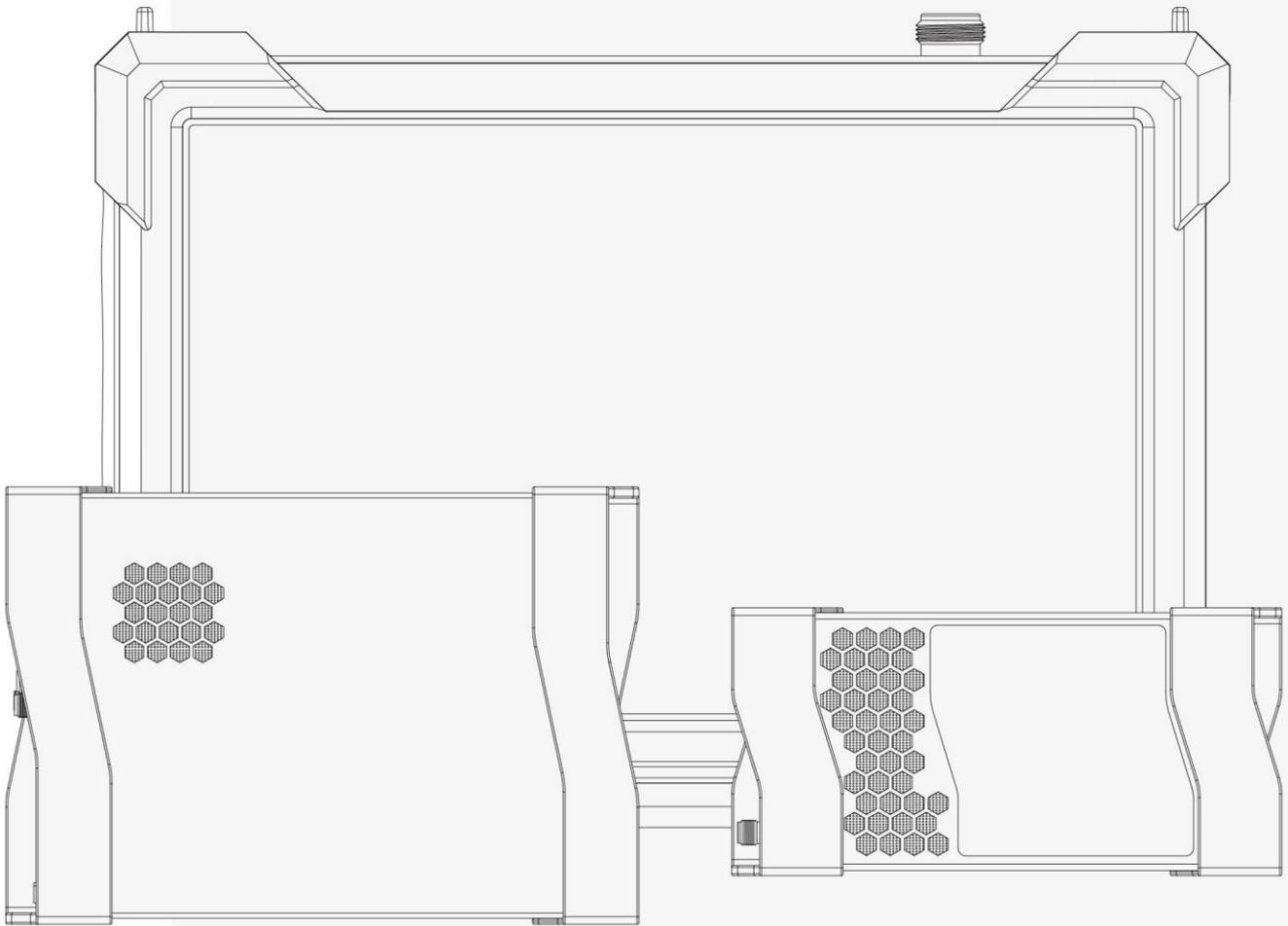




# HTRA API Example Usage Guide



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# Version Management

Updated Description Sheet

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| Version | Description     | Date       |
|---------|-----------------|------------|
| V2.0    | Initial Version | 12/05/2025 |

# 1. C/C++

## 1.1 Configure Development Environment

The following uses configuring Debug Win32 as an example. For [other build types and platforms](#), please refer to the end of this chapter.

1. Open Visual Studio 2019 and create a new project;
2. After creation is complete, copy the "Windows\HTRA\_API" folder from the delivery USB drive to a directory at the same level as the project;

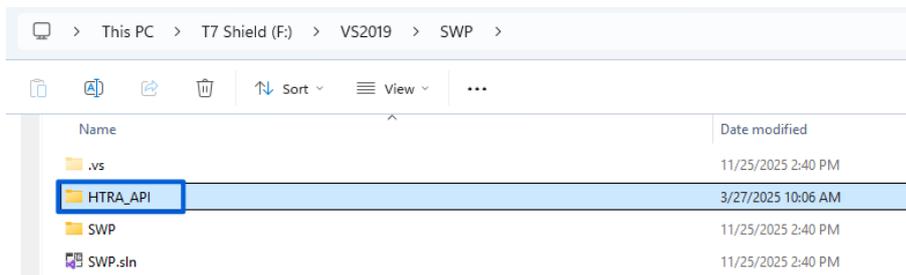


Figure 1 Copy the HTRA\_API file

3. Double-click to open SWP.sln, right-click on "Source Files" -> "Add" -> "New Item" -> "C++ File (.cpp)" to create a new SWP.cpp file;
4. Click "Project" -> "Properties" in the menu bar, set "Configuration" to "Debug" and "Platform" to "Win32";
5. In Configuration Properties -> Debugging, set the Environment variable to "Path=..\HTRA\_API\x86";

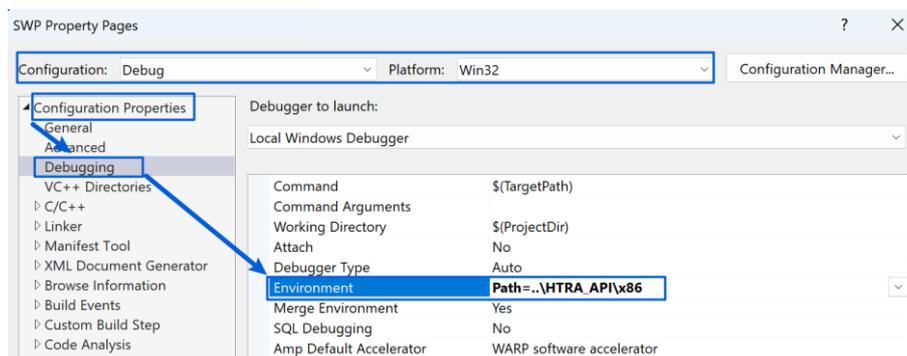


Figure 2 Configure environment variables

6. In Configuration Properties -> C/C++ -> General, set the Additional Include Directories to "\$\$(SolutionDir)\HTRA\_API\x86";

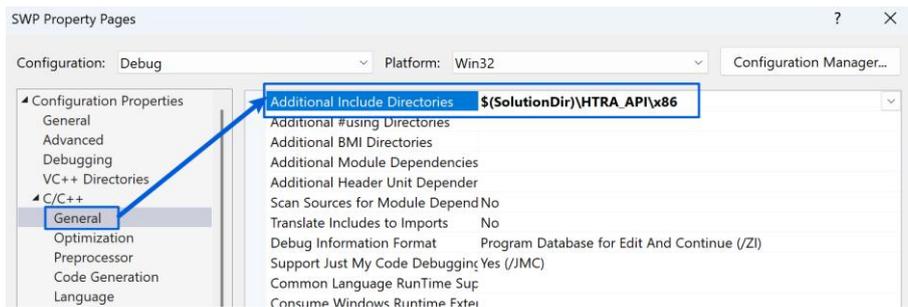


Figure 3 Add additional include directories

- Set the "Additional Library Directories" under Configuration Properties -> Linker -> General to "\$(SolutionDir)\HTRA\_API\x86";

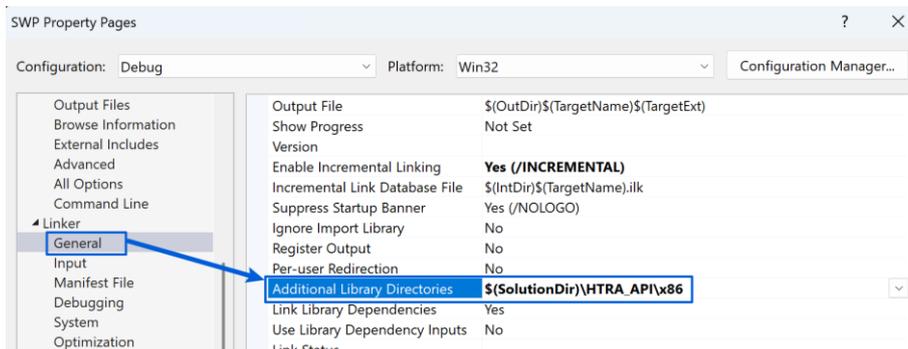


Figure 4 Configure additional library directories

- Add "htra\_api.lib" to "Additional Dependencies" under Configuration Properties -> Linker -> Input, then click "OK".

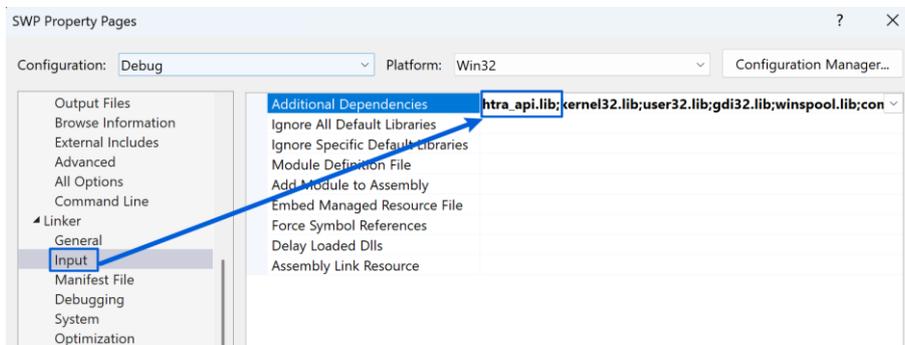


Figure 5 Configure additional dependencies

- Configure Release Win32: Set "Configuration" in [Step 4](#) to "Release", and keep all other settings unchanged;
- Configure Debug x64: Set "Configuration" in [Step 4](#) to "Debug" and "Platform" to "x64". Also replace all environment variables or additional directory paths containing "HTRA\_API\x86" with "HTRA\_API\x64";
- Configure Release x64: Set "Configuration" in [Step 4](#) to "Release" and "Platform" to "x64". Also replace all environment variables or additional directory paths containing "HTRA\_API\x86" with "HTRA\_API\x64";

## 1.2 Usage Process for C++ Examples

Note: Only one example can run at a time, and the example cannot run simultaneously with SASStudio4.

### 1.2.1 Usage of General C++ Example

1. Use Visual Studio to open the solution HTRA\_C++\_Examples.sln located in the folder Windows\HTRA\_API\_Example\HTRA\_C++\_Examples on the provided USB drive;
2. Click the HTRA\_C++\_Examples project on the right, then open the main.cpp file under the Source Files folder;
3. Each example program is encapsulated in a separate function. To use one, uncomment the corresponding routine, save the file, select the build architecture, and then click Run.

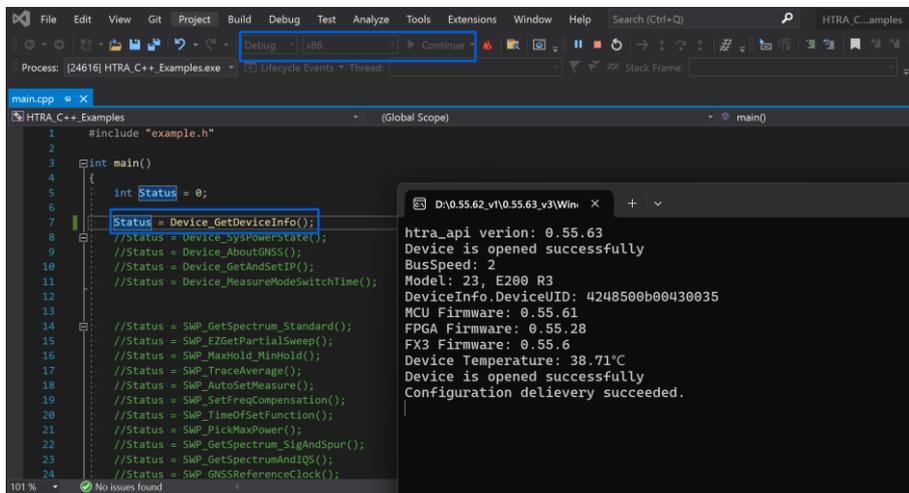


Figure 6 Run the Device\_GetDeviceInfo example

### 1.2.2 Usage of the AM/FM Demodulation Example

1. Open the solution Htra\_Demodulation.sln in Windows\HTRA\_C++\_Examples\Htra\_Demodulation on the supplied USB drive using Visual Studio;
2. Click the Htra\_Demodulation project on the right, then open the main.cpp file under the Source Files folder;
3. In the C++ example package, each demo routine is encapsulated in a separate function. To run a demo, uncomment the corresponding routine, save the file, select the build architecture, and click Run.

### 1.2.3 Usage of the Recording and Playback Example

1. Open the solution Htra\_RecordingandPlayBack.sln in Visual Studio, located in the USB drive under Windows\HTRA\_API\_Example\Htra\_RecordingandPlayBack;
2. Double-click the Htra\_RecordingandPlayBack project on the right to open the main.cpp file in the source files;
3. Each routine in the recording and playback example is encapsulated in a separate function. To use the example, simply uncomment it.

#### ■ Usage of the Reading Example

- 1) For example, when reading SWP mode stream disk data, uncomment the SWPMode\_PlayBack function and save;
- 2) Place the recording file generated in SWP mode into the folder Windows\HTRA\_C++\_Examples\Htra\_RecordingandPlayBack\Htra\_RecordingandPlayBack\data;

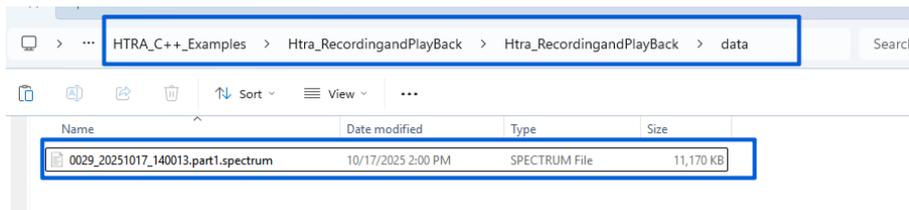


Figure 7 Place the recording file under the standard spectrum analysis mode

- 3) Click to enter SWPMode\_PlayBack.cpp and modify the name of the recorded file in the SWPMode\_PlayBack() function;

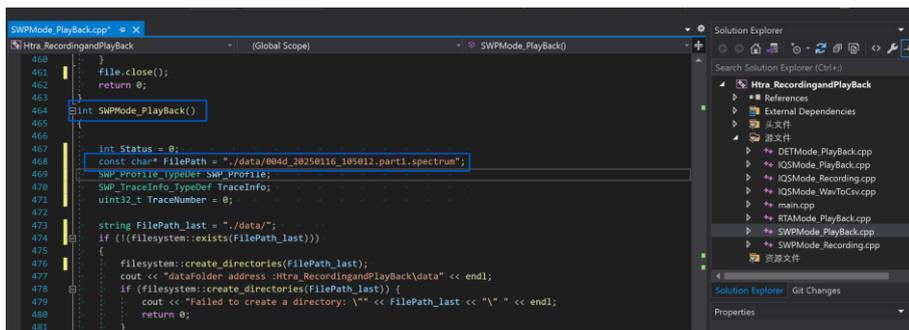


Figure 8 Modify the recording file name

- 4) Running the program will generate the parsed data file "SWPMode\_Data.txt" in the data folder under the SWP mode.

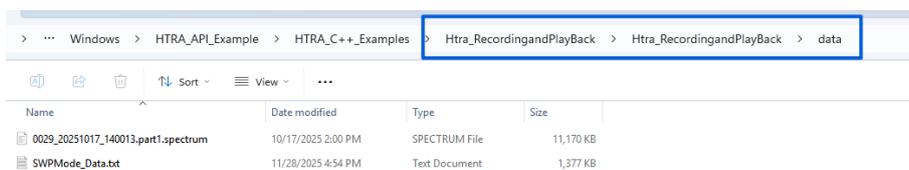


Figure 9 View the parsed data in SWP mode

## ■ Usage of the Recording Example

- 1) For example, when testing the IQSMODE\_Recording routine, uncomment and save;
- 2) Click to enter the IQSMODE\_Recording() function, configure the relevant parameters, and then run the program. During execution, the file will be continuously recorded until manually stopped;
- 3) The recording file data in IQS mode can be found in the HTRA\_C++\_Examples\Htra\_RecordingandPlayBack\Htra\_RecordingandPlayBack\data folder.

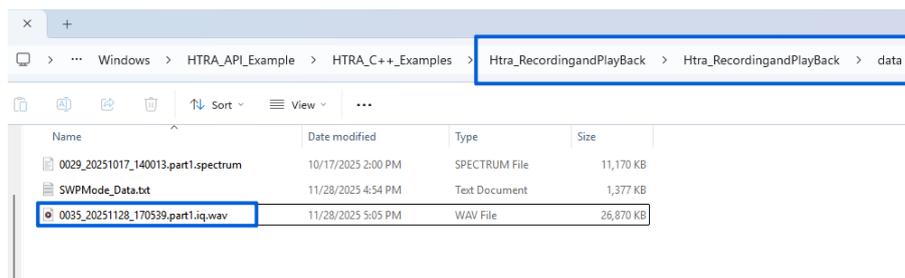


Figure 10 View the recorded file data in IQ streaming mode

## 1.3 Device-related

### 1.3.1 Get Device Information

Device\_GetDeviceInfo.cpp: Get device information, including API version, USB version, device model, device UID, MCU version, FPGA version, and device temperature.

### 1.3.2 Device Standby

Device\_SysPowerState.cpp: An example of setting the device's standby state, which can be configured to normal operating state or RF powered down state (low power).

### 1.3.3 GNSS-related

Device\_AboutGNSS.cpp: Retrieves information such as latitude, longitude, altitude, and time obtained from the GNSS module, acquires GNSS-related latitude and time information from MeasAuxInfo in SWP mode, and obtains latitude and time information from IQStream.DeviceState in IQS mode.

### 1.3.4 Get and modify the IP address of the NX device

Device\_GetAndSetIP.cpp: Retrieve the device's IP address and modify it using the device UID or the device's current IP address.

### 1.3.5 Mode switching time consumption

Device\_MeasureModeSwitchTime.cpp: Get the time required for the current host computer to switch between different modes.

