulation rate, in Hz.
double depth	Modulation depth, in %.
mod_shape_type shape	Modulation waveform. Refer to the definition of the mod_shape_type enumeration.

10.11 fm_profile

fm_profile	
double rate	Modulation rate, in Hz.
double deviation	Frequency deviation of the modulation, in Hz.
mod_shape_type shape	Modulation waveform. Refer to the definition of the mod_shape_type enumeration.

10.12 dsss_profile

dsss_profile	
double symbolrate	Symbol rate, in Hz.
mod_digitalmod_type digitalmod_type	Digital modulation type. Refer to the definition of the mod_digitalmod_type enumeration.
int32_t code	Spreading code, PN value, recommended value: 5.
int32_t filter_symbols	Number of filter symbols, must be an even number. Range: 2 to (sps × filter_symbols ≤ 400), default is 8.
int32_t sps	Samples per symbol, even number from 4 to 32, default is 4.
double alpha	Raised cosine / root raised cosine: 0.025 to 1 Gaussian filter: 0.15 to 2.5 The alpha parameter is only valid for raised cosine, root raised cosine, and Gaussian filtering.
int32_t sequenceseed	Initial seed of the pseudo-random sequence, range: 1 to 2,147,483,647.
mod_filter_type filter_type	Filter type. Refer to the definition of the mod_filter_type enumeration.

10.13 pulse_profile

pulse_profile	
double width	Pulse width, in seconds (s).
double period	Period, in seconds (s). The period must be greater than the pulse width.

10.14 multitone_profile

multitone_profile	
double tonephase	Phase, in the range [0, 2*pi].
int32_t tonecount	Number of tones.
double freqspacing	Frequency spacing, in Hz.

10.15 stepsweep_profile

stepsweep_profile	
double center	Center frequency, in Hz.
double span	Span, in Hz.
int32_t points	Number of points.
double dwelltime	Dwell time, in seconds (s).

10.16 rampsweep_profile

rampsweep_profile	
double span	Span, in Hz.
double sweeptime	Sweep time, in seconds (s).
double period	Period, in seconds (s).

10.17 ofdm_profile

ofdm_profile	
double idleinterval	Idle time between transmit bursts, in seconds (s).
int32_t fftsize	Number of FFT points, supporting 16, 32, 64, 128, 256, 512, 1024, and 2048. Additionally, fftsize > guardbandcarriers_left + guardbandcarriers_right.
int32_t symbolcount	Number of symbols.
int32_t guardbandcarriers_left	Number of guard carriers on the left side.
int32_t guardbandcarriers_right	Number of guard carriers on the right side.
int32_t guardinterval	Guard interval, in %.
int32_t window_length	Window length, in %.
uint8_t windowed	Whether windowing is enabled.
mod_digitalmod_type digitalmod_type	Digital modulation type. Note: only the following types are supported: DigitalModType_BPSK、DigitalModType_QPSK、DigitalModType_PSK8、DigitalModType_PSK16、DigitalModType_QAM16、DigitalModType_QAM64、DigitalModType_QAM256
uint8_t nulldc	Whether DC is nulled.
double samplerate	Sampling rate: 195.3125e3 to 125e6, default is 20 MHz.

10.18 awgn_profile

awgn_profile	
double bandwidth	Idle time between transmit bursts, in seconds (s).
int32_t length	Number of FFT points, supporting 16, 32, 64, 128, 256, 512, 1024, and 2048. Additionally, fftsize > guardbandcarriers_left + guardbandcarriers_right.

11. Enumeration Variables

11.1 state

STATE_OFF	Global configuration, 0.
STATE_ON	Global configuration, 1.

11.2 fan_mode

FAN_ON	Fan forced on mode.
FAN_OFF	Fan forced off mode.
FAN_AUTO	Automatically adjust fan state based on temperature

11.3 eth_interface_type

ETH_HIGHSPEED	High-speed Ethernet bus interface
ETH_STANDARD	Standard Ethernet bus interface

11.4 referenceclock_source

REFCLKSOURCE_INTERNAL	Internal reference clock source
REFCLKSOURCE_EXTERNAL	External reference clock source

11.5 lomode

LOMODE_AUTO	In this mode, the instrument automatically selects the optimal operating parameters based on the current output frequency, frequency step, and operating state.
LOMODE_LOWSPUR	This mode optimizes the phase noise performance of the local oscillator by adjusting the PLL control strategy to improve signal phase stability.
LOMODE_LOWPHASENOISE	This mode optimizes the local oscillator output spectrum, effectively suppressing fractional spurs and related spurious components to improve spectral purity.

11.6 channel_type

CHANNELTYPE_RX	Receive channel.
CHANNELTYPE_TX	Transmit channel.
CHANNELTYPE_VX	Vector network analysis channel.

11.7 trigger_action

TRIGGER_ACTION_HOP	Execute a single frequency hop.
TRIGGER_ACTION_SWEEP	Perform a full sweep.

11.8 trigger_edge

TRIGGER_EDGE_RISING	Rising edge trigger.
TRIGGER_EDGE_FALLING	Falling edge trigger.