## 1.4 SWP Mode

### 1.4.1 10 MHz Reference Clock Using Internal GNSS Module

SWP\_GetSpectrum\_Standard.cpp: Obtain spectrum data by calling the function interface.

### 1.4.2 Maximum and minimum hold

SWP\_MaxHold\_MinHold.cpp: Set the trace mode to MaxHold or MinHold, and use SWP\_ResetTraceHold to reset the hold.

### 1.4.3 Average Trace

SWP\_TraceAverage.cpp: Average processing of the acquired trace.

### 1.4.4 Automatic Configuration Measurement

SWP\_AutoSetMeasure.cpp: Automatically configures relevant parameters based on specific SWP applications, completing measurements by issuing automatic configuration parameters.

### 1.4.5 Frequency Compensation

SWP\_SetFreqCompensation.cpp: When an external attenuator is present, compensation can be applied to the corresponding frequency band to ensure that the test results remain accurate.

### 1.4.6 Function execution time, sweep speed, and throughput

SWP\_TimeOfSetFunction.cpp: Obtains the call duration of the SWP\_Configuration, SWP\_GetPartialSweep, and SWP\_GetFullSweep functions, along with the sweep speed and throughput under the current configuration.

### 1.4.7 Obtain spectrum peak values

SWP\_PickMaxPower.cpp: Obtain the maximum power point of the current spectrum and its corresponding frequency point.

### 1.4.8 Signals and Spurious

SWP\_GetSpectrum\_SigAndSpur.cpp: This can distinguish between signals and spurious after obtaining spectrum data.

### 1.4.9 Simultaneous Acquisition of Spectrum and IQ

SWP\_GetSpectrumAndIQS.cpp: This allows for the simultaneous acquisition of spectrum data and IQ data.

### 1.4.10 Reading SWP Stream Disk Data from Application Software

SWPMode\_PlayBack.cpp: This can read the recorded file data in SWP mode from Application Software and write the read spectrum data into SWP Mode\_Data.txt.

#### [1.4.11 Using GNSS 10MHz Reference Clock](#)

SWP\_GNSSReferenceClock.cpp: This uses a high-quality GNSS module's 10MHz reference clock in SWP mode.

#### [1.4.12 External Trigger Mode](#)

SWP\_GetSpectrum\_Trigger.cpp: This obtains spectrum data when the trigger source is set to external trigger.

#### [1.4.13 Trace Alignment Method](#)

SWP\_GetSpectrum\_TraceAlign.cpp: Obtain spectrum data when the trace alignment method is set to align to the starting frequency or align to the center frequency.

#### [1.4.14 Number of Spectrum Frames Obtainable within a Certain Time](#)

SWP\_Fixedtime\_GetFrames.cpp: Loop 50 times to obtain 10 seconds of spectrum data, resulting in the average number of spectrum frames that can be obtained within 10 seconds.

#### [1.4.15 External Trigger Calibration of Internal 10MHz Reference Clock](#)

SWP\_GetSpectrum\_Calibration.cpp: An example of the device calibrating the clock via GNSS-1PPS or through external trigger.

#### [1.4.16 Phase noise measurement](#)

SWP\_Meas\_PhaseNoise.cpp: Measures the single-sideband phase noise (unit: dBc/Hz) of the received signal at the user-specified frequency deviation, supports multi-frequency point configuration.

#### [1.4.17 Channel power measurement](#)

SWP\_Meas\_ChannelPower.cpp: Measures the channel power of the received signal.

#### [1.4.18 Adjacent Channel Power Ratio Measurement](#)

SWP\_Meas\_ACPR.cpp: Measure the adjacent channel power ratio of the received signal.

#### [1.4.19 Percentage occupied bandwidth Measurement](#)

SWP\_Meas\_OBW.cpp: Measures the occupied bandwidth of the received signal in percentage.

#### [1.4.20 XdB Occupied Bandwidth Measurement](#)

SWP\_Meas\_XdBBW.cpp: Measures the occupied bandwidth of the received signal in XdB.

#### [1.4.21 IM3 measurements](#)

SWP\_Meas\_IM3.cpp: IM3 measurement of the received signal.

### 1.4.22 Frequency interval matching RBW

SWP\_RBW\_Spaced\_Trace.cpp: Makes the frequency interval between two points of the trace close to the set RBW value.

### 1.4.23 Using an External 10MHz Reference Clock

SWP\_RefCLKSource\_External.cpp: Use external 10MHz reference clock. (Take the use of external 10MHz reference clock in SWP mode as an example, the same method is used in other modes).

## 1.5 IQS Mode

### 1.5.1 Obtain Fixed Number or Continuous Stream of IQ Data

IQS\_GetIQ\_Standard.cpp: Obtain a fixed number or continuous stream of IQ data under professional configuration.

### 1.5.2 IQ data converted to voltage V units

IQS\_ScaleIQDataToVolts.cpp: Converts the acquired IQ data into data in volts (V).

### 1.5.3 Time taken to issue configuration and acquire IQ

IQS\_ConfigandGetIQ\_Time.cpp: Obtains the call duration of the IQS\_Configuration and IQS\_GetIQStream\_PM1 functions.

### 1.5.4 IQ to Spectrum Data

DSP\_IQSToSpectrum.cpp: Converts the acquired time-domain IQ data into spectrum data using spectral analysis methods.

### 1.5.5 IQ to Spectrum (using liquid library version)

IQS\_ToSpectrumByLiquid.cpp: Uses the liquid library to convert the acquired time-domain IQ data into spectrum data through spectral analysis methods.

### 1.5.6 FM Demodulation Playback

DSP\_FMDemod.cpp: Performs FM demodulation on the IQ data and plays the demodulated audio.

### 1.5.7 FM Demodulation Data Analysis

IQS\_FMDDataAnalysis.cpp: Audio analysis of the IQ data after FM demodulation to get the audio voltage, audio frequency, SINAD and total harmonic distortion.

### 1.5.8 AM Demodulation Playback

DSP\_AM\_Demod.cpp: Performs AM demodulation on IQ data and plays the demodulated audio.

### 1.5.9 AM Demodulation Data Analysis

IQS\_FMDDataAnalysis.cpp: Audio analysis of the IQ data after AM demodulation to get the audio voltage, audio frequency, SINAD and total harmonic distortion.

### 1.5.10 Digital Downconversion

DSP\_DDC.cpp: Resamples the obtained IQ data.

### 1.5.11 Digital Low-Pass Filter

DSP\_LPF.cpp: Perform low-pass filtering on the obtained IQ data.

### 1.5.12 Audio Analysis

IQS\_AudioAnalysis.cpp: Performs audio analysis on the demodulated IQ data to obtain audio voltage, audio frequency, SINAD, and total harmonic distortion.

### 1.5.13 Read the IQS stream disk data from Application Software

IQSMode\_PlayBack.cpp: Parses the recorded file data in IQS mode from Application Software and writes the read spectrum data into the IQSMode\_Data.txt file.

### 1.5.14 Record IQ data in .wav format

IQSMode\_Recording.cpp: Stores the acquired IQ data in .wav format.

### 1.5.15 .wav changed to .csv

IQSMode\_WavToCsv.cpp: Parses and extracts I and Q channel data from the .wav recording file data in IQS mode, converting it into a .CSV format file for saving.

### 1.5.16 Streaming and reading IQ data

IQS\_GetIQToTxt.cpp: Writes the obtained IQ data into a .txt file.

### 1.5.17 Multithreaded acquisition, processing, and streaming of IQ data

IQS\_Multithread\_GetIQ\_FFT\_Write: Simultaneously acquires IQ data, performs FFT, and writes IQ data into a .txt file.

### 1.5.18 GNSS1PPS trigger

IQS\_GNSS\_1PPS.cpp: Configure the trigger source to be the 1PPS signal provided by the internal GNSS system.

### 1.5.19 IQS multi-device synchronization

IQS\_MultiDevSync\_fixed.cpp: Multiple devices simultaneously collect the same signal at the same time.

### 1.5.20 External Trigger

IQS\_ExternalTrigger.cpp: Configure the trigger source as external trigger.

### 1.5.21 Timer Trigger

IQS\_TimerTrigger.cpp: Configure the trigger source as timer trigger.

### 1.5.22 Level Trigger(pre-trigger)

IQS\_LevelTrigger\_PreTriggerr.cpp: Configure the trigger source as level trigger and set the pre-trigger time.

### 1.5.23 Level Trigger (Trigger delay)

IQS\_LevelTrigger\_TriggerDelay.cpp: Configure the trigger source to be level trigger and set the trigger delay time.

### 1.5.24 Using GNSS 10MHz Reference Clock

IQS\_Enable\_GNSS\_10MHz.cpp: Use a high-quality GNSS module's 10MHz reference clock in IQS mode.

### 1.5.25 Fixed Step Multi-Frequency IQ Data Acquisition

IQS\_SetFreqScan: Configure the start and end frequencies and frequency points of IQ in advance. After configuring once, the data will be collected sequentially according to the set frequency points.

## 1.6 DET Mode

### 1.6.1 Obtain detection data for fixed points or continuous streams

DETMode\_Standard.cpp: Obtain detection data for fixed points or continuous streams.

### 1.6.2 Read the DET stream disk data of Application Software

DETMode\_PlayBack.cpp: Read the recorded files in DET mode from Application Software and output the detection data to the DETMode\_Data.txt file.

### 1.6.3 Pulse detection (to be opened later)

## 1.7 RTA Mode

### 1.7.1 Obtain real-time spectrum data for fixed points or continuous stream

RTAMode\_Standard.cpp: Obtain real-time spectrum data for a fixed number of points (duration) or continuous stream.

### 1.7.2 Read the RTA stream disk data of Application Software

RTAMode\_PlayBack.cpp: Read the recorded file data in RTA mode from Application Software, while being able to specify reading a certain packet of data, and write the read spectrum data to the RTAMode\_Data.txt file.

### 1.7.3 Time consumption of each frame of data in RTA mode

RTAMode\_Standard\_perframe.cpp: Acquire 100 frames of data and calculate the average processing time for each frame.

## 1.8 ASG Signal Source (optional)

### 1.8.1 Output single tone/sweep/power scan signals

ASG\_SignalOutput.cpp: Output single tone/sweep/power scan signals as needed.

## 2. Qt

### 2.1 Configure Development Environment

The following uses the configuration of an x64 architecture development environment as an example.

1. Create a new folder (taking "QtTest" as an example) to store the project files;
2. Copy the "Windows\HTRA\_API\x64\htra\_api" folder from the provided USB drive into the newly created "QtTest" folder;
3. Open Qt Creator, and click "File" -> "New File or Project";
4. In project dialog, click "Application (Qt)", select "Qt Widgets Application", then click "Choose...";
5. Enter the project name (e.g., "test"), click the "Browse" button, select the previously created "QtTest" folder, and then click "Next";
6. Select "qmake", continue by clicking "Next" until the "Kit Selection" screen appears. On this screen, choose a build environment, and then click "Next";

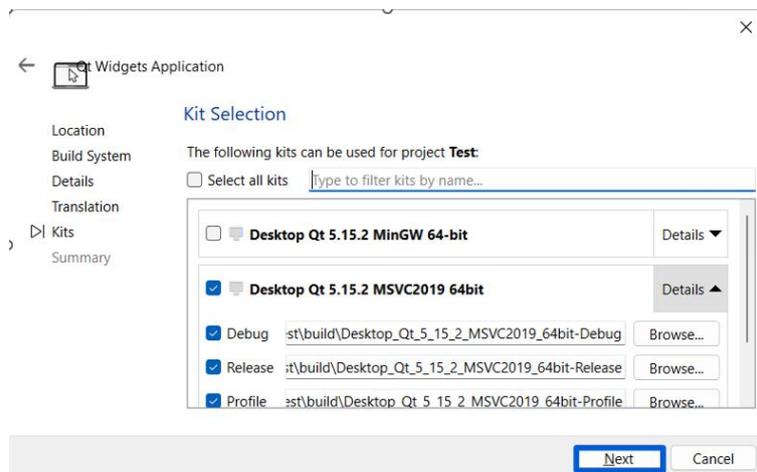


Figure 11 Select the build environment

7. Click "Finish" to create the project;
8. In the Qt Creator main interface, right-click the "Test" project, select "Add Library..." -> "External Library" -> "Next";
9. Click to browse the library file, select the htra\_api.lib library in "QtTest\htra\_api", and click "Open";
10. Uncheck all options under Windows, then click "Static Library", finally select the Windows platform, and click "Next";

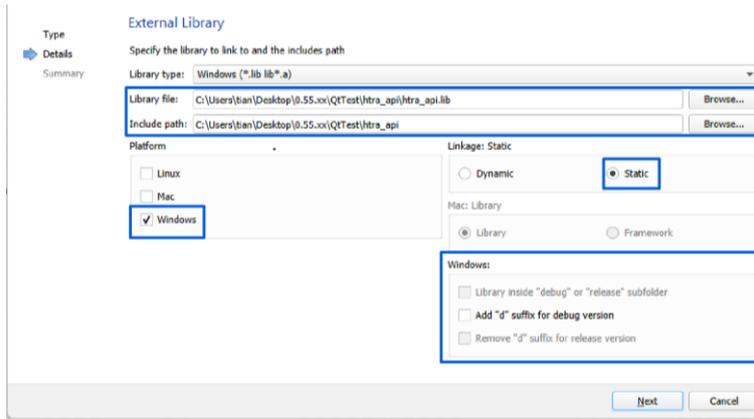


Figure 12 Set the build configuration

11. Click "Finish" to add the external library; Delete the last line `else:win32-g++:PRE_TARGETDEPS+=$$PWD/../../htra_api/libhtra_api.a` in the "test.pro" file. After saving, you can write project code normally;

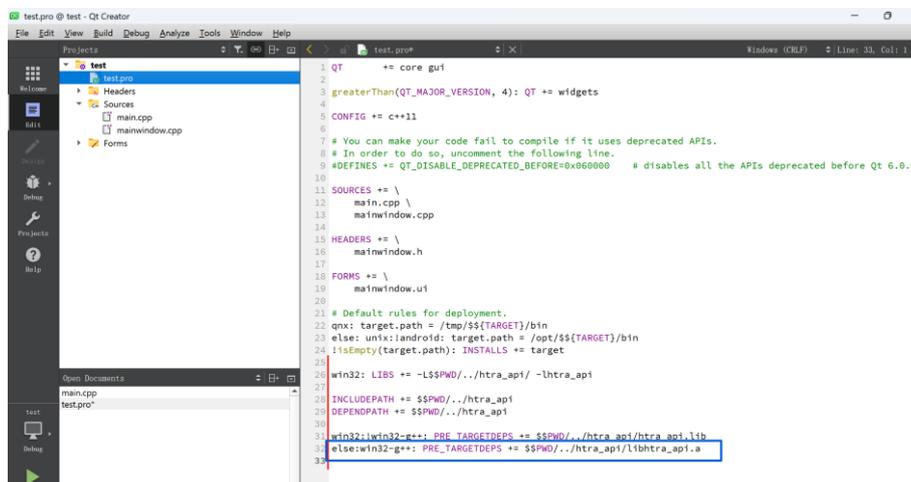


Figure 13 Modify the test.pro file

12. After writing the code, click "Run". The program running correctly is illustrated as follows.

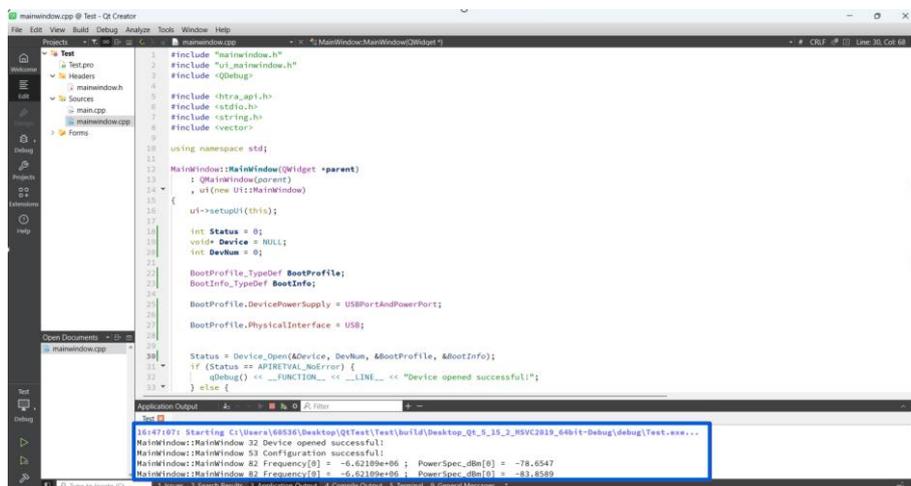


Figure 14 Result

## 2.2 Qt Example Usage Process

Note: Only one example can run at a time; the example and SASTudio4 cannot run simultaneously.

All Qt examples on the provided USB drive follow the same usage process. The following introduces the usage of the HTRA\_Qt\_Example project as an example:

1. Use Qt Creator to open the htrademopro file located in the Windows\HTRA\_API\_Example\HTRA\_Qt\_Examples\htrademopro folder on the USB drive;
2. Click "Projects" to configure a 64-bit build environment for the project (the provided example uses 64-bit library files. If you need to use a 32-bit build environment, replace the libraries in the "HTRA\_Qt\_Example\htra\_api" folder with the 32-bit libraries from "\Windows\HTRA\_API\x86");

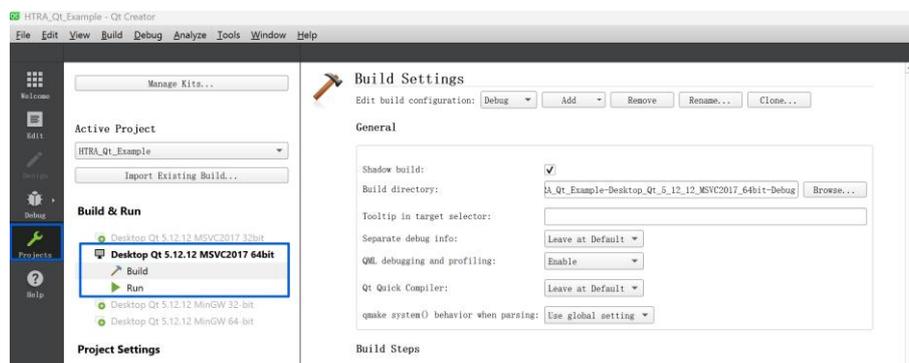


Figure 15 Configure a 64-bit build environment

3. After configuring the environment, click "Edit" to open main.cpp in the Sources folder of the "HTRA\_Qt\_Example" project. Uncomment the relevant functions, save the file, and click "Run" to execute different examples.

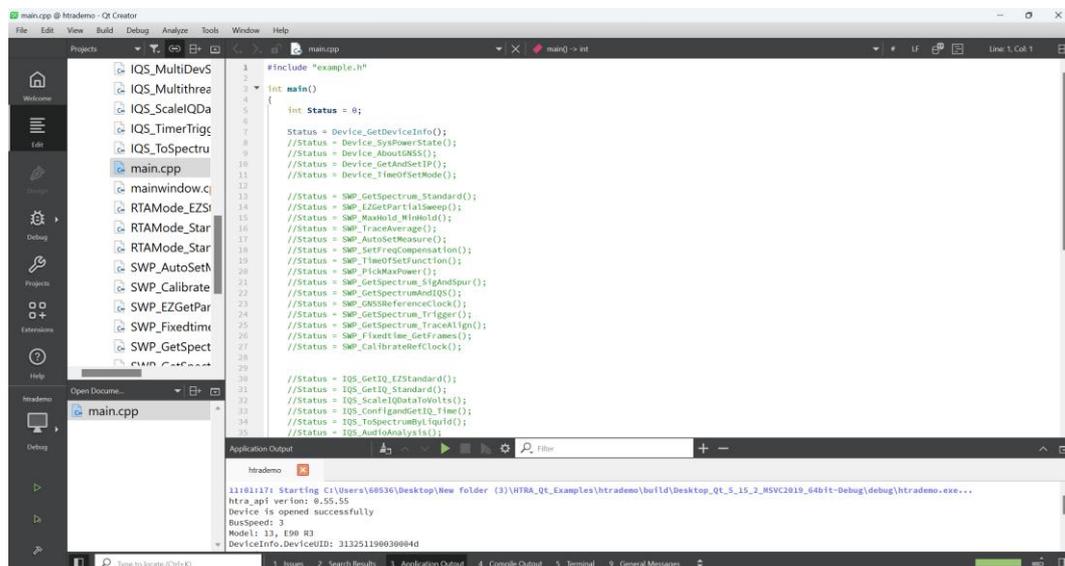


Figure 16 Running the QT Example

## 2.3 Qt Example Description

The Qt examples on the USB stick include a general example (HTRA\_Qt\_Example), an FM and AM demodulation example (HTRA\_Demodulation), and an IQ to Spectrum example (IQS\_ToSpectrumBuLiquid) using the Liquid library, refer to the C/C++ examples chapter for specific examples.

# 3. Python

## 3.1 Configure Development Environment

1. Create a new folder on the desktop (e.g., TEST);
2. Open the provided USB drive, go to "\\Windows\HTRA\_API\_Example\HTRA\_Python\_Examples", and copy the "HTRA\_API" folder and "htra\_api.py" file into the newly created test folder;
3. Open Visual Studio Code, click "File" → "Open Folder", and select the newly created test folder;
4. In the left Explorer panel, click the "New File" icon to create a new Python file (e.g., test.py), and you can start writing code normally.

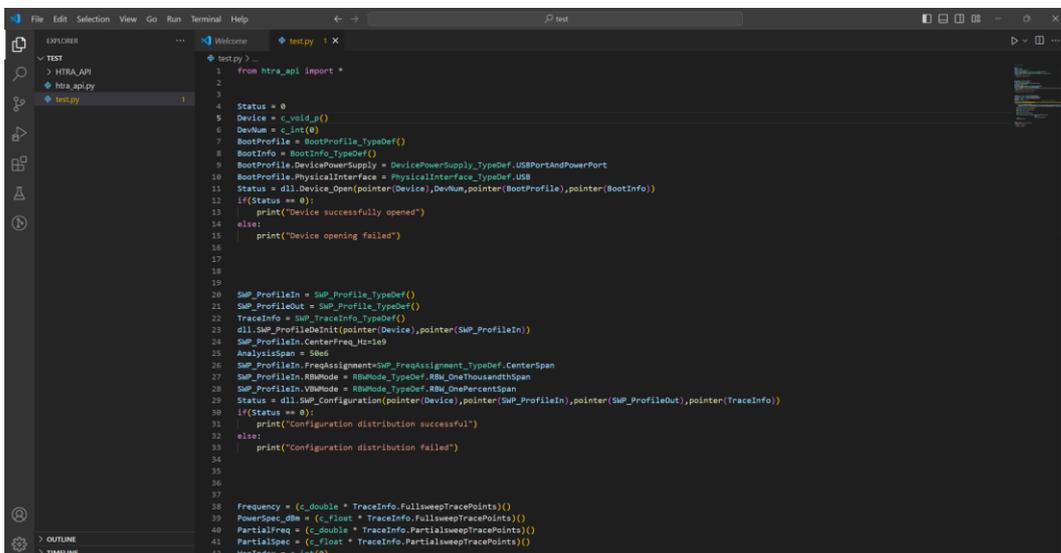


Figure 17 Creating a New Python Project

### 3.2 Python Example Usage Process

1. Open the "Windows\HTRA\_API\_Example\HTRA\_Python\_Examples" project folder on the provided USB drive using Visual Studio Code or another IDE. The "htra\_api.py" file is the Python mapping for the dynamic library, and the other files are example programs;
2. After properly configuring the Python environment, select any example program (e.g., SWPMode\_Standard.py) and run the file directly. The program running successfully is illustrated as follows:

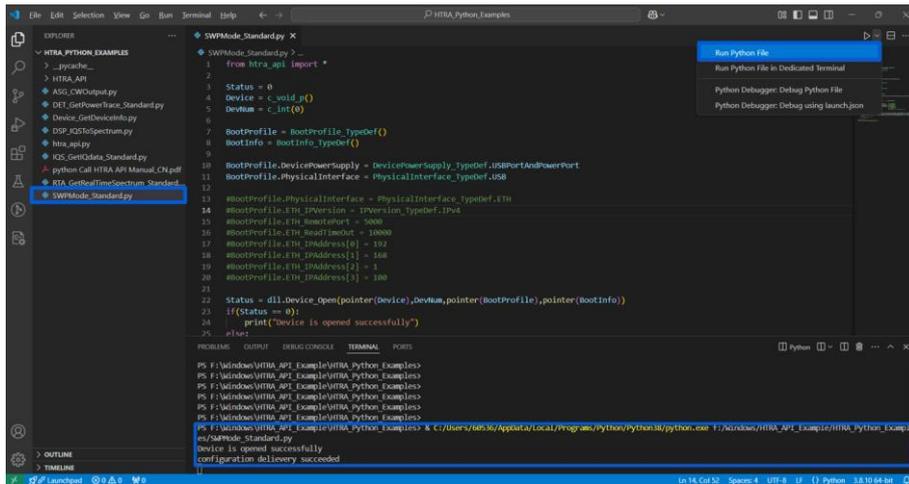


Figure 18 Running SWPMode\_Standard.py

### 3.3 Python Example Description

#### 3.3.1 Get device information

Device\_GetDeviceInfo.py: Retrieves various device information, including API version, USB version, device model, device UID, MCU version, FPGA version, and device temperature.

#### 3.3.2 Obtain Standard Spectrum Data

SWP\_GetSpectrum\_Standard.py: Obtains complete spectrum data within a specified frequency band(Plotting the spectrum if the host computer includes the matplotlib library).

#### 3.3.3 Obtain IQ Data for a Fixed Number of Points or Duration

IQS\_GetIQdata\_Standard.py: Obtains IQ data under different trigger modes in IQS mode.

#### 3.3.4 Obtain Power Detection Data for a Fixed Number of Points or Duration

DET\_GetPowerTrace\_Standard.py: Obtains power detection data under different trigger modes in DET mode(Plotting the Time-power graph if the host computer includes the matplotlib library).

#### 3.3.5 Obtain real-time spectrum data for a fixed number of points or duration

RTA\_GetRealTimeSpectrum\_Standard.py: Obtain real-time spectrum data under different trigger modes in RTA mode.

#### 3.3.6 IQ to Spectrum Data

DSP\_IQSToSpectrum.py: Convert the IQ data obtained in IQS mode into spectrum data(If the host computer contains the matplotlib library then plot the spectrum and IQ time-domain graphs).

#### 3.3.7 GNSS Related

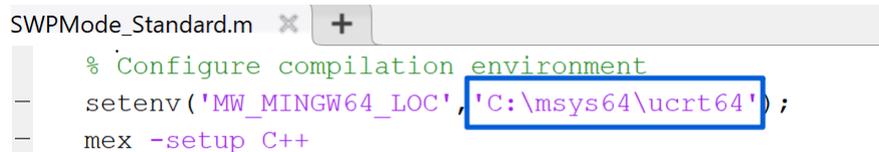
Device\_AboutGNSS.py: Obtain information such as longitude, latitude, altitude, and time acquired by the GNSS module; obtain the longitude, latitude, and time information from the MeasAuxInfo structure in IQS mode.

## 4. Matlab

The following uses Matlab 2016a as an example to demonstrate how to call the 64-bit htra\_api dynamic link library.

### 4.1 Running the Matlab Example

1. [Download and install a C++ compiler](#);
2. After properly connecting the device, open Matlab. Copy the current path of the "Windows\HTRA\_API\_Example\HTRA\_Matlab\_Examples" folder from the provided USB drive into Matlab's file path box and press Enter;
3. Click the SWPMode\_Standard.m file on the left, and confirm whether the compiler address in the first line of the example is consistent with the compiler path installed on the local system;



```
SWPMode_Standard.m x +
% Configure compilation environment
setenv('MW_MINGW64_LOC', 'C:\msys64\ucrt64');
mex -setup C++
```

Figure 19 Confirm the compiler address

4. Click "Run". The appearance of the Figure 1 window indicates successful execution of the example. For functional descriptions of each example, please refer to the [Introduction to Accompanying Examples](#) section in the accompanying materials.

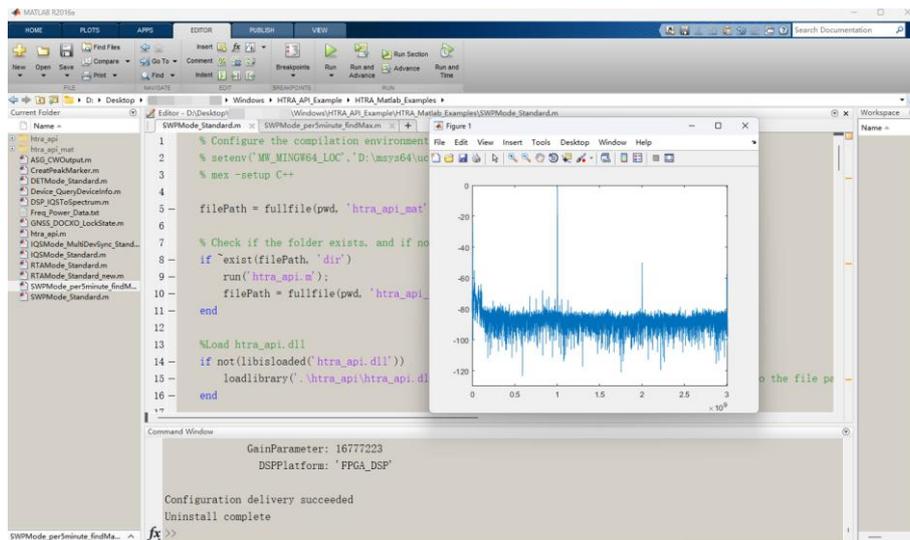


Figure 20 Run the SWPMode\_Standard.m File

Note: Since calling the dynamic link library requires a C++ compiler, it is recommended to use MSYS2 to install the g++ compiler. Refer to <https://www.msys2.org/> for download and installation instructions.

## 4.2 Introduction to Accompanying Examples

### 4.2.1 Get device information

Device\_QueryDeviceInfo.m: Retrieve device information, including API version, USB version, device model, device UID, MCU version, FPGA version, and device temperature.

### 4.2.2 Obtain Standard Spectrum Data

SWPMode\_Standard.m: Obtain complete spectrum data within the specified frequency band.

### 4.2.3 Create multiple markers to display frequency and power of the markers

CreatPeakMarker.m: Obtain spectrum data within the specified frequency band, create markers, and perform peak searching.

### 4.2.4 Collect the peak spectrum every five minutes

SWPMode\_per5minute\_findMax.m: Obtain spectrum data within the specified frequency band and search for the peak globally every five minutes.

### 4.2.5 Obtain continuous stream or fixed number of IQ data

IQSMode\_Standard.m: Acquire IQ data under different trigger modes in IQS mode.

### 4.2.6 The acquired IQ data is converted into spectrum data

DSP\_IQSToSpectrum.m: After acquiring IQ data, the obtained IQ data is converted into spectrum data.

### 4.2.7 Acquire continuous stream or fixed number of power detection data

DET\_GetPowerTrace\_FixedPoints.m: Acquire power detection data under different triggering modes in DET mode.

### 4.2.8 Acquire continuous stream or fixed duration real-time spectrum data

RTAMode\_FixedPoints.m: Acquire real-time spectrum data under different triggering modes in RTA mode.

### 4.2.9 Internal signal source output signal

ASG\_CWOutput.m: Output single-tone signals, frequency sweep signals, and power sweep signals. Applicable only to devices with signal source options.

### 4.2.10 Lock GNSS antenna and DOCXO oscillator

GNSS\_DOCXO\_LockState.m: Call the API interface to lock the GNSS antenna and DOCXO oscillator, applicable only to devices with IO expansion board options.

#### 4.2.11 Multi-machine synchronization

IQSMODE\_MultiDevSync\_Standard.m: When using the same reference clock source input and the same trigger source input, two devices simultaneously acquire IQ data, allowing for the observation of the synchronization of their collected data.

## 5. C#

### 5.1 Configure Development Environment

#### 5.1.1 Development Environment Confirmation

Open the Visual Studio Installer, select the .NET Desktop Development and Universal Windows Platform Development components, then click Modify to ensure that Visual Studio 2019 includes the C# development environment.

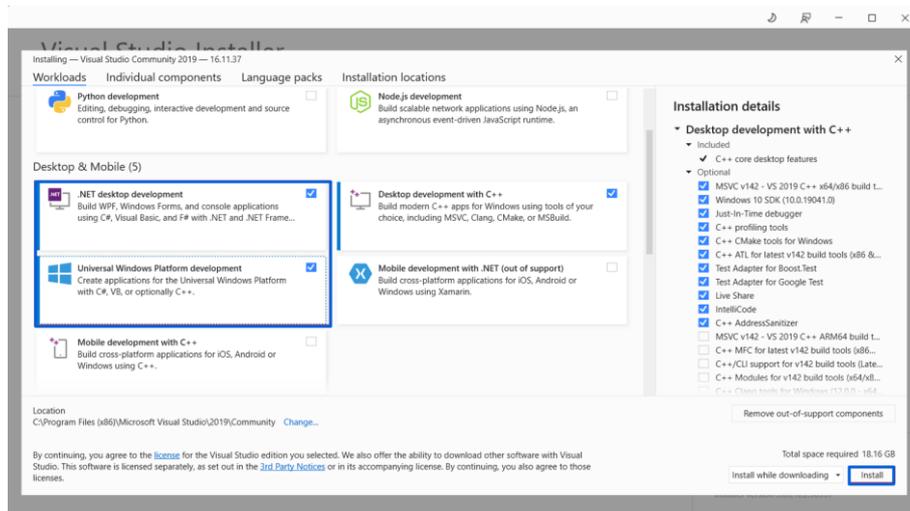


Figure 21 Configuring the C# Development Environment in Visual Studio

#### 5.1.2 Project Setup

1. Open Visual Studio 2019 and click "Create a new project";
2. Select "C# Console Application" and click "Next";
3. Enter the project name and location, uncheck "Place solution and project in the same directory." Select ".NET Framework 4.5" as the framework, and then click "Create";
4. After the project is created, open the project, right-click the solution, and select "Add New Project";
5. In the "Add New Project" dialog, select "Library" as the project type, then choose "Class Library (Universal Windows)" under C#, and click "Next";

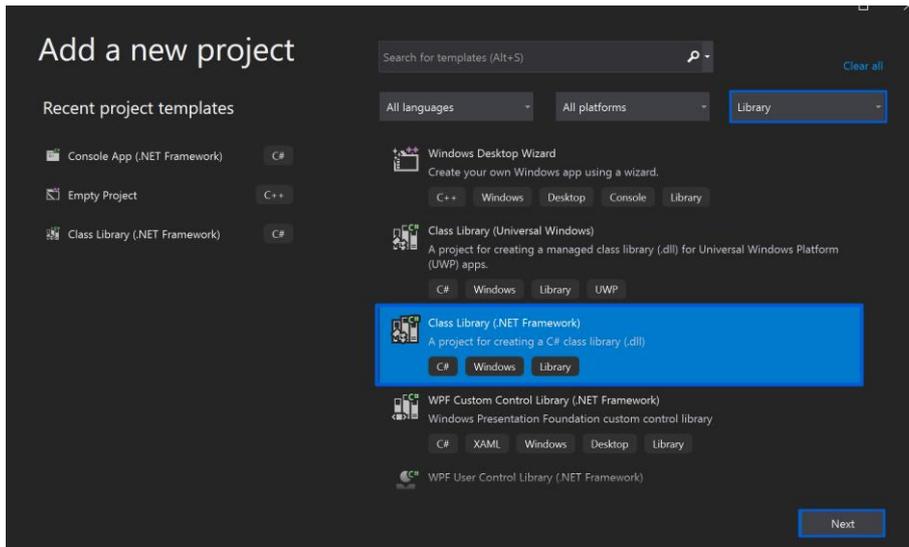


Figure 22 Add New Project

6. Modify the project name as needed (e.g., HtraApi), keep the default location, select ".NET Framework 4.5" as the framework, and click "Create";
7. Right-click ConsoleApp1 and select "Properties". In the project properties window, click the "Build" tab and change the "Platform target" to "x86". Then click the "Debug" tab, enter "htra\_api" in the "Working directory" field, click "OK" in the popup, and finally save and close the properties window;