11.9 trigger_source

TRIGGER_SOURCE_BUS	Bus trigger: under this trigger, trigger edges are ignored.
TRIGGER_SOURCE_EXTERNAL	External trigger.
TRIGGER_SOURCE_XPPS	GNSS 1PPS trigger.
TRIGGER_SOURCE_LEVEL	Level trigger (Rx only).
TRIGGER_SOURCE_FREQMASK	Spectrum template trigger (Rx only).

11.10 mod_digitalmod_type

DigitalModType_BPSK	BPSK
DigitalModType_DBPSK	DBPSK
DigitalModType_QPSK	QPSK
DigitalModType_DQPSK	DQPSK
DigitalModType_OQPSK	OQPSK
DigitalModType_Pi4DQPSK	Pi4DPSK
DigitalModType_PSK8	8PSK
DigitalModType_D8PSK	D8PSK
DigitalModType_PSK16	16PSK
DigitalModType_QAM16	16QAM
DigitalModType_QAM64	64QAM
DigitalModType_QAM256	256QAM
DigitalModType_QAM1024	1024QAM
DigitalModType_ASK2	2ASK
DigitalModType_FSK2	2FSK
DigitalModType_FSK4	4FSK
DigitalModType_FSK8	8FSK
DigitalModType_FSK16	16FSK
DigitalModType_ASK4	4ASK
DigitalModType_ASK8	8ASK
DigitalModType_APSK16	16ASK
DigitalModType_QAM8	8QAM

11.11 mod_filter_type

FilterType_Rectangular	Rectangular filter
FilterType_RaisedCosine	Raised cosine filter
FilterType_RootRaisedCosine	Root raised cosine filter
FilterType_Gaussian	Gaussian filter
FilterType_HalfSine	Half-sine filter

11.12 mod_shape_type

ModShape_Sine	Sine wave
ModShape_Square	Square wave
ModShape_Triangle	Triangle wave
ModShape_Ramp	Sawtooth wave

Appendix 1: API Return Value Index

Error Code	Error/Warning Reason	Type[1]	Handling
0	No error	-	No action required; subsequent operations can proceed normally.
-1	Bus open error	Error	Check device power and data cable connections. Verify that the driver is correctly installed. After resolving the issue, call device_open_usb again to open the device.
-8	Bus transmission error	Error	Reconnect the device. If the issue persists, please contact official technical support.
-29	Transmit power calibration file missing [2]	Error	Check whether the transmit power calibration file is placed in the designated directory. After resolving the issue, call device_open_usb again to open the device.
-43	IQ calibration file missing [2]	Error	Check whether the IQ calibration file is placed in the designated directory. After resolving the issue, call device_open_usb again to open the device.
10	Data transmission timeout	Warning	Wait 10 ms, then retry sending.
42	Using default transmit power calibration file	Warning	Does not affect device operation, but RF output power may deviate.
44	Using default IQ calibration file	Warning	Does not affect device operation, but accuracy may be affected.
98	Parameter out of range, clamped	Warning	The out-of-range parameters are automatically forced back into the device's valid range. The actual values at that time can be queried via the query function. This does not affect continued device operation.
99	Transmit power is too low, but still within limits	Warning	The power level may be inaccurate, but this does not affect continued device operation. Please contact official technical support.
100	Transmit power is too high, but still within limits	Warning	The power level may be inaccurate, but this does not affect continued device operation. Please contact official technical support.
15	System clock unlocked	Warning	The test results may be inaccurate, but this does not affect continued device operation. Please contact official technical support.
16	ADC clock unlocked	Warning	The test results may be inaccurate, but this does not affect continued device operation. Please contact official technical support.
18	RF local oscillator unlocked	Warning	The test results may be inaccurate, but this does not affect continued device operation. Please contact official technical support.

-601	Modulation license file missing	Error	Please place the xx._mod.lic file in the /CalFile/ folder.
-602	Modulation license file verification failed	Error	Usually due to incorrect license content; please contact official technical support.
-603	Device validation failed	Error	Device validation failed when creating the device object. Please check if the device is properly opened and contact official technical support.
-604	Object creation failed	Error	Object creation failed when creating the device object. Please check if the device is properly opened and contact official technical support.
-605	Object release failed	Error	Failed to release the device object. Please contact official technical support.
-606	Modulation type error	Error	When generating a signal, the input modulation type is incorrect. Please correct the modulation type, resend, and regenerate the signal.
-607	Modulation parameter error	Error	When generating a signal, the input modulation parameters are incorrect. Please correct the modulation parameters, resend, and regenerate the signal.
-608	Modulation library missing	Error	The modulation library is not found in the same path as the h2_api library. Please place genSignalWave.dll (Windows) or libgenSignalWave.so (Linux) in the same path as the h2_api library.
-609	Parameter cannot be configured	Error	The current parameter cannot be configured. The last available parameter has been applied.

- [1]. If the type is "Error," the issue must be resolved immediately and the device reopened; otherwise, the device cannot continue with subsequent operations. If the type is "Warning," the device can continue with subsequent operations without closing or reopening, but it is still recommended to handle specific return values selectively based on the current application scenario.
- [2]. For return values -29 and -43, it is also necessary to confirm that the file path contains only English characters. If the path contains Chinese characters, the API will report a file load failure.

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