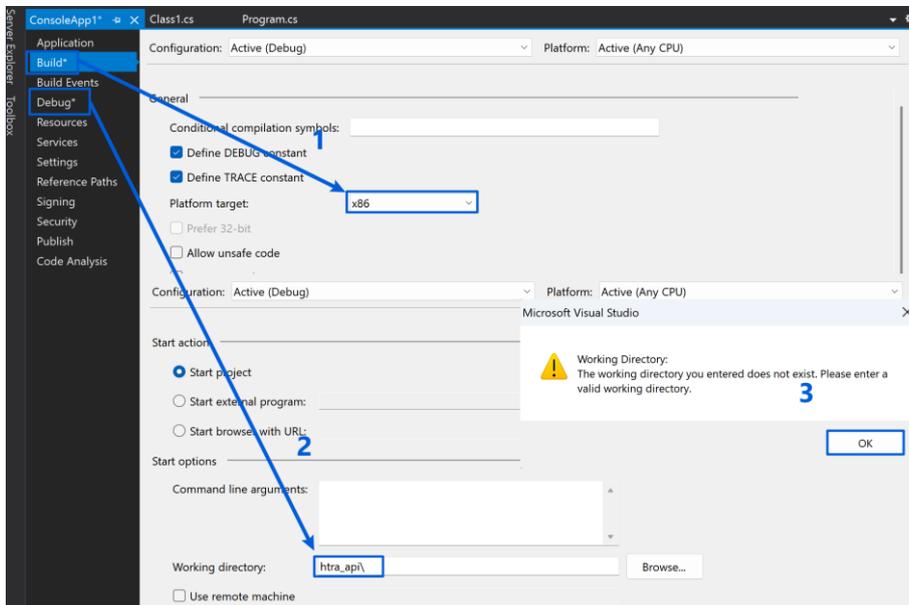


Figure 23 Configure Project Properties

8. Right-click the library HtraApi and select "Properties". In the library properties window, click the "Build" tab, change the "Platform target" to "x86," and save;
9. Copy the contents of the HtraApi.cs file from the "\\Windows\HTRA\_API\_Example\HTRA\_CSharp\_Examples" folder on the provided USB drive into the Class1.cs file in the project library, replace the code, and save;

10. Select the ConsoleApp1 project, right-click "References," choose "Add Reference," check the HtraApi library in the project, click "OK," and confirm that the library reference has been added;

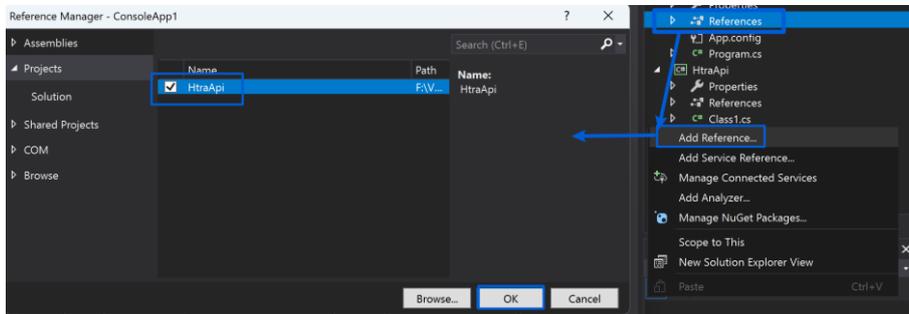


Figure 24 Add Library Reference

11. Copy the htra\_api folder from the "\\Windows\HTRA\_API\x86" directory on the provided USB drive to the "bin\Debug" folder of the project, and ensure that the "Htra\_api\CalFile" folder contains the calibration files for the instruments being used;

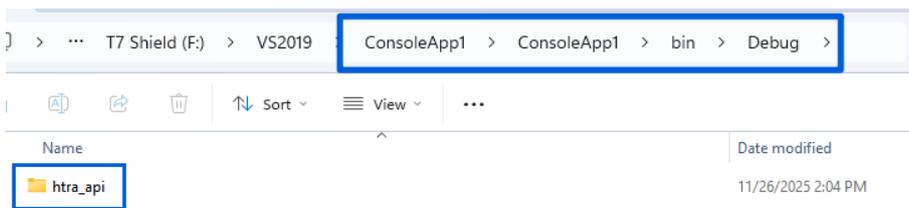


Figure 25 Copy the htra\_api file

12. You can refer to the C# examples on the provided USB drive and write code as needed;

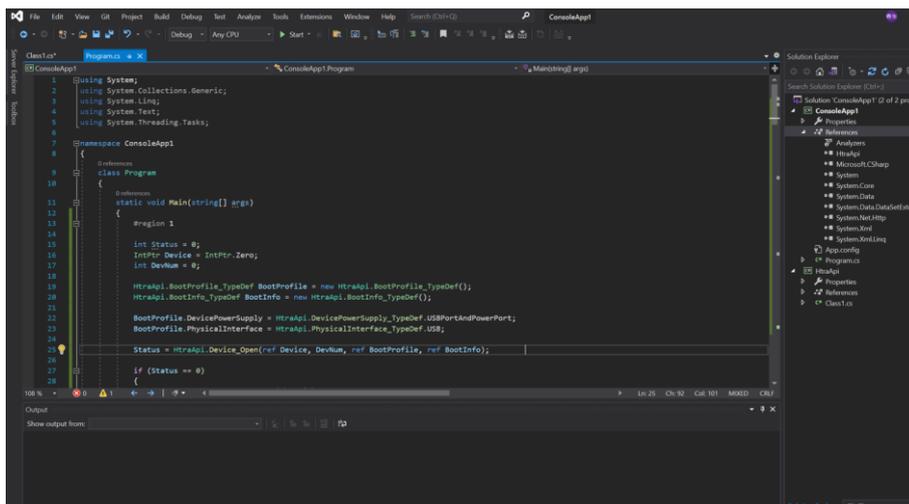


Figure 26 Write C# example

## 5.2 C# Example Usage Process

1. Open the solution HTRA\_CSharp\_Examples.sln in Visual Studio from the "\\Windows\HTRA\_API\_Example\HTRA\_CSharp\_Examples" folder on the provided USB drive;
2. Click the HTRA\_CSharp\_Examples project on the right, then open the Program.cs file within it;

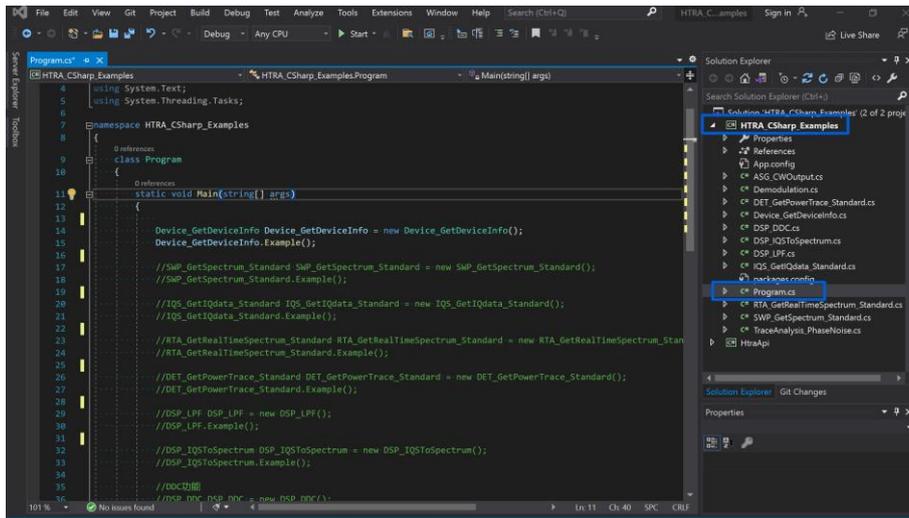


Figure 27 Open the Programme.cs file

3. Each routine in the provided C# examples is encapsulated in a separate class. To use a routine, simply uncomment it (multiple examples cannot be used simultaneously).  
For example, to use the Device\_GetDeviceInfo routine, uncomment it and run the program.  
A successful run is illustrated as follows;

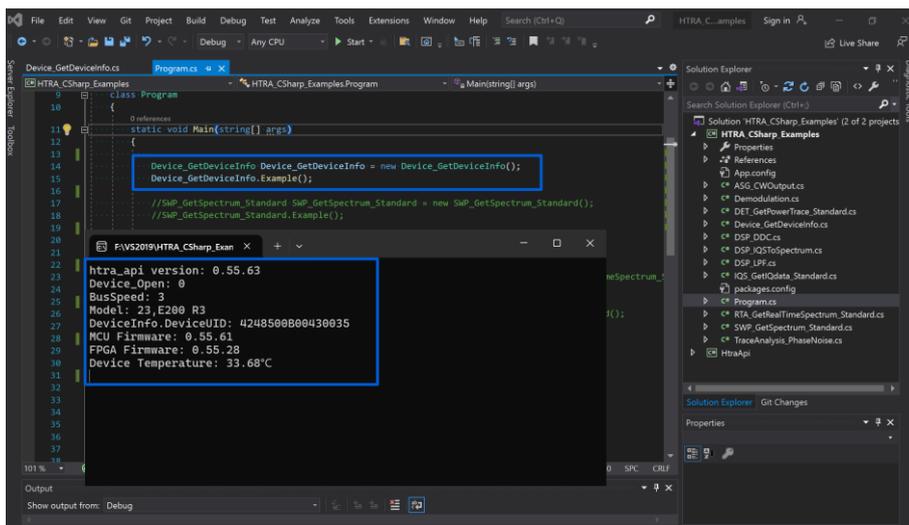


Figure 28 Run Device\_GetDeviceInfo.cs

## 5.3 C# Example Descriptions

### 5.3.1 Get device information

Device\_GetDeviceInfo.cs: Retrieves device information including API version, USB version, device model, device UID, MCU version, FPGA version, and device temperature.

### 5.3.2 Obtain Standard Spectrum Data

SWP\_GetSpectrum\_Standard.cs: Obtains complete spectrum data within a specified frequency band.

### 5.3.3 Obtain IQ Data for a Fixed Number of Points or Duration

IQS\_GetIQdata\_Standard.cs: Acquires IQ data under different trigger modes in IQS mode.

### 5.3.4 Obtain Power Detection Data for a Fixed Number of Points or Duration

DET\_GetPowerTrace\_Standard.cs: Obtains power detection data under different trigger modes in DET mode.

### 5.3.5 Obtain real-time spectrum data for a fixed number of points or duration

RTA\_GetRealTimeSpectrum\_Standard.cs: Retrieves real-time spectrum data under different trigger modes in RTA mode.

### 5.3.6 Output single-tone signal

ASG\_CWOutput.cs: Devices with signal source functionality options output single-tone signals, frequency sweep signals, or power sweep signals through ASG functionality.

### 5.3.7 AM/FM Demodulation

Demodulation.cs: DSP\_FMDemod performs FM demodulation and playback of the acquired IQ data. DSP\_AMDemod performs AM demodulation and playback of the acquired IQ data.

### 5.3.8 IQ to Spectrum Data

DSP\_IQSToSpectrum.cs: Converts the IQ data obtained in IQS mode into spectrum data.

### 5.3.9 Low-pass filtering

DSP\_LPF.cs: Applies low-pass filtering to the acquired IQ data and converts it to spectrum.

### 5.3.10 Digital Downconversion

DSP\_DDC.cs: Performs digital down-conversion on the acquired IQ data and converts it to spectrum.

### 5.3.11 Phase noise test

DSP\_TraceAnalysis\_PhaseNoise.cs: Demonstration of Phase Noise Test Function.

# 6. Labview

## 6.1 Configure Development Environment

### 6.1.1 Using the API in the LabVIEW Environment

1. Open LabVIEW, click "Create Project", select "Project", and click "Finish". An untitled empty project will appear. Press "Ctrl+S" to save the project, choose the save path, enter a project name (e.g., HTRA\_Labview\_Examples), and click "OK";
2. Copy the "htra\_api" folder from the "\\Windows\HTRA\_API\_Example\HTRA\_Labview\_Examples" directory on the USB drive to the same directory level as the project. Additionally, you may create an "Examples" folder to store example VIs. If needed, you can also create another folder such as "Subvi" to store sub-VIs;

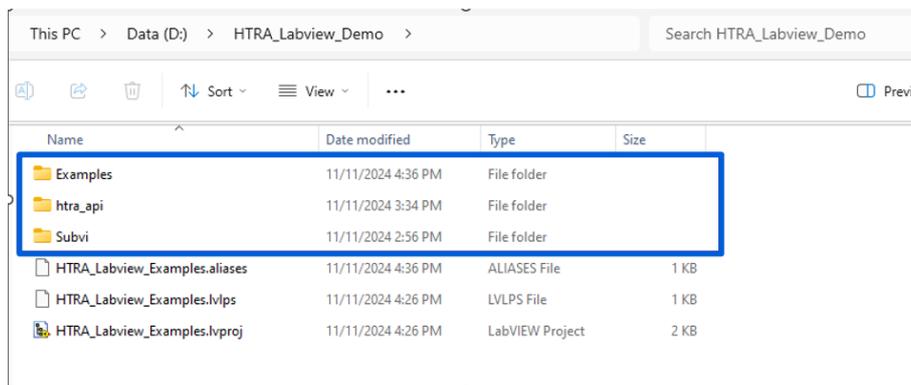


Figure 29 Copy htra\_api

3. In the LabVIEW project, add the newly created Examples folder and the htra\_api folder to the project, then save it;

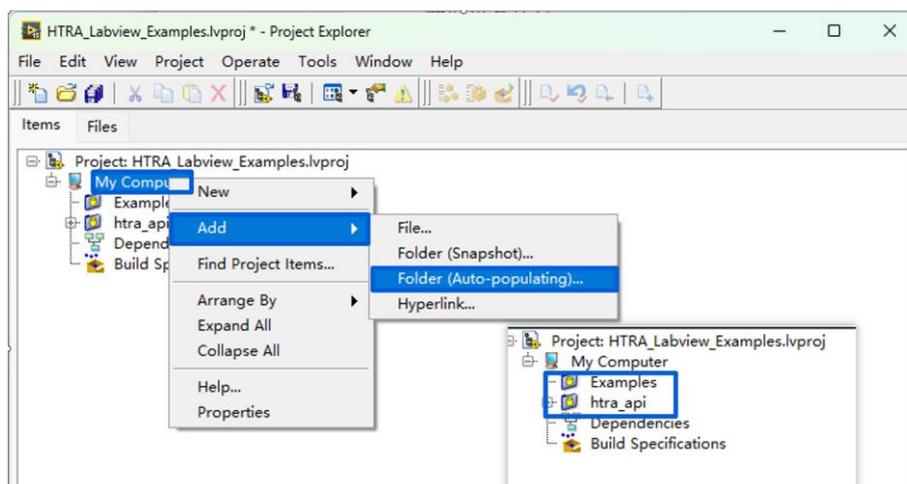


Figure 30 Add to project

4. Create a new VI in the Examples folder. In the block diagram, you can call the exported

LabVIEW API functions. The calling process is the same as in the C environment;

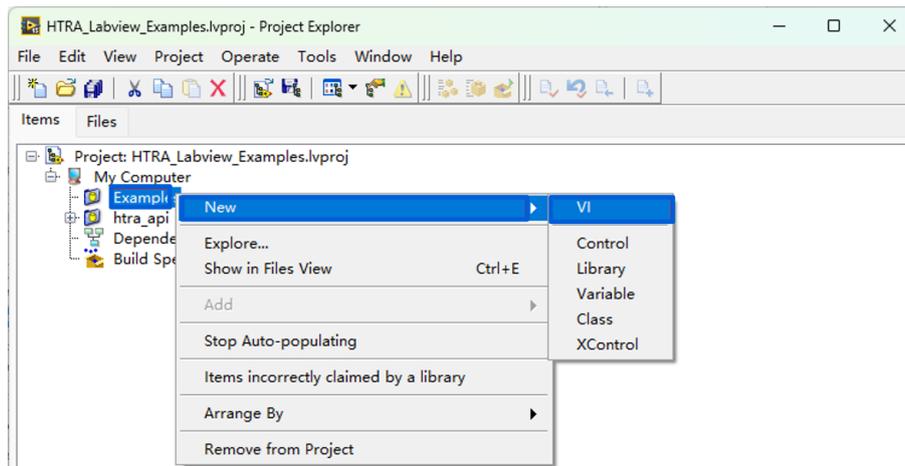


Figure 31 Create VI

5. Finally, save the VI to the Examples folder and rename it as needed.

## 6.2 Labview Example Usage Process

The usage process of Labview examples included in the USB drive is as follows:

1. Use LabVIEW to open the project "HTRA\_Labview\_Examples.lvproj" located in the USB drive under Windows\HTRA\_API\_Example\HTRA\_Labview\_Examples;

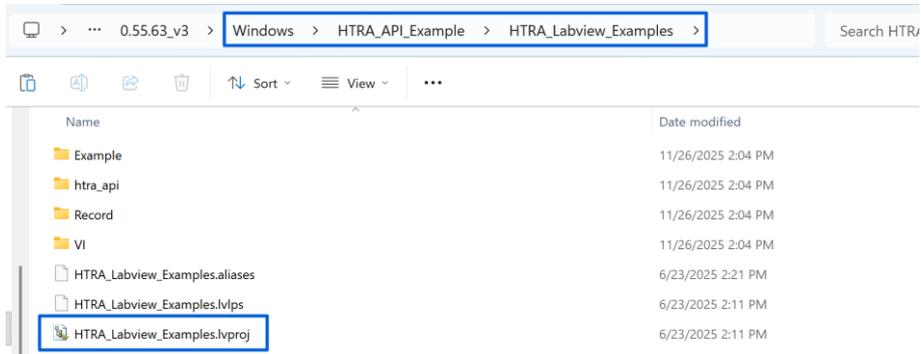


Figure 32 Open Labview Project

2. Double-click any example VI in the Example folder. Here, SWP\_GetSpectrum\_Standard.vi is used as an example;

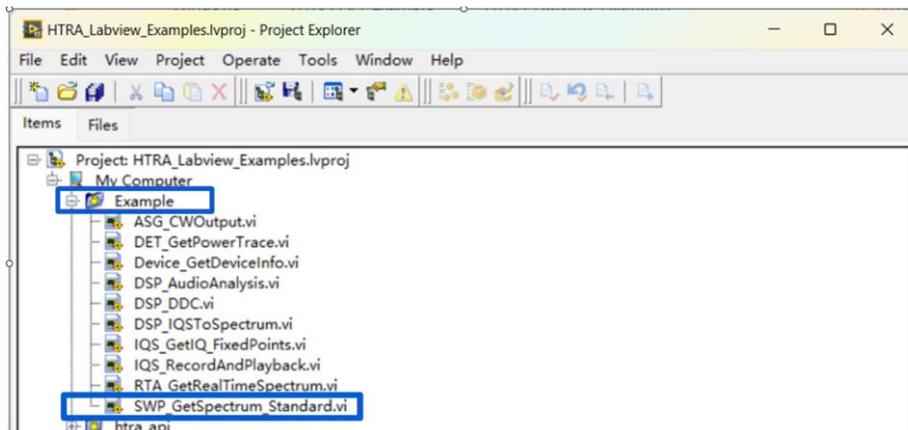


Figure 33 Open example

3. After opening the VI, click the Run button in the upper-left corner to execute the program. The running interface is shown below;

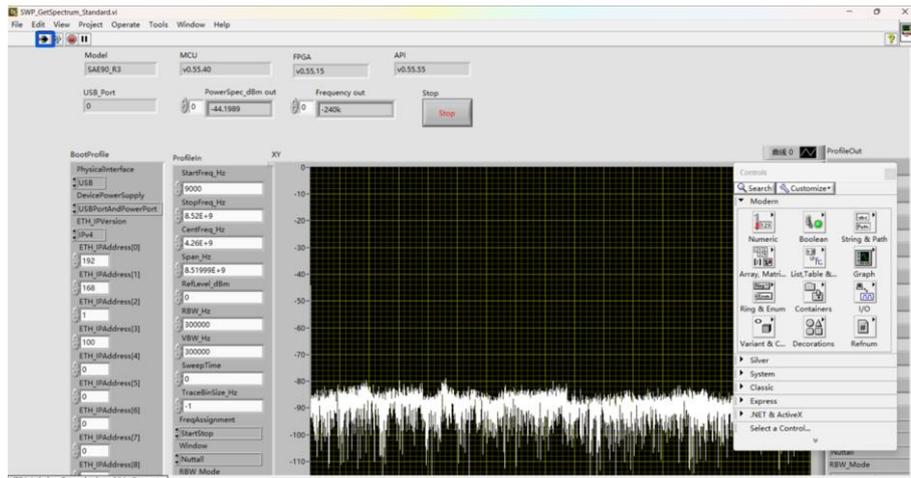


Figure 34 Successfully Run the SWP\_GetSpectrum\_Standard Example

## 6.3 Labview Example Description

### 6.3.1 Get device information

Device\_GetDeviceInfo.vi: An example for obtaining various device information, including: API version, device model, device UID, MCU version, FPGA version, and device temperature.

### 6.3.2 Standard spectrum acquisition

SWP\_GetSpectrum\_Standard.vi: Obtains standard spectrum data within a specified frequency band and displays the image.

### 6.3.3 Obtain IQ Data for a Fixed Number of Points or Duration

IQS\_GetIQ\_FixedPoints.vi: Obtains IQ data with a fixed number of points. When the device receives a Bus trigger signal, it returns IQ data with a fixed number of points.

### 6.3.4 Streaming and reading IQ data

IQS\_RecordAndPlayback.vi: Obtains IQ data, records the IQ data as a txt file, and plays back the recorded IQ data.

### 6.3.5 IQ to Spectrum Data

DSP\_IQSToSpectrum.vi: Obtains IQ data and converts the acquired IQ data into spectrum data.

### 6.3.6 Digital Downconversion

DSP\_DDC.vi: Performs digital downconversion on the IQ data stream and resamples to generate a sub-IQ stream for further spectrum analysis.

### 6.3.7 Audio Analysis

DSP\_AudioAnalysis.vi: Analyzes audio voltage (V), audio frequency (Hz), signal-to-noise ratio (dB), and total harmonic distortion (%).

### 6.3.8 Obtain Power Detection Data for a Fixed Number of Points or Duration

DET\_GetPowerTrace.vi: Obtain a fixed number of DET data points. When the device receives a Bus trigger signal, it returns a fixed number of DET data points.

### 6.3.9 Obtain real-time spectrum data for a fixed number of points or duration

RTA\_GetRealTimeSpectrum.vi: Obtain a fixed number of RTA data points. When the device receives a Bus trigger signal, it returns a fixed number of RTA data points.

### 6.3.10 ASG Signal Source Output Signal

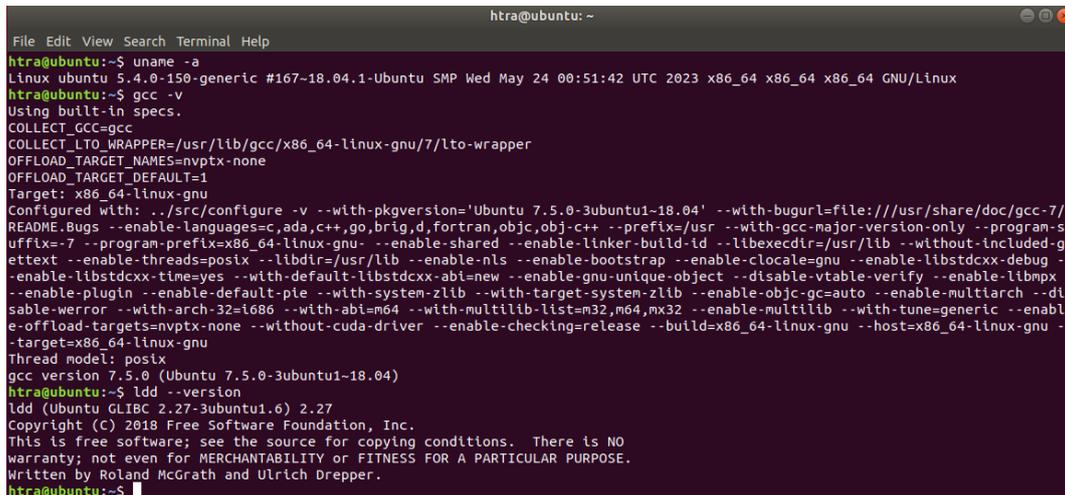
ASG\_CWOutput.vi: Control the internal signal generator of the device to output single-tone signals, sweep signals, and power scan signals.

# 7. Linux

## 7.1 Environment Version Compatibility Self-Check

When using the device in a Linux system, you first need to confirm whether the current Linux environment's system architecture, gcc version, and GLIBC version are supported according to the following process:

1. Open the terminal and enter `uname -a` to check the Linux system architecture, for example, here the Linux system architecture is `x86_64`;
2. In the terminal, enter `gcc -v` to check the system gcc version, for example, here the gcc version is `7.5.0`;
3. In the terminal, enter `ldd --version` to check the system GLIBC version, for example, here the GLIBC version is `2.27`;



```
htra@ubuntu: ~  
File Edit View Search Terminal Help  
htra@ubuntu:~$ uname -a  
Linux ubuntu 5.4.0-150-generic #167-18.04.1-Ubuntu SMP Wed May 24 00:51:42 UTC 2023 x86_64 x86_64 x86_64 GNU/Linux  
htra@ubuntu:~$ gcc -v  
Using built-in specs.  
COLLECT_CCC=gcc  
COLLECT_LTO_WRAPPER=/usr/lib/gcc/x86_64-linux-gnu/7/lto-wrapper  
OFFLOAD_TARGET_NAMES=nvptx-none  
OFFLOAD_TARGET_DEFAULT=1  
Target: x86_64-linux-gnu  
Configured with: ../src/configure -v --with-pkgversion='Ubuntu 7.5.0-3ubuntu1-18.04' --with-bugurl=file:///usr/share/doc/gcc-7/README.Bugs --enable-languages=c,ada,c++,go,brig,d,fortran,objc,obj-c++ --prefix=/usr --with-gcc-major-version-only --program-suffix=-7 --program-prefix=x86_64-linux-gnu- --enable-shared --enable-linker-build-id --libexecdir=/usr/lib --without-included-g  
ettext --enable-threads=posix --libdir=/usr/lib --enable-nls --enable-bootstrap --enable-clocale=gnu --enable-libstdcxx-debug -  
-enable-libstdcxx-time=yes --with-default-libstdcxx-abi=new --enable-gnu-unique-object --disable-vtable-verify --enable-libmpx  
--enable-plugin --enable-default-pie --with-system-zlib --with-target-system-zlib --enable-objc-gc=auto --enable-multitarch --di  
sable-werror --with-arch-32=i686 --with-abi=m64 --with-multilib-list=m32,m64,mx32 --enable-multilib --with-tune=generic --enabl  
e-offload-targets=nvptx-none --without-cuda-driver --enable-checking=release --build=x86_64-linux-gnu --host=x86_64-linux-gnu -  
-target=x86_64-linux-gnu  
Thread model: posix  
gcc version 7.5.0 (Ubuntu 7.5.0-3ubuntu1-18.04)  
htra@ubuntu:~$ ldd --version  
ldd (Ubuntu GLIBC 2.27-3ubuntu1.6) 2.27  
Copyright (C) 2018 Free Software Foundation, Inc.  
This is free software; see the source for copying conditions. There is NO  
warranty; not even for MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.  
Written by Roland McGrath and Ulrich Drepper.  
htra@ubuntu:~$
```

Figure 35 Check the Linux System Architecture and Version

4. Compare the terminal information with the table to confirm whether the current environment is supported. If it is not supported, please contact technical support.

Table 1 Terminal Information Comparison Table

|                                |  |
|--------------------------------|--|
| <b>x86 processor</b>           | Support Intel and AMD processors   |
| <b>ARM processor</b>           | aarch64 (armv8), armv7 processors, such as: Raspberry Pi 4b, RK3399, RK3568, RK3588, T507, NVIDIA Jetson TX2 |
| <b>Compilation environment</b> | gcc4.8, glib2.17 and above   |
| <b>Distribution</b>            | Customized system for Raspberry Pi 4b, Ubuntu 18.04, etc.  |

## 7.2 Accompanying documentation

Currently, the Linux section of the accompanying USB drive contains the following materials:

### 7.2.1 HTRA\_C++\_Examples

The HTRA\_C++\_Examples folder contains:

1. Examples folder: C++ example programs (see the [C++ Example Usage](#) section for instructions);
2. Makefile: Build script used to compile the example programs into executables;
3. bin folder: Stores device calibration files and the executables generated from building the example programs.

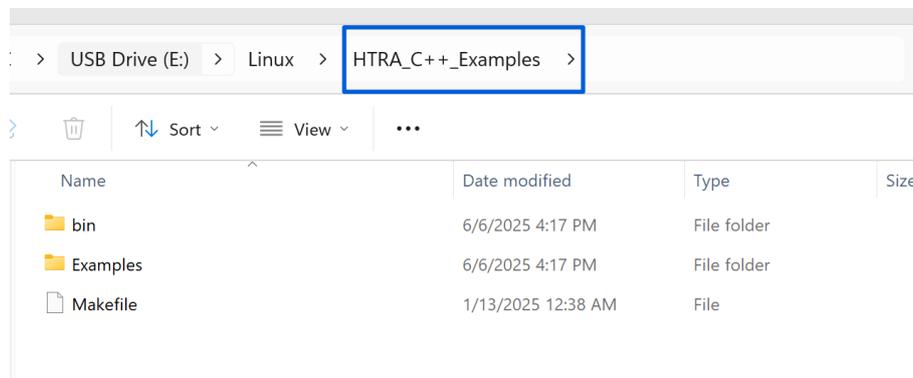


Figure 36 Contents of the HTRA\_C++\_Examples Folder on Linux

### 7.2.2 HTRA\_Qt\_Examples

The HTRA\_Qt\_Examples folder contains:

1. htrademo folder: Qt examples and .pro files (see the [Qt Example Usage](#) section for instructions);
2. bin folder: Stores device calibration files and executables generated from compiling the example programs;
3. htraapi folder: Stores the dynamic link libraries.

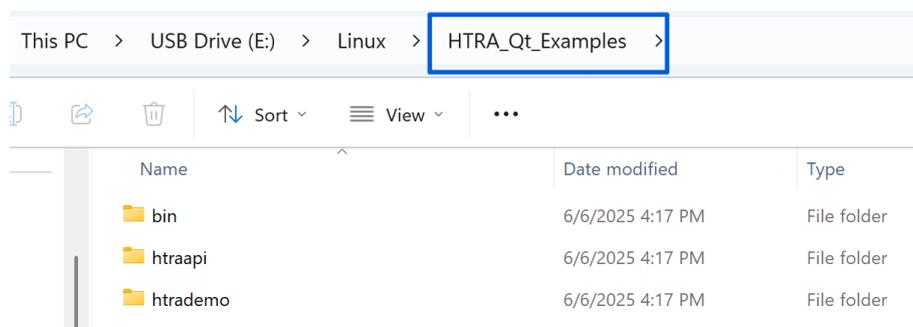


Figure 37 Contents of the HTRA\_Qt\_Examples Folder on Linux

### 7.2.3 HTRA\_Python\_Examples

The HTRA\_Python\_Examples folder specifically contains:

1. Python example programs (see the [Python Example Usage](#) section for instructions);
2. CalFile folder: Stores device calibration files;
3. Htraapi folder: Stores the dynamic link libraries.

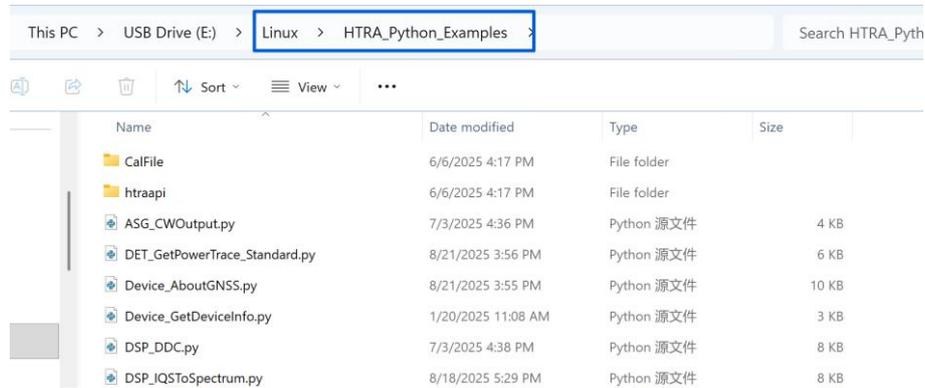


Figure 38 Contents of the HTRA\_Python\_Examples folder in Linux

### 7.2.4 Install\_HTRA\_SDK

1. The Install\_HTRA\_SDK folder contains:
  - install\_htraapi\_lib.sh: Driver configuration script
  - htraapi folder: Stores drivers, header files, and libraries
2. The Install\_HTRA\_SDK/htraapi folder contains:
  - configs folder: Driver configuration files
  - inc folder: Header files
  - lib folder: Dynamic link libraries
3. The Install\_HTRA\_SDK/htraapi/lib folder contains:
  - arrch64 folder: Dynamic link libraries for the arrch64 architecture
  - arrch64\_gcc7.5 folder: Dynamic link libraries for arrch64 with more efficient FFT (requires GCC version above 7.5)
  - x86\_64 folder: Dynamic link libraries for the x86\_64 architecture
  - x86\_64\_gcc5.4 folder: Dynamic link libraries for x86\_64 with more efficient FFT (requires GCC version above 5.4)
  - armv7 folder: Dynamic link libraries for the armv7 architecture

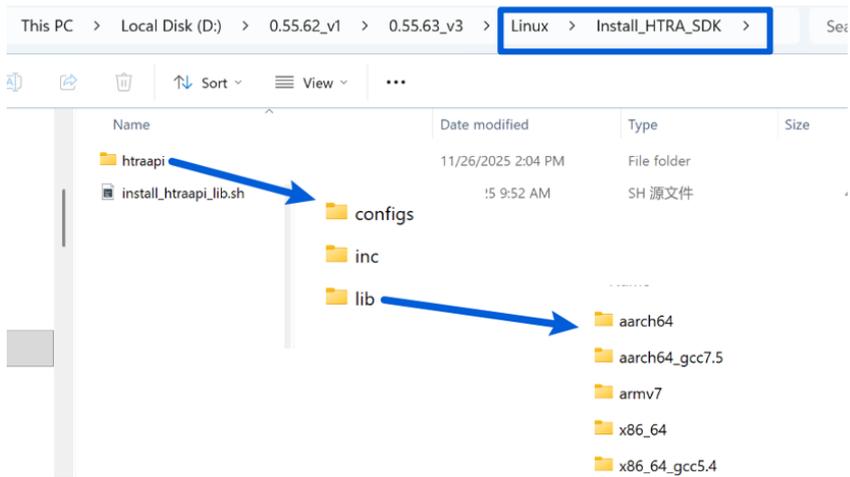


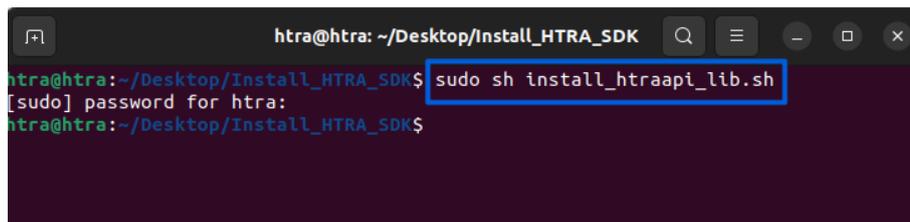
Figure 39 Contents of the Install\_HTRA\_SDK Folder on Linux

### 7.3 Driver File Configuration

To use the device in Linux, the driver files must be configured first. The specific procedure is as follows:

1. Configure the driver files: First, copy the Install\_HTRA\_SDK folder to the Linux host. Then, open a terminal in the Install\_HTRA\_SDK folder and enter `sudo sh install_htraapi_lib.sh` to configure the driver files.

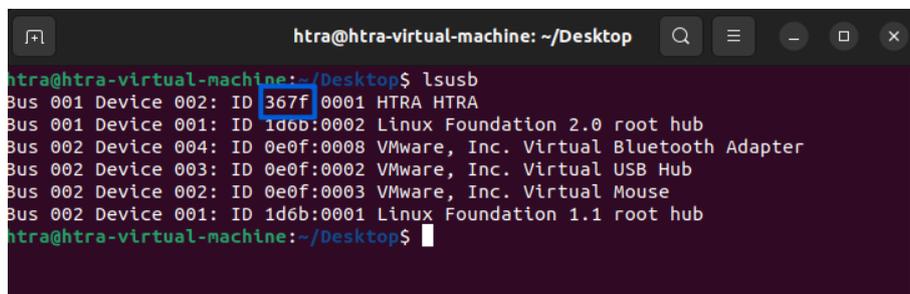
Note: If the development board does not have the `sudo` command, simply enter `sh install_htraapi_lib.sh`.



```
htra@htra: ~/Desktop/Install_HTRA_SDK
htra@htra:~/Desktop/Install_HTRA_SDK$ sudo sh install_htraapi_lib.sh
[sudo] password for htra:
htra@htra:~/Desktop/Install_HTRA_SDK$
```

Figure 40 Configure driver files on Linux

2. Configuration check: Ensure the device is correctly connected to the host computer (if the host computer is a virtual machine, ensure the device is connected to the virtual machine and that USB compatibility is 3.1) and provide normal power to the device. At this point, as shown in the figure, enter `lsusb` in the terminal to view the list of USB devices on the machine, where "ID: 6430 (or ID: 3675 or ID: 04b5)" indicates successful device connection.



```
htra@htra-virtual-machine: ~/Desktop
htra@htra-virtual-machine:~/Desktop$ lsusb
Bus 001 Device 002: ID 367f:0001 HTRA HTRA
Bus 001 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub
Bus 002 Device 004: ID 0e0f:0008 VMware, Inc. Virtual Bluetooth Adapter
Bus 002 Device 003: ID 0e0f:0002 VMware, Inc. Virtual USB Hub
Bus 002 Device 002: ID 0e0f:0003 VMware, Inc. Virtual Mouse
Bus 002 Device 001: ID 1d6b:0001 Linux Foundation 1.1 root hub
htra@htra-virtual-machine:~/Desktop$
```

Figure 41 Check device connection status on Linux

### 7.4 C++ Example Usage and Project Creation

#### 7.4.1 C++ Example Usage

Prerequisite: Ensure the device is properly connected and the driver files have been correctly configured as described in the [Driver File Configuration](#) section.

You can follow the process below and use the C++ examples provided on the USB drive (the specific functions of the examples can be found in the corresponding [C/C++ sections](#)).

1. Select the program to compile: First, copy the "Linux\HTRA\_C++\_Examples" folder from the provided USB drive to the host computer. Then, open main.cpp in the Examples folder and uncomment the examples you want to test or use;

```

1 #include "example.h"
2
3 int main()
4 {
5     int Status = 0;
6
7     //Status = Device_GetDeviceInfo();
8     //Status = Device_SysPowerState();
9
10    Status = SWP_GetSpectrum_Standard();
11    //Status = SWP_EzGetPartStatsweep();
12    //Status = SWP_MaxHold_MinHold();

```

Figure 42 Uncomment the SWP\_GetSpectrum\_Standard Example

2. Compile the selected example: First, check the system architecture according to the [Environment Version Compatibility Self-Check](#) section. Open a terminal in the HTRA\_C++\_Examples folder and enter the corresponding command based on the host system architecture (the following example shows how to compile the SWP\_GetSpectrum\_Standard routine).

- For x86\_64 system:  
*make Example=SWP\_GetSpectrum\_Standard*
- For aarch64 system:  
*make TARG=aarch64 Example=SWP\_GetSpectrum\_Standard*
- For armv7 system:  
*make TARG=armv7 Example=SWP\_GetSpectrum\_Standard*

```

htra@htra: ~/Desktop/HTRA_C++_Examples
htra@htra:~/Desktop/HTRA_C++_Examples$ make Example=SWP_GetSpectrum_Standard
g++ -o bin/SWP_GetSpectrum_Standard Examples/SWP_GetSpectrum_Standard.cpp Exampl
es/main.cpp Examples/Error_handling.cpp -std=c++11 -I/opt/htraapi/inc -L/opt/htr
aapi/lib/x86_64 -lhtraapi -Wl,-rpath='/opt/htraapi/lib/x86_64'
/usr/bin/ld: /tmp/cc5FkTxU.o: in function `main':
main.cpp:(.text+0x14): undefined reference to `Device_GetDeviceInfo'
collect2: error: ld returned 1 exit status
make: *** [Makefile:18: release] Error 1
htra@htra:~/Desktop/HTRA_C++_Examples$

```

Figure 43 Compile SWP\_GetSpectrum\_Standard on x86\_64 System

3. Verify the calibration files: Go to the "HTRA\_C++\_Examples\bin\CalFile" folder and ensure it contains the calibration files for the devices being used;

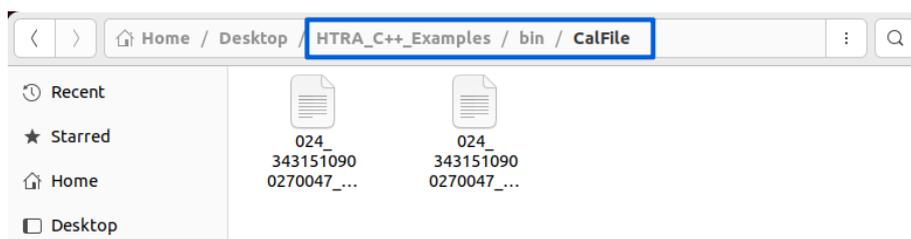
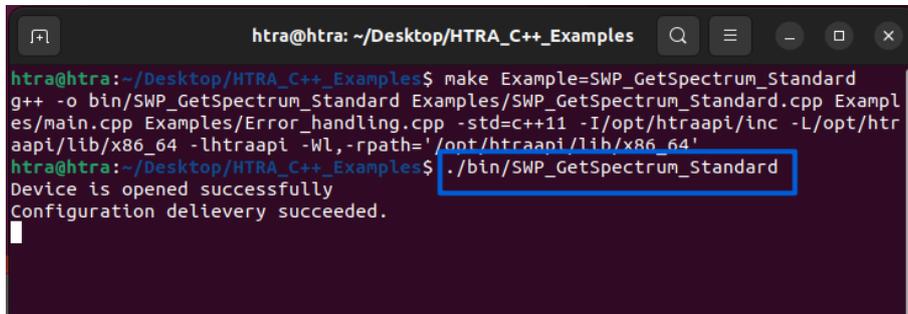


Figure 44 Verify the calibration files

4. Run the program: After successfully compiling the program and verifying the calibration files, open a terminal and enter:

`./bin/SWP_GetSpectrum_Standard` to run the selected example.



```
htra@htra: ~/Desktop/HTRA_C++_Examples
htra@htra:~/Desktop/HTRA_C++_Examples$ make Example=SWP_GetSpectrum_Standard
g++ -o bin/SWP_GetSpectrum_Standard Examples/SWP_GetSpectrum_Standard.cpp Exampl
es/main.cpp Examples/Error_handling.cpp -std=c++11 -I/opt/htraapi/inc -L/opt/htr
aapi/lib/x86_64 -lhtraapi -Wl,-rpath='/opt/htraapi/lib/x86_64'
htra@htra:~/Desktop/HTRA_C++_Examples$ ./bin/SWP_GetSpectrum_Standard
Device is opened successfully
Configuration delivery succeeded.
```

Figure 45 Run the Compiled SWP\_GetSpectrum\_Standard Example

### 7.4.2 C++ Project Creation and Compilation

Prerequisite: Correctly configure the driver files as described in the [Driver File Configuration](#) section.

1. Write the code:

The Linux dynamic libraries provided on the USB drive are identical to those on Windows. The code you write only needs to comply with the HAROGIC HTRA API Programming Guide.

2. Compile and run:

- 1). Create a new folder to store the entire project (e.g., C++\_Test). Inside this folder, create a CalFile folder to store calibration files and an htraapi folder to store header files and dynamic link libraries;

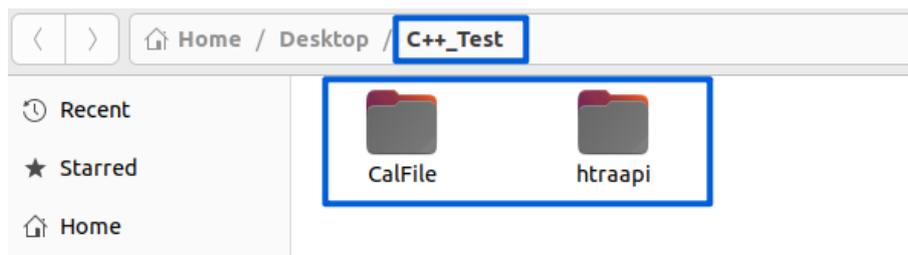


Figure 46 Create Project Folder

- 2). Inside the htraapi folder, create an inc folder to store header files and a lib folder to store dynamic link libraries;

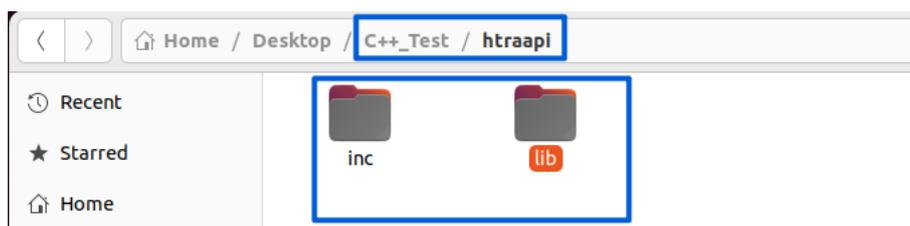


Figure 47 Create inc and lib Folders under htraapi

- 3). Copy the files from the CalFile folder on the USB drive into the newly created "C++\_Test\CalFile" folder;
- 4). Copy the header files from "Linux\Install\_HTRA\_SDK\htraapi\inc" on the USB drive into the newly created "C++\_Test\htraapi\inc" folder;
- 5). Check the system architecture according to the [Environment Version Compatibility Self-Check](#) section. Then, following the [description of the lib folder](#), copy the files from the folder corresponding to your architecture into the "C++\_Test\htraapi\lib" folder. (The illustration shows an x86\_64 architecture host.);

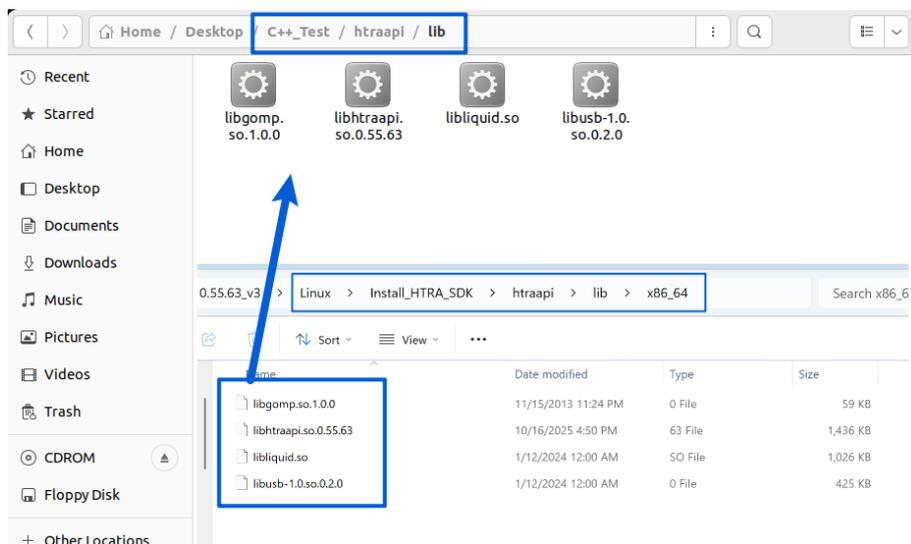


Figure 48 Copy the Dynamic Link Libraries for the Corresponding Architecture into the lib Folder

- 6). Open a terminal in the lib folder and enter the following command to create symbolic links for the copied dynamic link libraries (the commands are the same for all three architectures): In the following, the libhtraapi.so library uses version 0.55.63 as an example; for other versions, simply adjust the version number accordingly:

- `ln -sf libhtraapi.so.0.55.63 libhtraapi.so.0`
- `ln -sf libhtraapi.so.0 libhtraapi.so`
- `ln -sf libusb-1.0.so.0.2.0 libusb-1.0.so.0`
- `ln -sf libusb-1.0.so.0 libusb-1.0.so`
- `ln -sf libgomp.so.1.0.0 libgomp.so.1`
- `ln -sf libgomp.so.1 libgomp.so`

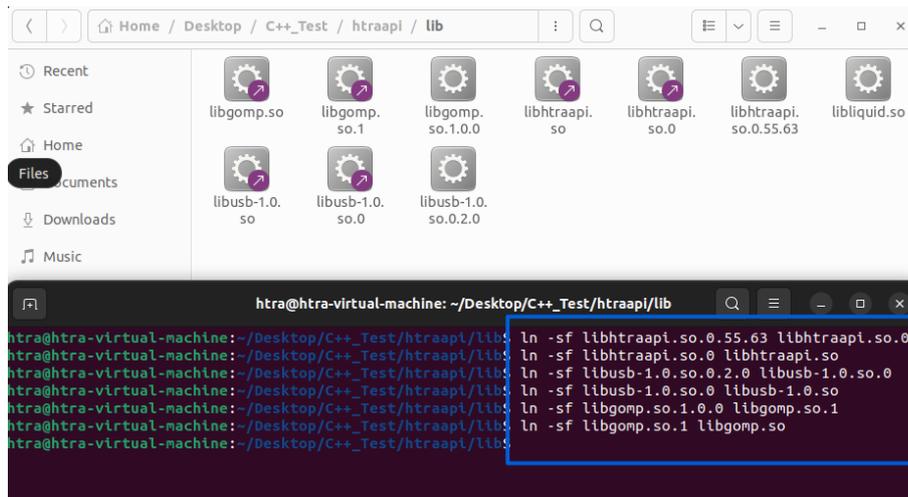


Figure 49 Create Symbolic Links for Dynamic Link Libraries

- 7). Place the written code files in the top-level folder of C++\_Test;

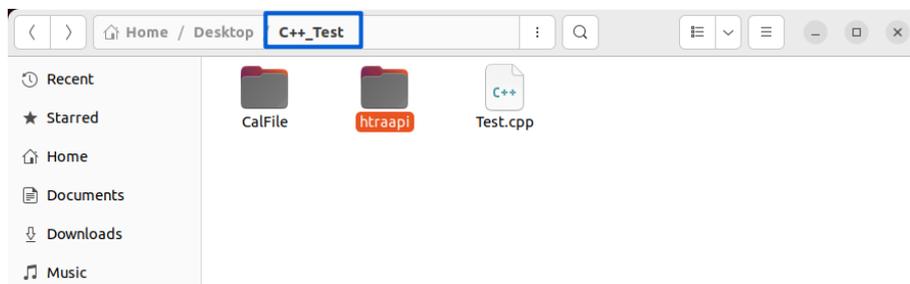


Figure 50 Place the Code Files

- 8). Compile to generate the executable: Based on the system architecture confirmed in the [Environment Version Compatibility Self-Check](#) section, open a terminal in the C++\_Test folder and enter the command corresponding to your architecture;

The following example uses Test.cpp. Compile it on different operating systems to generate an executable named Test:

- For x86\_64 system:

```
g++ -o Test Test.cpp -std=c++11 -I ./htraapi/inc -L ./htraapi/lib -lhtraapi -Wl,-rpath='./htraapi/lib'
```

- For arch64 system:

```
aarch64-linux-gnu-g++ -o Test Test.cpp -std=c++11 -I ./htraapi/inc -L ./htraapi/lib -lhtraapi -Wl,-rpath='./htraapi/lib'
```

- For armv7 system:

```
arm-linux-gnueabi-g++ -o Test Test.cpp -std=c++11 -I ./htraapi/inc -L ./htraapi/lib -lhtraapi -Wl,-rpath='./htraapi/lib'
```

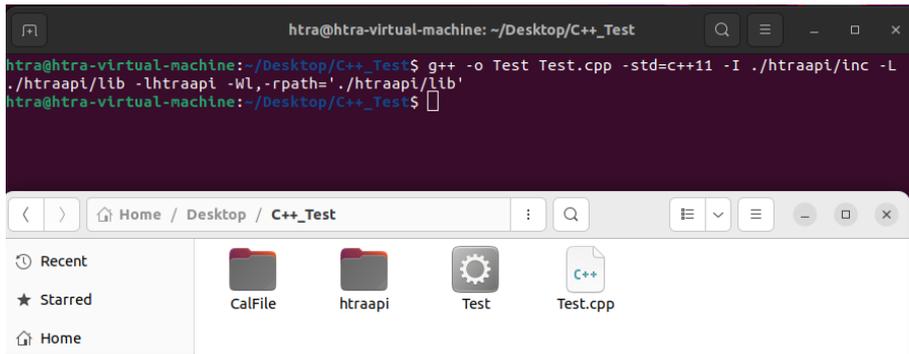


Figure 51 Compile to Generate Executable

9). Run the program: Enter `./Test` to start the executable file.

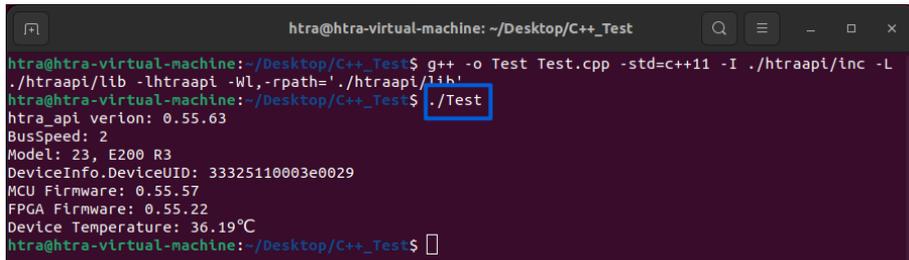


Figure 52 Run the Test Executable

### 7.4.3 C++ Project Cross Compilation

If the host computer has a cross-compilation toolchain and you want to cross-compile for the device, follow the process below.

The following example shows how to cross-compile an aarch64 executable on an x86\_64 host:

1. Generate the executable for the target architecture:
- 1). Follow steps 1 to 8 in the "[C++ Project Creation and Compilation](#)" section to create the project, place the calibration files, and add the aarch64 architecture header and library files. Then, create symbolic links, place the program code, and compile the executable using the target architecture compilation command. As shown below, when compiling an aarch64 executable, use the compilation command for an aarch64 system.

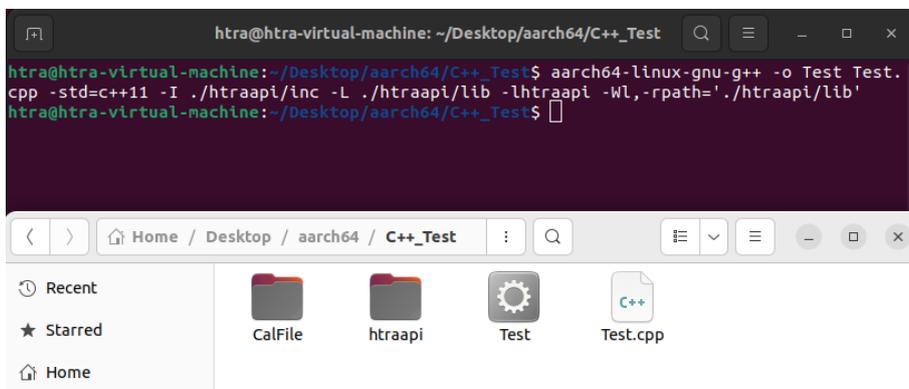
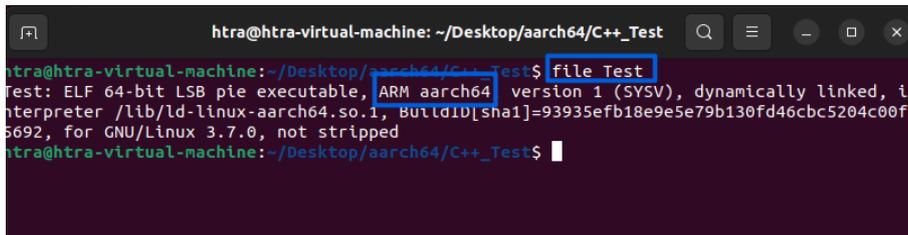


Figure 53 Cross-Compile an aarch64 Executable

- 2). After generating the executable, enter `file Test` to check the architecture of the executable. You should see that the current executable is for the aarch64 architecture.



```
htra@htra-virtual-machine: ~/Desktop/aarch64/C++_Test
htra@htra-virtual-machine:~/Desktop/aarch64/C++_Test$ file Test
Test: ELF 64-bit LSB pie executable, ARM aarch64 version 1 (SYSV), dynamically linked, interpreter /lib/ld-linux-aarch64.so.1, BuildID[sha1]=93935efb18e9e5e79b130fd46cbc5204c00f5692, for GNU/Linux 3.7.0, not stripped
htra@htra-virtual-machine:~/Desktop/aarch64/C++_Test$
```

Figure 54 Check Executable Architecture

2. Run the executable on an aarch64 host:
  - 1). Navigate to the project directory and execute `zip -r C++_Test.zip C++_Test` to compress the entire C++\_Test folder into a ZIP archive. Then, copy the generated ZIP file to the aarch64 host;

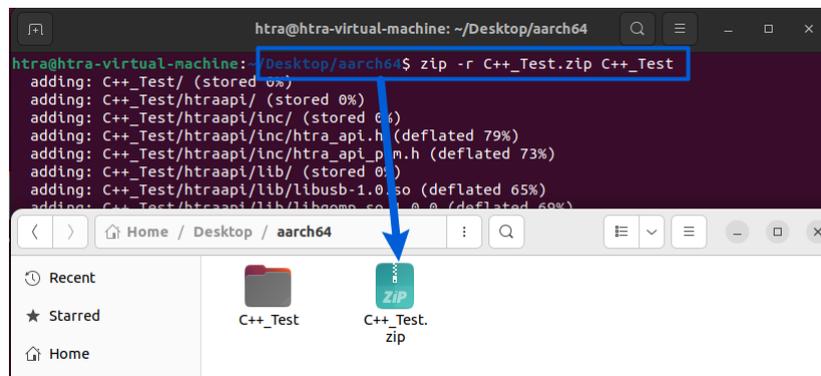


Figure 55 Compress the Created Project

- 2). On the aarch64 host, enter `unzip C++_Test.zip` to extract the project;
- 3). Following the [Driver File Configuration](#) section, configure the driver files on the aarch64 host;
- 4). After configuring the driver files, go to the C++\_Test folder and run the program by entering `./Test` in the terminal.

## 7.5 Using QT Examples and Project Creation

### 7.5.1 Qt Example Usage Process

Usage prerequisite: Ensure the device is properly connected and the driver files have been correctly configured according to the [Driver File Configuration](#) chapter.

The following example demonstrates how to run the Qt sample on Ubuntu 22.04, using an x86\_64 architecture.

1. Copy the "Linux\HTRA\_Qt\_Examples" folder from the included USB drive to the host PC;
2. Refer to the [Environment Version Compatibility Self-Check](#) chapter to confirm the system architecture, then copy the contents from the corresponding architecture folder under "Linux\Install\_HTRA\_SDK\htraapi\lib" on the USB drive into the host PC's "HTRA\_Qt\_Examples\htraapi" folder;

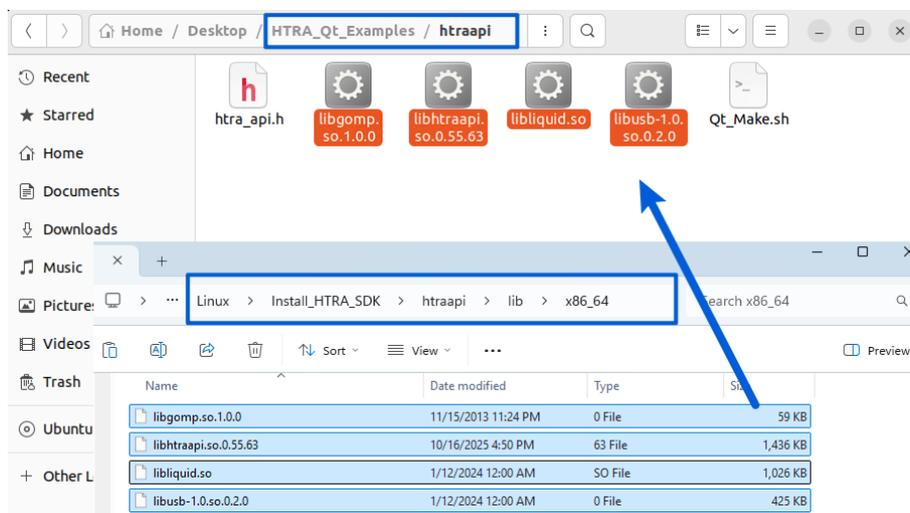


Figure 56 Copy the dynamic libraries for the corresponding architecture

3. Open a terminal in the htraapi folder and enter `sudo sh Qt_Make.sh`. When prompted, enter the password to authorize the creation of symbolic link;

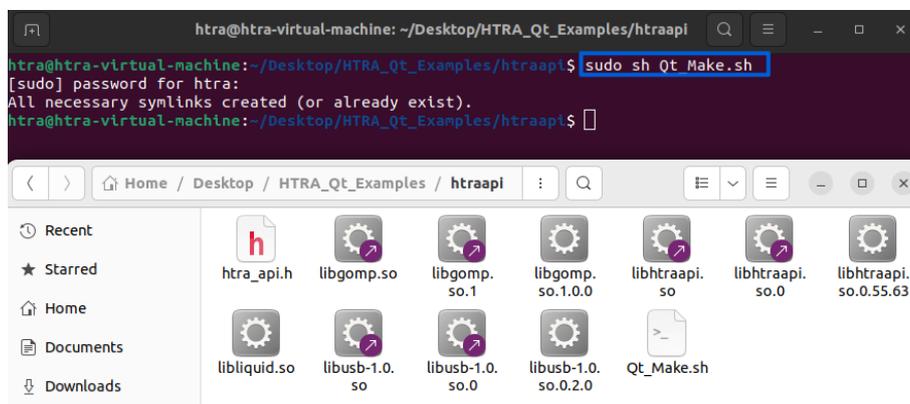


Figure 57 Create symbolic links for the dynamic libraries

4. Enter the "HTRA\_Qt\_Examples\bin\CalFile" folder and ensure that it contains the calibration files for the device in use;
5. Use Qt Creator to open the htrdemo.pro file located in "HTRA\_Qt\_Examples\htrdemo", and configure the project's build environment;

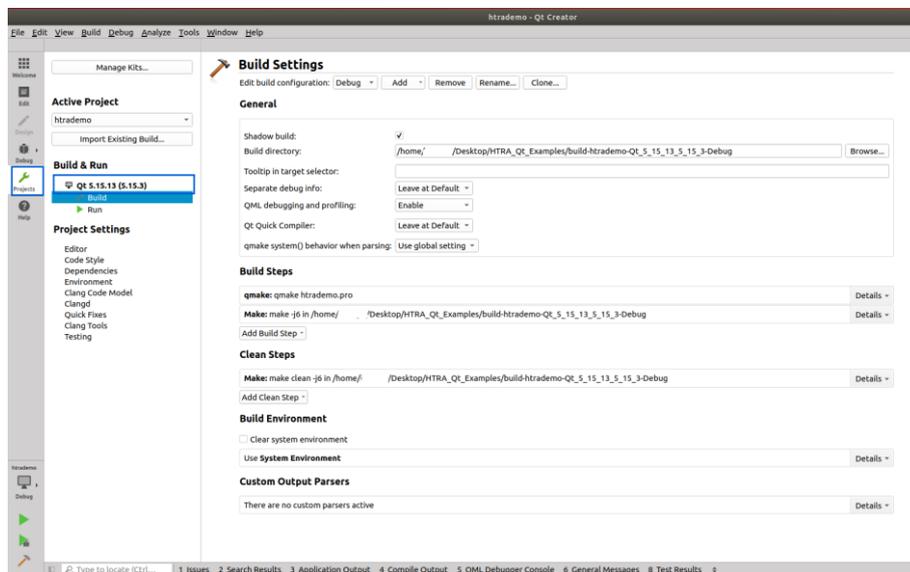


Figure 58 Build environment

6. Click "Edit", open main.cpp under the "Sources" folder of the "htrdemo" project, uncomment the relevant functions, save the file, and click Run to execute different examples;

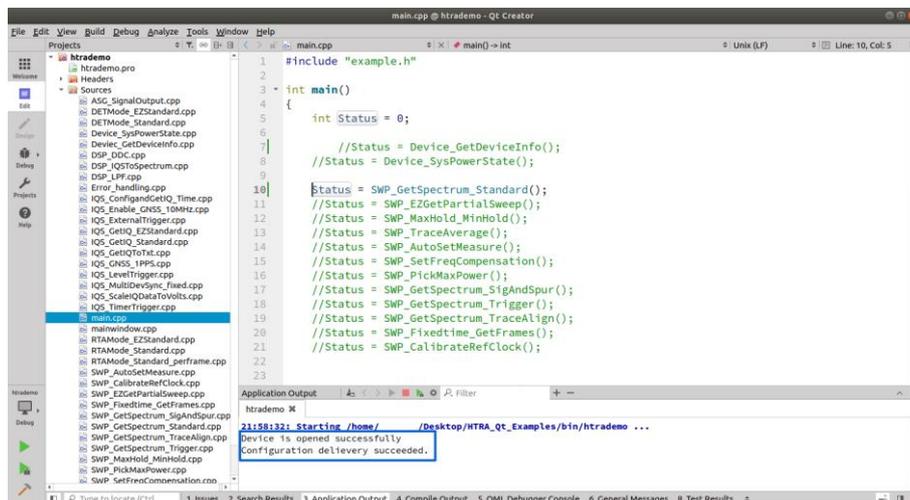


Figure 59 Run the SWP\_GetSpectrum\_Standard example

## 7.5.2 Qt Project Creation and Compilation

Provided that the driver files have been correctly configured as described in the [Driver File Configuration](#) section, if you want to create and compile a Qt project, follow the process below:

The code should follow the API Programming Guide, and the steps for creating a GUI application are as follows:

1. Create a new folder to store the entire project (e.g., QtTest), including bin (for calibration files and generated executables) and htraapi (for header files and dynamic link libraries) subfolders;
2. Copy the instrument-specific CalFile folder from the USB drive into the QtTest\bin folder;
3. Copy the header files from Linux\Install\_HTRA\_SDK\htraapi\inc on the USB drive into the QtTest\htraapi folder;
4. Copy the dynamic link libraries from the folder corresponding to your system architecture under Linux\Install\_HTRA\_SDK\htraapi\lib on the USB drive into the QtTest\htraapi folder (here, an x86\_64 host is used as an example);

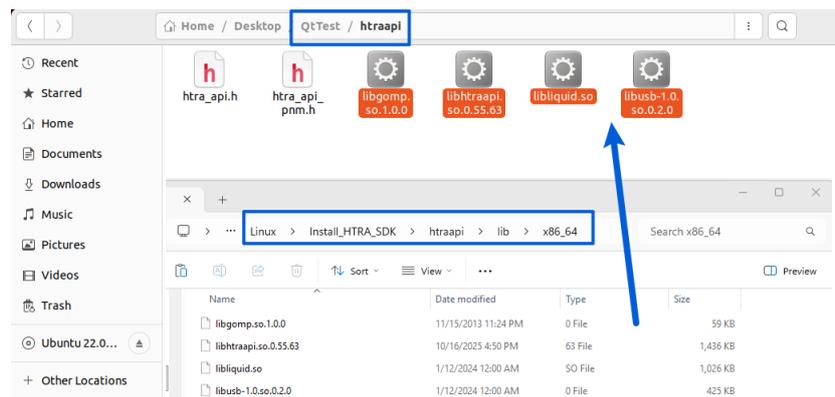


Figure 60 Copy the dynamic link libraries for the corresponding architecture

5. Open a terminal in the htraapi folder and enter the following commands in sequence to create symbolic links for the copied dynamic link libraries (the commands are the same for all architectures):

In the following, the libhtraapi.so library uses version 0.55.63 as an example; for other versions, simply adjust the version number accordingly:

- `ln -sf libhtraapi.so.0.55.63 libhtraapi.so.0`
- `ln -sf libhtraapi.so.0 libhtraapi.so`
- `ln -sf libusb-1.0.so.0.2.0 libusb-1.0.so.0`
- `ln -sf libusb-1.0.so.0 libusb-1.0.so`
- `ln -sf libgomp.so.1.0.0 libgomp.so.1`
- `ln -sf libgomp.so.1 libgomp.so`

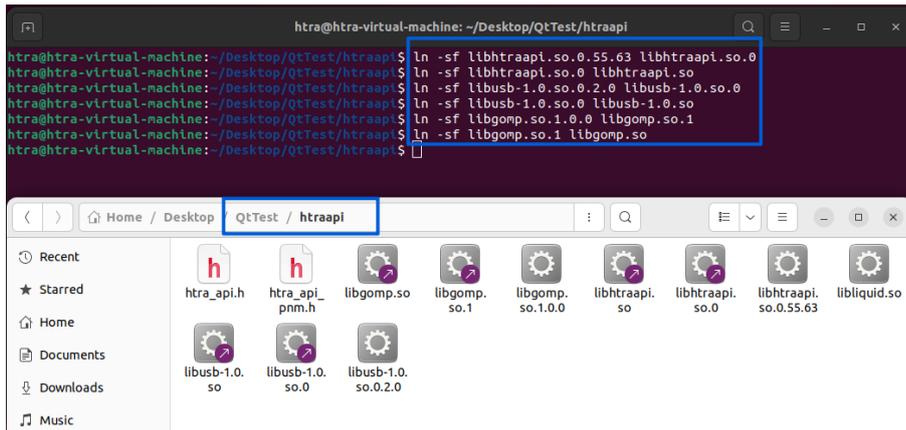


Figure 61 Create symbolic links for the dynamic libraries in htraapi

6. Open Qt Creator and click "File" -> "New File or Project";
7. In the project options, click "Application", select "Qt Widgets Application", and click "Choose...";
8. Enter the project name (e.g., "test"), click "Browse", select the previously created "QtTest" folder, and then click "Next";
9. Select "qmake", click "Next" until the "Kit Selection" screen appears. On this screen, choose a build environment and click "Next";
10. Click "Finish" to create the project;
11. In the Qt Creator main interface, right-click the "Test" project, select "Add Library..." -> "External Library" -> "Next";
12. Click "Browse" for the library file, select libhtraapi.so in "QtTest\htraapi", click "Open", choose the "Linux" platform, and click "Next".

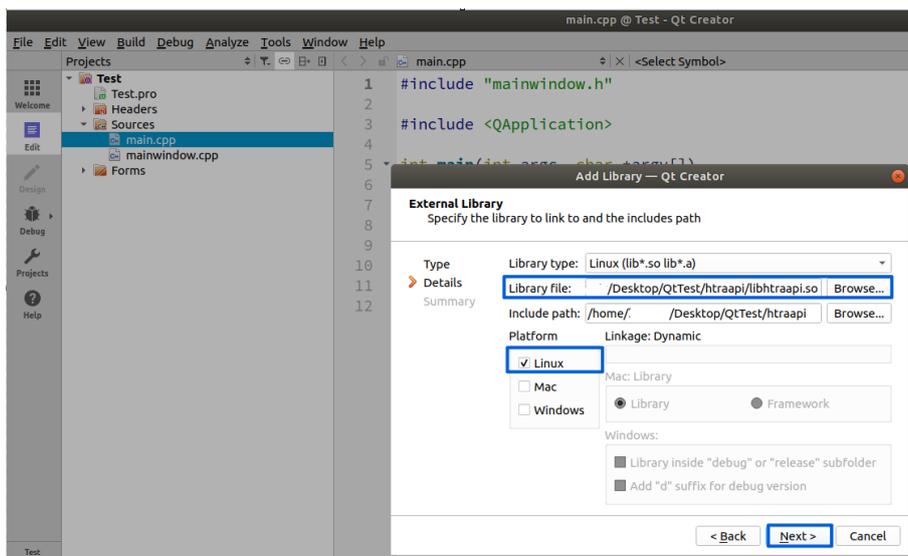


Figure 62 Select the Linux Platform

13. Click "Finish" to add the external library;

- In Test.pro, after `CONFIG += c++11`, add `DESTDIR = $$clean_path($$PWD/../bin)` to specify the location for the generated executable;

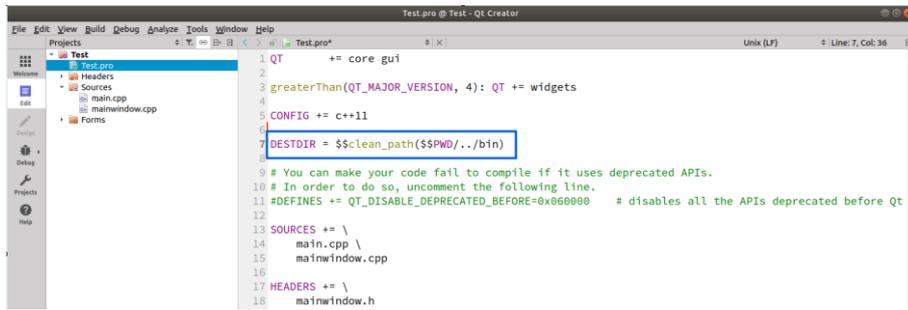


Figure 63 Specify the Executable Output Location

- After the library file, add `-Wl,-rpath,$$PWD/../htraapi` to specify the runtime library path for the executable;

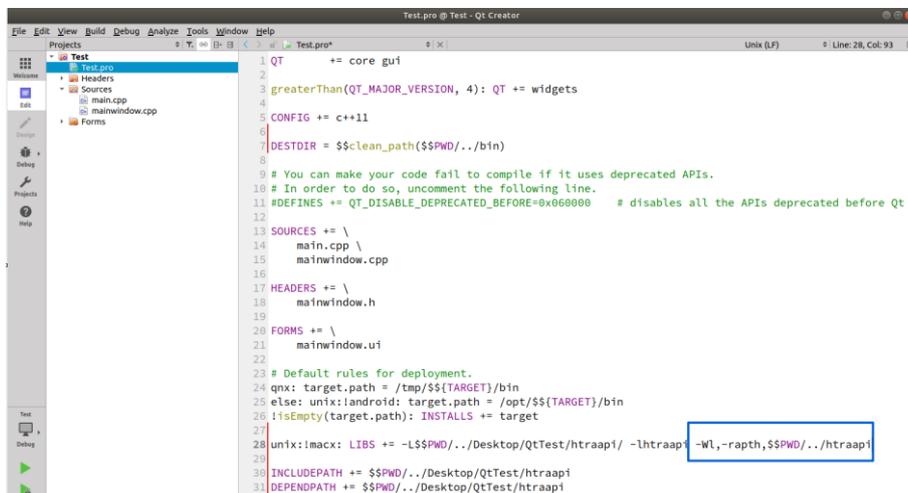


Figure 64 Specify the Runtime Library Path for the Executable

- Save the Test.pro file, then write the code in mainwindow.cpp and click Run. The normal operating interface is shown below;

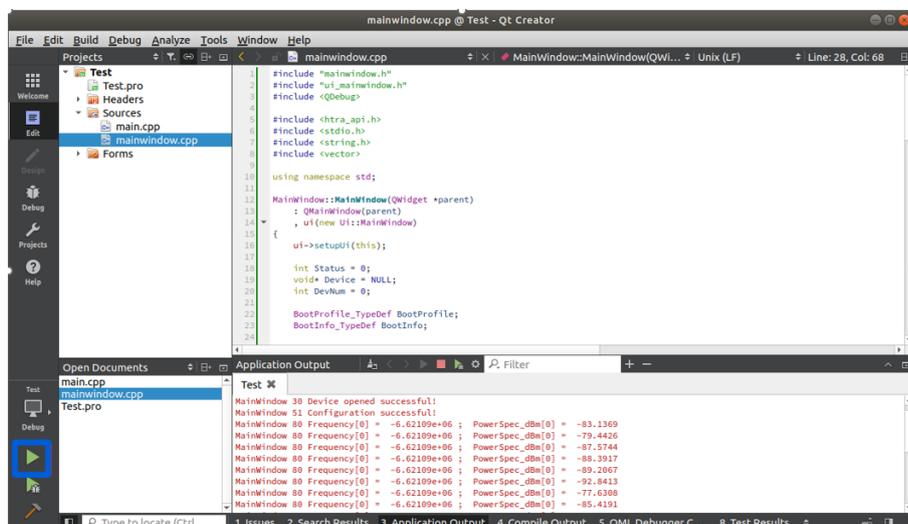


Figure 65 Run the Code

17. Close Qt Creator, navigate to the QtTest\bin folder, open a terminal, and enter `./Test` to run the executable;

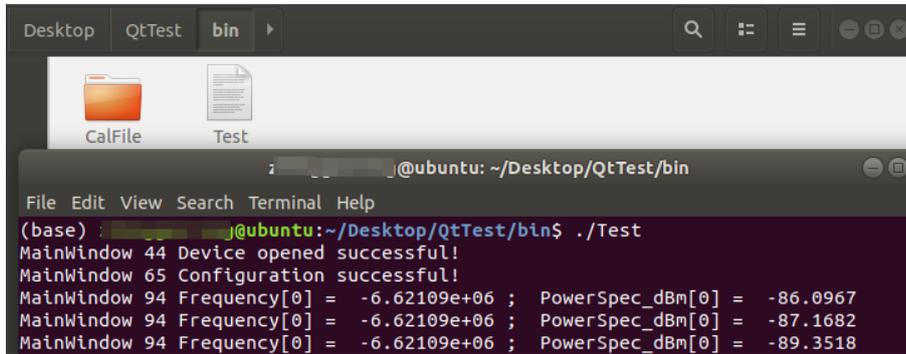


Figure 66 Run the Executable

### 7.5.3 Qt Project Cross-Compilation

If the host computer has a cross-compilation toolchain and you want to cross-compile for the device, follow the procedure below (here, an example of cross-compiling an aarch64 executable on an x86\_64 host is given):

1. First, generate the executable for the target architecture:
  - 1). Following steps 1 to 9 of the [Qt Project Creation and Compilation](#) process for a windowed application, create the project, place the calibration and header files, place the library files for the cross-compilation target architecture (`$\text{aarch64}$`), create a soft link (symlink) for the dynamic link libraries, create the program in Qt Creator, and select the `$\text{aarch64}$` Build Kit

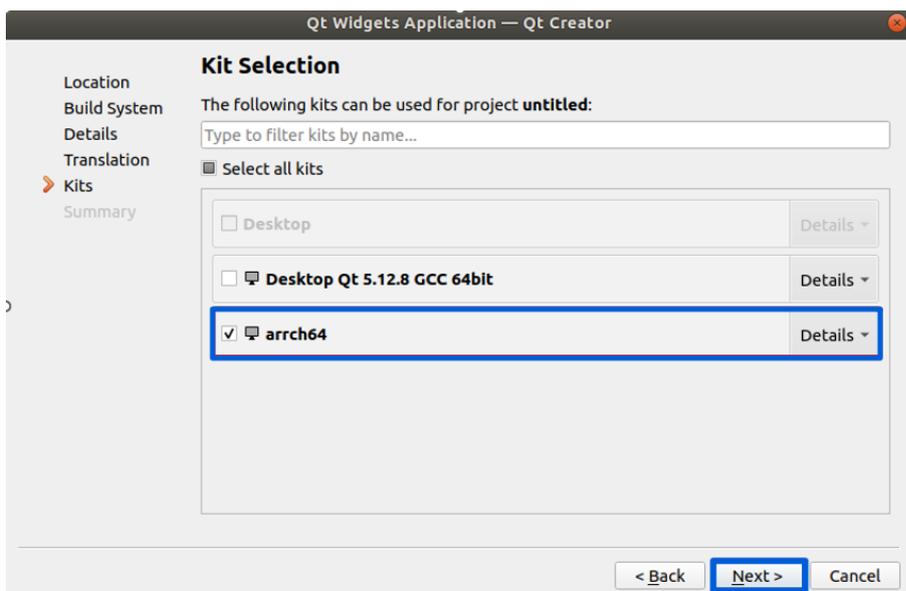


Figure 67 Select the target kit for the cross-compilation target architecture

- 2). Follow steps 10 to 16 of the windowed application creation process to perform project creation, library referencing, modification of the executable program generation location, project coding, and running;

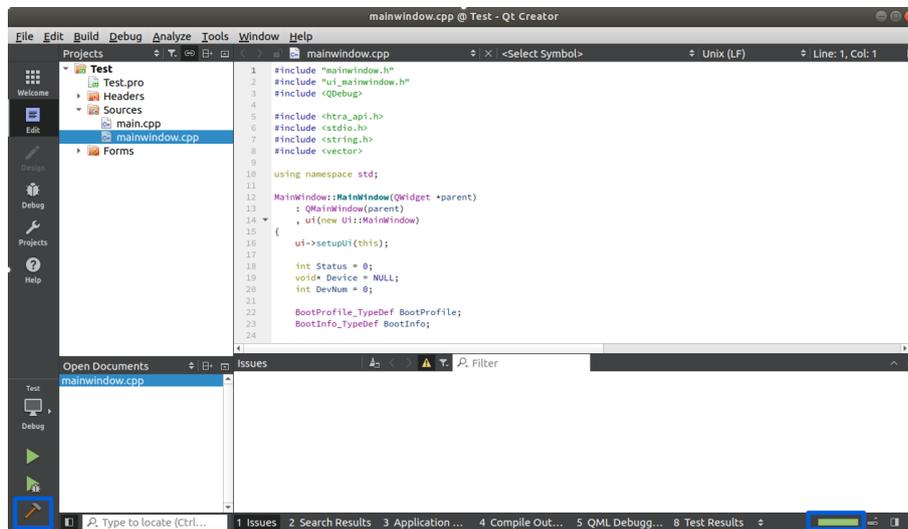


Figure 68 Build the executable program for the aarch64 architecture

- 3). After building the executable program, open the terminal in the QtTest\bin folder and enter file Test to view the executable program's architecture (the executable program name is Test, so the input command is file Test);

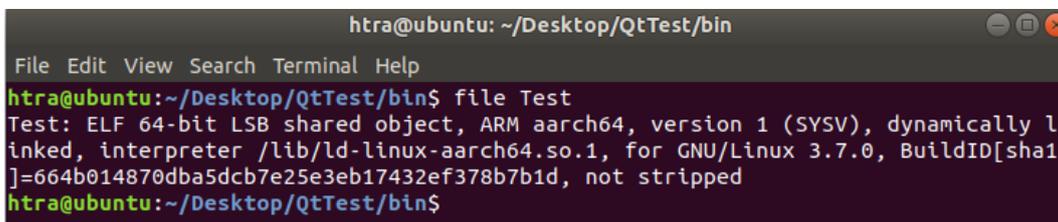


Figure 69 View the executable program's architecture

2. Run the executable program on the aarch64 architecture host machine:
  - 1). Enter the project directory (The example project is located on the Desktop, so enter cd Desktop/). Execute `zip -r QtTest.zip QtTest` to package the entire QtTest folder into a ZIP file. Then, copy the generated compressed package to the aarch64 host machine;

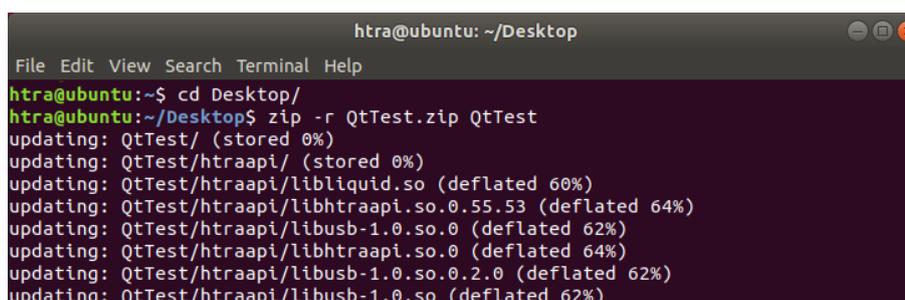
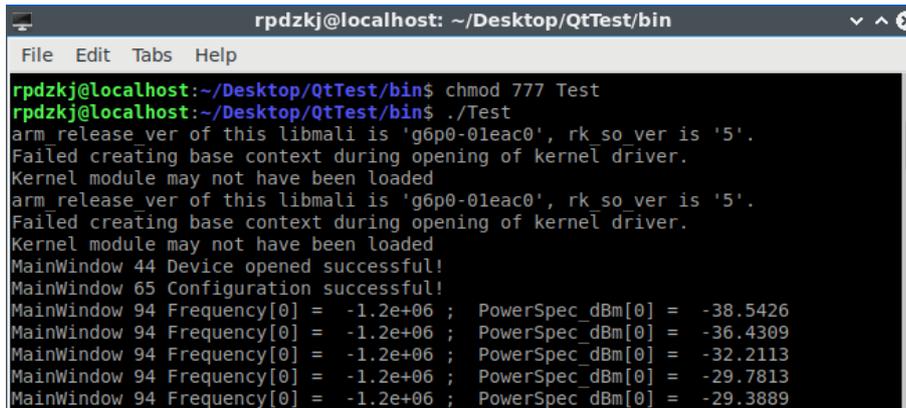


Figure 70 Compress the created project

- 2). On the aarch64 host machine, enter `unzip QtTest.zip` to unzip (or extract) the project;
- 3). Refer to the section on [Driver File Configuration](#) to configure the driver files on the aarch64 host machine;
- 4). After configuring the driver files, enter the QtTest folder. In the terminal, enter `chmod 777 Test` to grant permissions to the executable program. Subsequently, you can run the program by entering `./Test`.



```
rpdzkj@localhost: ~/Desktop/QtTest/bin
File Edit Tabs Help
rpdzkj@localhost:~/Desktop/QtTest/bin$ chmod 777 Test
rpdzkj@localhost:~/Desktop/QtTest/bin$ ./Test
arm release ver of this libmali is 'g6p0-01eac0', rk so ver is '5'.
Failed creating base context during opening of kernel driver.
Kernel module may not have been loaded
arm release ver of this libmali is 'g6p0-01eac0', rk so ver is '5'.
Failed creating base context during opening of kernel driver.
Kernel module may not have been loaded
MainWindow 44 Device opened successful!
MainWindow 65 Configuration successful!
MainWindow 94 Frequency[0] = -1.2e+06 ; PowerSpec_dBm[0] = -38.5426
MainWindow 94 Frequency[0] = -1.2e+06 ; PowerSpec_dBm[0] = -36.4309
MainWindow 94 Frequency[0] = -1.2e+06 ; PowerSpec_dBm[0] = -32.2113
MainWindow 94 Frequency[0] = -1.2e+06 ; PowerSpec_dBm[0] = -29.7813
MainWindow 94 Frequency[0] = -1.2e+06 ; PowerSpec_dBm[0] = -29.3889
```

Figure 71 Grant permissions and run the executable program

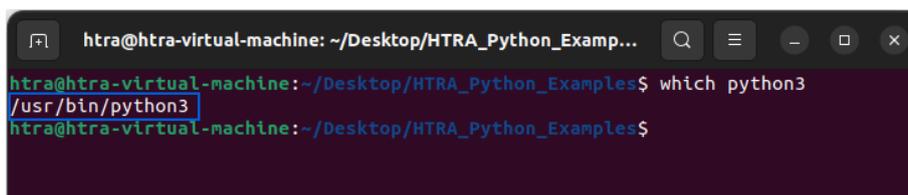
## 7.6 Usage of Python Examples and Project Creation

### 7.6.1 Usage of Python Examples

Prerequisite: Ensure the device is properly connected and the driver files have been correctly configured according to the [Diver File Configuration](#) section.

The functionality of the Python examples can be found in the [Python Example Description](#) chapter.

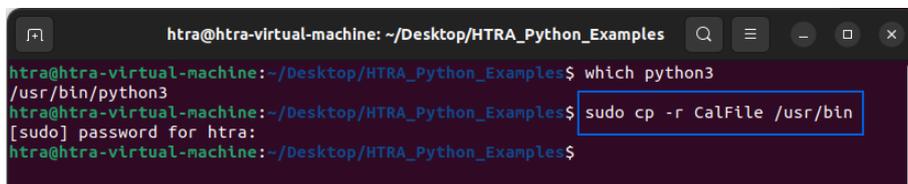
1. Copy the "Linux\HTRA\_Python\_Examples" folder from the included USB drive to the host PC. In this folder, open a terminal and enter `which python3` to check the location of the Python interpreter (for example, here it is `/usr/bin`);



```
htra@htra-virtual-machine: ~/Desktop/HTRA_Python_Expamp...
htra@htra-virtual-machine:~/Desktop/HTRA_Python_Examples$ which python3
/usr/bin/python3
htra@htra-virtual-machine:~/Desktop/HTRA_Python_Examples$
```

Figure 72 Check the Python3 Interpreter Location

2. Based on the obtained interpreter path, enter `sudo cp -r CalFile /usr/bin` to copy the device calibration files to the same directory as the Python interpreter. (If the interpreter is not located in `/usr/bin`, replace the path with the actual location.)



```
htra@htra-virtual-machine: ~/Desktop/HTRA_Python_Examples
htra@htra-virtual-machine:~/Desktop/HTRA_Python_Examples$ which python3
/usr/bin/python3
htra@htra-virtual-machine:~/Desktop/HTRA_Python_Examples$ sudo cp -r CalFile /usr/bin
[sudo] password for htra:
htra@htra-virtual-machine:~/Desktop/HTRA_Python_Examples$
```

Figure 73 Copy the Calibration Files to the Same Directory as the Interpreter

3. Refer to the [Environment Version Compatibility Self-Check](#) chapter to confirm the system architecture, then copy the contents from the corresponding architecture folder under "Linux\Install\_HTRA\_SDK\htraapi\lib" on the USB drive into the host PC's "HTRA\_Python\_Examples\htraapi" folder;

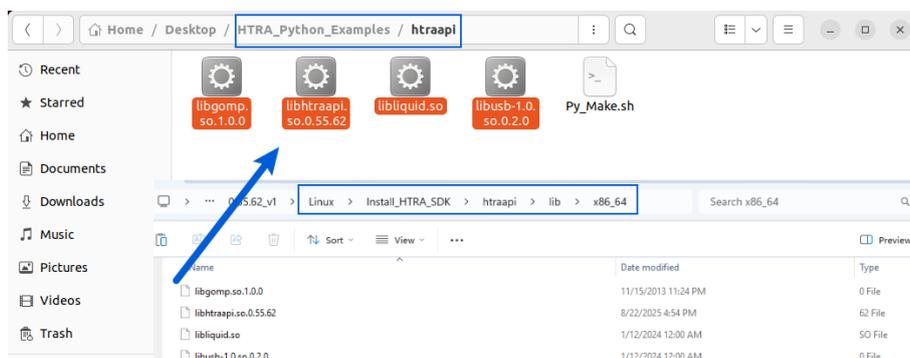
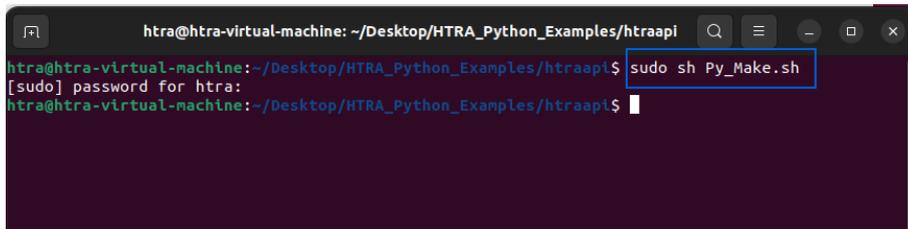


Figure 74 Copy the Dynamic Link Libraries

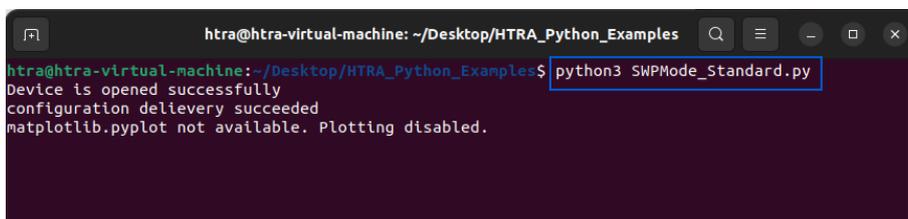
4. Open a terminal in the htraapi folder, enter `sudo sh Py_Make.sh`, and provide the password when prompted to grant permission for creating symbolic links for the libraries;



```
htra@htra-virtual-machine: ~/Desktop/HTRA_Python_Examples/htraapi
htra@htra-virtual-machine:~/Desktop/HTRA_Python_Examples/htraapi$ sudo sh Py_Make.sh
[sudo] password for htra:
htra@htra-virtual-machine:~/Desktop/HTRA_Python_Examples/htraapi$
```

Figure 75 Create symbolic links for the libraries in htraapi

5. In the HTRA\_Python\_Examples folder, open a terminal and enter `python3 SWPMode_Standard.py` to run the provided SWPMode\_Standard.py example.



```
htra@htra-virtual-machine: ~/Desktop/HTRA_Python_Examples
htra@htra-virtual-machine:~/Desktop/HTRA_Python_Example:$ python3 SWPMode_Standard.py
Device is opened successfully
configuration delivery succeeded
matplotlib.pyplot not available. Plotting disabled.
```

Figure 76 Run the Python Example

Note: If running the Python example on a different device, first copy the calibration files to the "HTRA\_Python\_Examples\CalFile" folder. Then, in a terminal within the HTRA\_Python\_Examples folder, enter `sudo cp -r CalFile /usr/bin` to update the calibration files to the same directory as the Python interpreter.

### 7.6.2 Python Project Creation

Provided that the driver files have been correctly configured as described in the [Diver File Configuration](#) section, if you want to create a Python project, follow the procedure below:

1. The code should follow the HAROGIC HTRA API Programming Guide;
2. When running the program, place it in the example folder (HTRA\_Python\_Examples) and follow the procedure in the [Usage of Python Examples](#) chapter.

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